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Backwards-compatible object audio carriage using Enhanced AC-3

EBU
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Introduction

Motivation

In traditional channel-based audio mixing, sound elements are mixed to the fixed speaker channels, i.e. left, right, centre, left surround and right surround. This paradigm is well known and works when the channel configuration at the decoding end can be predetermined, or assumed with reasonable certainty to be 2.0, 5.X or 7.X.

However, with the popularity of new speaker setups, no assumption can be made about the speaker setup used for playback. Therefore, channel-based audio does not offer a sufficient method for adapting a representation where the source speaker layout does not match the speaker layout at the decoding end. This presents a challenge when trying to author content that plays back well independently to the speaker configuration.

In object-based audio, individual sound elements are delivered to the playback device, where they are rendered based on the used speaker layout. Because individual sound elements can be associated with a much richer set of metadata, giving meaning to the elements, the method of adaptation to the speaker configuration reproducing the audio can provide better information regarding how to render to fewer speakers.

Enhanced AC-3 (E-AC-3), defined in ETSI TS 102 366 [1], is a widely used format for transmission of channel-based audio content. When the goal is to transport object-based audio in an environment where compatibility with pre-existing devices is paramount, joint object coding (JOC), as specified in the present document, can be used in conjunction with E-AC-3.

Document structure

The present document is structured as follows:

- Clause 4 explains the concept of object-based audio (OBA) and specifies the decoder interface.
- Clause 5 specifies object audio metadata (OAMD), the OBA metadata format.
- Annex B specifies how OAMD can be converted to an audio definition model (ADM), providing an interconnection to the professional metadata generation and monitoring.
- Clause 6 specifies the JOC tool that converts the output of an E-AC-3 decoder to objects, as specified in ETSI TS 102 366 [1].
- Clause 7 specifies the quadrature mirror filter bank tool that is used by the JOC tool.
- Annex C lists requirements on packaging a bitstream as defined in the present document into an ISO based media file format.
- Annex D lists requirements on an MPEG DASH media presentation description signaling a bitstream as defined in the present document.
- Annex E provides requirements on a MPEG CMAF compliant media format containing a bitstream as defined in the present document.

1 Scope

The present document specifies an extension to the E-AC-3 codec.

The extension adds an object-based three-dimensional spatial representation of coded audio information and metadata. It is backward compatible with the one- and two-dimensional channel-based spatial representation of coded audio information as defined in ETSI TS 102 366 [1].

NOTE: In this context, backward compatibility is defined as follows: The three-dimensional spatial representation specified in the present document can be decoded on a device compliant with the syntax and semantics specified in ETSI TS 102 366 [1]. In this case, such a device will output one- or two-dimensional channel-based audio as per the coding algorithm defined in ETSI TS 102 366 [1] alone. Thus, support for decoders specified in ETSI TS 102 366 [1] and associated user experiences are fully maintained with the extension defined herein.

The present document specifies the following:

- 1) Syntax and semantics of the OBA metadata, carried via the extensible metadata delivery format (EMDF), specified in ETSI TS 102 366 [1]
- 2) Syntax and semantics of metadata to control a tool for conversion of one- or two-dimensional channel-based audio to a higher number of audio signals, part of the three-dimensional spatial representation (JOC)
- 3) Additional requirements on the E-AC-3 decoder as specified in ETSI TS 102 366 [1]
- 4) Requirements on the OBA, the JOC tool, the quadrature mirror filter bank tool, packaging the bitstream into ISO based media file format, the signalling in an MPEG DASH media presentation description, and requirements on a MPEG CMAF compliant media file, containing a bitstream as defined in the present document.
- 5) Informative guidance for conversion from 1) to the ADM as defined in Recommendation ITU-R BS.2076 [i.1]

2 References

2.1 Normative References

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The following referenced documents are necessary for the application of the present document.

- [1] ETSI TS 102 366: "Digital Audio Compression (AC-3, Enhanced AC-3) Standard".
- [2] ISO/IEC 23000-19: "Common Media Application Format for Segmented Media".
- [3] ISO/IEC 23009-1: 'Dynamic adaptive streaming over HTTP (DASH) -- Part 1: Media presentation description and segment formats'.
- [4] ISO/IEC 14496-12: "Information technology -- Coding of audio-visual objects -- Part 12: ISO base media file format".

2.2 Informative References

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The following referenced documents are not necessary for the application of the present document, but they assist the user with regard to a particular subject area.

[i.1] Recommendation ITU-R BS.2076: "Audio Definition Model".

3 Definitions of terms, symbols, abbreviations and conventions

3.1 Terms

For the purposes of the present document, the following terms apply:

audio channel: data representing an audio signal designated to a dedicated speaker position

audio definition model: metadata model describing format and content of audio files, specified in Recommendation ITU-R BS.2076 [i.1]

audio object: data representing an object essence plus corresponding object properties

bed: group of multiple bed objects

bed object: static object whose spatial position is fixed by an assignment to a speaker

block: portion of a frame

channel-based audio: audio content that is presented by one or more audio signals and a corresponding channel configuration

channel configuration: targeted speaker layout

codec frame: series of PCM samples or encoded audio data representing the same time interval for all channels in the configuration

NOTE: Decoders usually operate in a codec-frame-by-codec-frame mode.

common media application format: MPEG media file format optimized for delivery of a single adaptive multimedia presentation to a large number and variety of devices; compatible with a variety of adaptive streaming, broadcast, download, and storage delivery methods

DASH descriptor: DASH element used for property signalling

NOTE: DASH descriptors share a common structure.

DASH supplemental property descriptor: DASH descriptor that specifies supplemental information about the containing DASH element that may be used by the DASH client for optimizing the processing

decoder interface: interoperability point of a decoder, accepting input data, providing output data, or both

elementary stream: bitstream that consists of a single type of encoded data (audio, video, or other data)

Enhanced AC-3: audio coding system developed by Dolby and specified in ETSI TS 102 366 [1]

extensible metadata delivery format: set of rules and data structures that enables robust signaling of metadata in an end-to-end process, involving a container, metadata payloads, and authentication protocols

NOTE: Specified in ETSI TS 102 366 [1].

intermediate spatial format: format that defines spatial position by distributing the signal to speakers located in a stacked-ring configuration

ISO based media file format: media file format as specified in ISO/IEC 14496-12 [4]

joint object coding: algorithms for delivering immersive audio at low bitrates, achieved by conveying a multi-channel downmix of the immersive content using perceptual audio coding algorithms together with parametric side information that enables the reconstruction of the audio objects from the downmix in the decoder

low-frequency effects: optional single channel of limited bandwidth (typically less than 120 Hz)

media presentation description: formalized XML-based description for a DASH media presentation for the purpose of providing a streaming service

object audio essence: part of the object that is PCM coded

object audio metadata: metadata used for rendering an audio object. The rendering information may dynamically change (e.g. gain and position)

object-based audio: audio comprised of one or more audio objects

object property: metadata associated with an object essence, which indicates the author's intention for the rendering process

pulse code modulation: digital representation of an analog signal where the amplitude of the signal is sampled at uniform intervals

QMF subband: frequency range represented by one row in a QMF matrix, carrying a subsampled signal

quadrature mirror filter bank: process in which a time-domain signal is transformed into the frequency domain and split into a filter bank comprising a number of frequency bands

rendering: processing of audio content to adapt it to a specific loudspeaker layout

room-anchored coordinates: coordinates specifying a position relative to a coordinate system which is fixed with respect to a room

screen-anchored coordinates: coordinates specifying a position relative to a coordinate system that is fixed with respect to the display surface in a room

speaker-anchored coordinates: coordinates specifying a position by choosing one speaker in a specific speaker layout

substream: part of an AC-4 bitstream, contains audio data and corresponding metadata

zone: sub-volume of the listening room

3.2 Symbols

For the purposes of the present document, the following symbols apply:

$\lceil x \rceil$	round x towards plus infinity
$\lfloor x \rfloor$	round x towards minus infinity
i	the imaginary unit

3.3 Abbreviations

For the purposes of the present document, the following abbreviations apply:

ADM	Audio Definition Model
CMAF	Common Media Application Format
DASH	Dynamic Adaptive Streaming over HTTP
E-AC-3	Enhanced AC-3
EMDF	Extensible Metadata Delivery Format
HH	Hours
HTTP	HyperText Transfer Protocol
IDX	Index
ISF	Intermediate Spatial Format
JOC	Joint Object Coding
LFE	Low-Frequency Effects
MM	Minutes
MPD	Media Presentation Description
MPEG	Moving Pictures Expert Group
MSB	Most Significant Bit
MTX	Matrix
MULZ	Mid-Upper-Lower-Zenith
OAMD	Object Audio MetaData
OBA	Object-Based Audio
PCM	Pulse Code Modulation
QMF	Quadrature Mirror Filter
SR	Stacked Ring
SS	Seconds
VEC	Vector
ZB	Bottom zone
ZU	Top zone

3.4 Conventions

Unless otherwise stated, the following conventions are used in the present document.

Typographic conventions:

- Italic font denotes variables (*n* is a variable)
- Monospace font denotes bitstream elements (`bits` is a bitstream element)

Function prototypes can take scalars, vectors, or matrices as argument and operate element-wise. The return type is either scalar or of the same form as the argument:

min(x)	The minimum value of the elements of <i>x</i>
max(x)	The maximum value of the elements of <i>x</i>
floor(x)	The largest integer(s) less than or equal to the elements of <i>x</i>
mod(a,b)	denotes the remainder of <i>a</i> after division by <i>b</i>
cos(x)	The cosine of the elements of <i>x</i>
sin(x)	The sine of the elements of <i>x</i>
exp(x)	The exponential value of the elements of <i>x</i>

NOTE 1: The return value of `exp()` can be complex valued.

NOTE 2: The return value of `mod()` can have a fractional part.

4 Object-based audio

4.1 Introduction

OBA gives content creators more control over how content is rendered to loudspeakers in consumer homes.

In channel-based audio coding, a set of tracks is implicitly assigned to specific loudspeakers by associating the set of tracks with a channel configuration. If the playback speaker configuration is different from the coded channel configuration, downmixing or upmixing specifications are required to redistribute audio to the available speakers. In object-based audio coding, rendering is applied to objects that comprise the object audio essence in conjunction with metadata that contains individually assigned object properties. The properties more explicitly specify how the content creator intends the audio content to be rendered (that is, they place constraints on how to render the essence into speakers).

4.2 Coordinate systems

4.2.1 Room-anchored coordinate system

The room-anchored coordinate system is a left-handed Cartesian system normalized to the room cuboid.

Coordinates are specified using three components:

- The x component increases from $x=0$ at the left wall to $x=1$ at the right wall.
- The y component increases from $y=0$ at the front wall to $y=1$ at the back wall.
- The z component increases from $z=-1$ at the floor to $z=1$ at the ceiling.

EXAMPLE: An object at the centre of the front wall has coordinates (0,5; 0; 0).

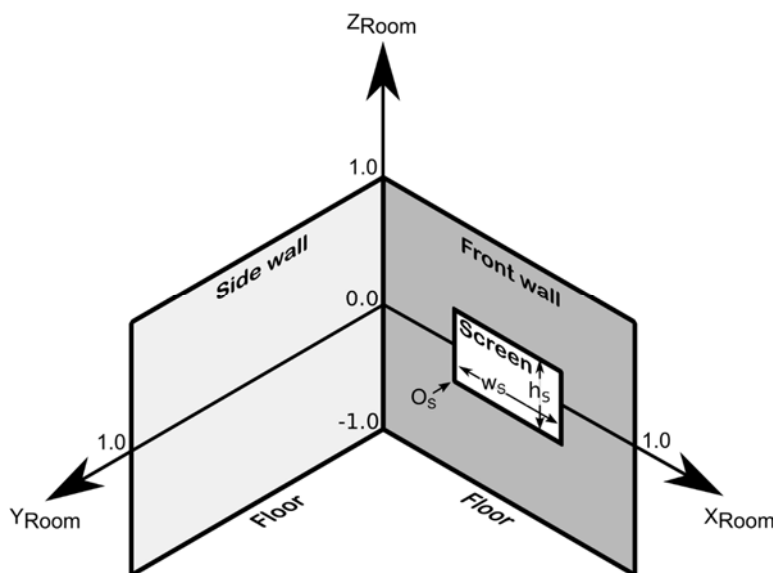


Figure 1: Room-anchored coordinate system

w_s and h_s are the dimensions of the screen, and O_s is the position of the bottom left screen corner.

Objects can also be outside the room.

NOTE: Object position is not bounded, though the coded representation imposes progressively coarser quantization at greater distances.

4.2.2 Screen-anchored coordinate system

In this coordinate system, the physical location of an object at a given coordinate changes with screen size and screen location:

- The x component increases from $x=0$ at the left screen edge to $x=1$ at the right screen edge.
- The y component increases from $y=0$ at the front wall to $y=1$ at the back wall.
- The z component increases from $z=-1$ at the bottom screen edge to $z=1$ at the top screen edge.

The following formula translates screen-anchored coordinates $(X_{\text{screen}}; Y_{\text{screen}}; Z_{\text{screen}})$ to room-anchored coordinates:

$$(X_{\text{room}}; Y_{\text{room}}; Z_{\text{room}}) = O_S + \left(w_S \times X_{\text{screen}}; Y_{\text{screen}}; \frac{h_S}{2} \times (Z_{\text{screen}} + 1) \right)$$

where w_S , h_S and O_S are specified in clause 4.2.1.

EXAMPLE: An object at the centre of the left screen edge has screen-referenced coordinates $(0; 0; 0)_{\text{screen}}$ and room-referenced coordinates $\left(O_{S_x}; O_{S_y}; O_{S_z} + \frac{h_S}{2} \right)_{\text{room}}$.

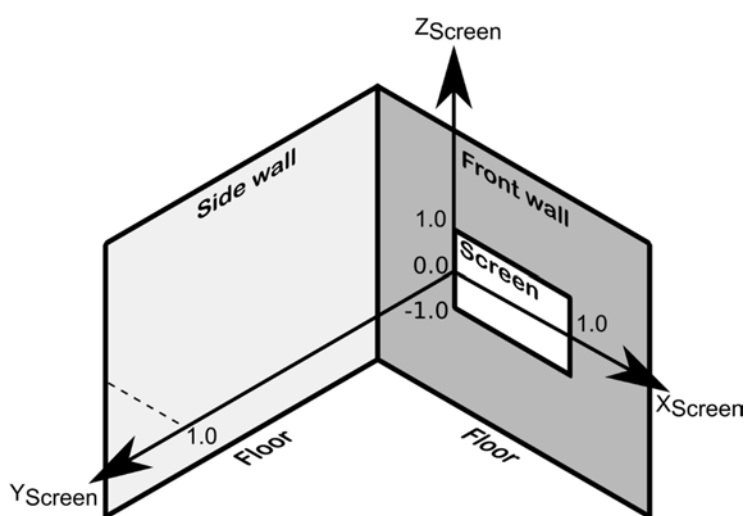


Figure 2: Screen-anchored coordinate system

4.2.3 Speaker-anchored system

In this system, the coordinates of the object are indicated by referring to a specific speaker, meaning the physical location of the object changes with the actual speaker placement.

This system is typically used with objects contained in bed instances.

NOTE: If there is no speaker at the referenced position, the physical object position can be interpolated between nearby speakers in the room.

EXAMPLE: In a 2.0 set-up, an object at "L" is rendered from the left speaker. An object at "C" is located mid-way between the L and R speakers, and may be rendered by panning.

4.3 Decoding of object-based audio content

OBA content is signalled using a specific configuration of the E-AC-3 bitstream.

The decoder shall decode the incoming OBA content as specified in the present document, if the following requirements are met:

- The metadata payloads of JOC and OAMD are present as specified in clause 8.2.
- The incoming channel configuration is supported by the JOC tool, as specified in clause 6.3.2.2.

The decoder shall decode the incoming OBA content by performing the following steps:

- 1) Decode the channel-based audio from the incoming E-AC-3 bitstream, as specified in clause 8.1.
- 2) Transform the time domain signals to the quadrature mirror filter bank domain, as specified in clause 7.2.
- 3) Utilize the JOC decoder tool, as specified in clause 6, to reconstruct the audio object (object) essences from the channel-based downmix.
- 4) Transform the quadrature mirror filter bank samples of the object essences to the time domain, as specified in clause 7.3.
- 5) Decode the object properties as specified in clause 5.2.
- 6) Provide the pulse code modulation (PCM) object essences and the metadata for the object properties at the decoder interface, specified in clause 4.4.

4.4 Decoder interface

The decoder shall provide an interface for the OBA comprising object audio essence audio data and time-stamped metadata updates for the corresponding object properties.

At the interface the decoder shall provide the decoded per-object metadata in time stamped updates. For each update the decoder shall provide the data specified in the *metadata_update* structure in the following pseudo-code.

Pseudocode 1

```

/// metadata_update data structure ///
struct {
    t_timing          timing_data;
    t_position        position_update;
    t_size            size_update;
    t_priority        priority_update;
    t_gain            gain_update;
    t_channel_lock    channel_lock_update;
    t_zone_constraints zone_constraints_update;
    t_divergence      divergence_update;
    t_trim            trim_update;
} metadata_update;

/// declaration ///
enum coordinate_system {
    ROOM,
    SCREEN,
    SPEAKER,
}

enum speaker_labels {
    RC_L, // room-centric left
    RC_R, // room-centric right
    RC_C, // room-centric centre
    RC_LFE, // room-centric low frequency effect
    RC_LS, // room-centric left side/surround
    RC_RS, // room-centric right side/surround
    RC_LB, // room-centric left back
    RC_RB, // room-centric right back
    RC_TFL, // room-centric top front left
    RC_TFR, // room-centric top front right
    RC_TSL, // room-centric top side left
    RC_TSR, // room-centric top side right
    RC_TBL, // room-centric top back left
    RC_TBR, // room-centric top back right
    RC_LW, // room-centric left wide
    RC_RW, // room-centric right wide
    RC_LFE2, // room-centric low frequency effects 2
}

```



```

enum zone {
    SCREEN_ZONE,
    SIDE_ZONE,
    SURROUND_ZONE,
    BACK_ZONE,
    CENTRE_AND_BACK_ZONE,
    TOP_AND_BOTTOM_ZONE,
    ZONE_COUNT = 8
}

enum zone_constraints {
    INCLUDE,
    EXCLUDE,
}

/// type definitions ///
typedef struct {
    unsigned start_sample;
    unsigned frame_offset;
    unsigned ramp_duration;
} t_timing;

typedef union {
    struct {
        float x;
        float y;
        float z;
    } 3D_coordinates;
    unsigned speaker_label; // one of enum speaker_labels
} t_coordinates;

typedef struct {
    unsigned anchor; // one of enum coordinate_system
    t_coordinates coordinates;
    float screen_factor;
    float depth_factor;
} t_position;

typedef struct {
    float width;
    float depth;
    float height;
} t_size;

typedef struct {
    int trim_mode;
    float trim_centre;
    float trim_surround;
    float trim_height;
    float bal3D_Y_tb;
    float bal3D_Y_lis;
} t_trim

typedef float t_priority;
typedef float t_gain;
typedef boolean t_channel_lock;
typedef unsigned[ZONE_COUNT] t_zone_constraints; // each one of enum zone_constraint
typedef float t_divergence;

```

The decoded per-object metadata corresponds to the object properties, as specified in clause 5.2. The timing of the updates correspond to the temporal context of metadata updates, as specified in clause 5.3.

NOTE: Table B.10 lists room-anchored coordinates of speakers for the *speaker_labels*.

5 Object audio metadata

5.1 Introduction

OAMD is the coded bitstream representation of the metadata for OBA processing.

The OAMD bitstream is carried inside an EMDF container, specified in ETSI TS 102 366 [1].

The present document specifies:

- the general OBA content description in clause 5.1a
- the object properties in clause 5.2
- the timing concept within the OAMD bitstream in clause 5.3
- the structure of the OAMD bitstream in clause 5.4
- the OAMD bitstream syntax in clause 5.5
- the bitstream elements contained in the OAMD bitstream in clause 5.6

The OAMD bitstream elements signal:

- OAMD content description metadata, as specified in clause 5.6.0
- object properties metadata, as specified in clause 5.6.1
- timing metadata, as specified in clause 5.6.2
- other metadata, as specified in clause 5.6.4

5.1a OBA content description

The top-level `object_audio_metadata_payload` and the contained `program_assignment` contain several bitstream elements that carry general information about the transmitted OBA content such as:

- version of the OAMD payload syntax
- total number of objects
- type of objects (e.g. dynamic objects or bed instances)
- program composition

For the full list of transmitted information and the detailed semantics see clause 5.6.0.

5.2 Object properties

5.2.1 Position

5.2.1.1 Introduction

The position property is the data that is provided as `position_update` at the decoder interface.

The position property of an object is specified differently for the following cases:

- 1) The object is not contained in a bed and `b_object_use_screen_ref=0`; position property is specified in clause 5.2.1.2.

- 2) The object is not contained in a bed and `b_object_use_screen_ref=1`; position property is specified in clause 5.2.1.3
- 3) The object is contained in a bed; position property is specified in clause 5.2.1.4.

NOTE: Clause 5.6.4.8 specifies how to determine if an object is contained in a bed.

Table 1 lists the related bitstream elements and their reference.

Table 1: Position related bitstream elements

bitstream element	reference
<code>b_use_screen_ref</code>	Clause 5.6.1.1.18
<code>pos3D_X_bits</code>	Clause 5.6.1.1.8
<code>pos3D_Y_bits</code>	Clause 5.6.1.1.9
<code>pos3D_Z_bits</code>	Clause 5.6.1.1.11
<code>pos3D_Z_sign_bits</code>	Clause 5.6.1.1.10
<code>b_differential_position_specified</code>	Clause 5.6.1.1.7
<code>diff_pos3D_X_bits</code>	Clause 5.6.1.1.12
<code>diff_pos3D_Y_bits</code>	Clause 5.6.1.1.13
<code>diff_pos3D_Z_bits</code>	Clause 5.6.1.1.14
<code>b_object_distance_specified</code>	Clause 5.6.1.1.15
<code>b_object_at_infinity</code>	Clause 5.6.1.1.16
<code>distance_factor_idx</code>	Clause 5.6.1.1.17
<code>b_use_screen_ref</code>	Clause 5.6.1.1.18
<code>screen_factor_bits</code>	Clause 5.6.1.1.19
<code>depth_factor_idx</code>	Clause 5.6.1.1.20
<code>b_standard_chan_assign</code>	Clause 5.6.1.1.3
<code>bed_channel_assignment_mask</code>	Clause 5.6.1.1.4
<code>nonstd_bed_channel_assignment_mask</code>	Clause 5.6.1.1.5
<code>b_lfe_only</code>	Clause 5.6.1.1.6
<code>ext_prec_pos3D_X</code>	Clause 5.6.6.4.3
<code>ext_prec_pos3D_Y</code>	Clause 5.6.6.4.4
<code>ext_prec_pos3D_Z</code>	Clause 5.6.6.4.5

5.2.1.2 Position in room-anchored coordinates

The decoder shall set *anchor* = ROOM.

Let $C = (\text{pos3D_X}; \text{pos3D_Y}; \text{pos3D_Z})$.

If `b_object_distance_specified` is false, the position $P(x_{\text{Room}}, y_{\text{Room}}, z_{\text{Room}})$ of the object shall be determined as $P = C$.

NOTE 1: In this case the object is located inside the room.

If `b_object_distance_specified` is true, the position P of the object shall be determined as follows:

- 1) $O = (0, 5; 0, 5; 0)$.
- 2) Let I be the point where ray $O - C$ intersects the room boundaries as shown in figure 3.
- 3) $P = \text{distance_factor} \times I + (1 - \text{distance_factor}) \times O$, where $\text{distance_factor} = \frac{d_s}{d_r}$.

NOTE 2: In this case the object is located outside the room.

The decoder shall set *3D_coordinates* to the three dimensional coordinates $(x_{\text{Room}}, y_{\text{Room}}, z_{\text{Room}})$ of the position P .

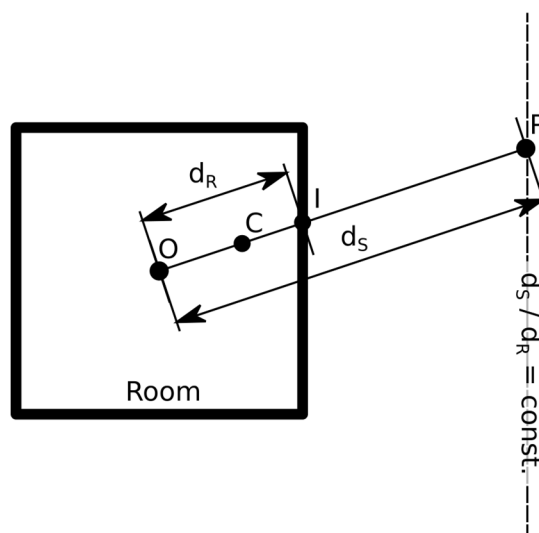


Figure 3: Projection of a room-anchored position to a position outside the room

The room anchored coordinate system is specified in clause 4.2.1.

5.2.1.3 Position in screen-anchored coordinates

The decoder shall set *anchor* = SCREEN.

The position $P(x_{S_{screen}}, y_{S_{screen}}, z_{S_{screen}})$ shall be determined as $P = (\text{pos3D_X}; \text{pos3D_Y}; \text{pos3D_Z})$

The decoder shall set *3D_coordinates* at the decoder interface to the three dimensional coordinates $(x_{S_{screen}}, y_{S_{screen}}, z_{S_{screen}})$ of the position P.

Position P together with *screen_factor* and *depth_factor* can be used to flexibly vary between a screen-anchored and a room-anchored position. A position $P_{interpolated}$ can be determined as follows:

- 1) Let $C_R = O_S + \left(w_S \times X_{screen}; Y_{screen}; \frac{h_S}{2} \times (Z_{screen} + 1) \right)$ be the transformation of screen-anchored coordinates to the room-anchored system as specified in clause 4.2.2.
- 2) Let $C_S = P$.
- 3) Let $M_1 = \begin{vmatrix} \text{screen_factor} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \text{screen_factor} \end{vmatrix}$
- 4) Let $M_2 = \begin{vmatrix} y^{\text{depth_factor}} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & y^{\text{depth_factor}} \end{vmatrix}$
- 5) Let $I = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix}$ be the 3x3 identity matrix.
- 6) $P_{interpolated} = M_2 \times (M_1 \times C_S + (I - M_1) \times C_R) + (I - M_2) \times C_R$.

The screen-anchored coordinate system is specified in clause 4.2.2.

5.2.1.4 Position in speaker-anchored coordinates

The decoder shall set *anchor* = SPEAKER.

For a bed the coordinate of each contained bed object is indicated by the *bed_channel_assignment*.

The *bed_channel_assignment* is a list of channel labels that indicate a speaker-anchored coordinate. Objects contained in the bed are mapped to the channel labels in the same order. Each object has one coordinate, e.g. one speaker it is intended be played back from.

EXAMPLE: For a bed containing the objects (*obj0*, *obj1*, *obj2*, *obj3*, *obj4*, *obj5*) the speaker-anchored coordinates are indicated by the *bed_channel_assignment* = (RC_L, RC_R, RC_C, RC_LFE, RC_LS, RC_RS). In this case the channel label of *obj0* is 'RC_L', indicating the coordinate of the loudspeaker "Room Centric Left", the label of *obj1* is 'RC_R', and so on.

For each object contained in a bed, the decoder shall set *speaker_label* to the coordinate indicated by the corresponding *bed_channel_assignment*.

The speaker-anchored coordinate system is specified in clause 4.2.3.

5.2.2 Size

The size property is the data that is provided as *size* at the decoder interface.

The size property comprises the three values (width; depth; height) that indicate the apparent 3-dimensional spatial extent of the object.

Width, depth and height can be controlled independently along the three axes x, y and z of the coordinate system and are bounded by [0; 1], in units of the coordinate system's dimensions.

The size property shall be set as (width; depth; height) = (object_width; object_depth; object_height).

EXAMPLE 1: If all size properties are one, the object is as wide as the room.

EXAMPLE 2: If all size properties are zero, the object is a point source.

EXAMPLE 3: If two of the size properties are zero, it extends along a line.

EXAMPLE 4: If only one of the size properties is zero, it is a rectangle.

EXAMPLE 5: If all sizes are non-zero and equal, the object is a cube; otherwise it is a rectangular cuboid.

Table 2 lists the related bitstream elements and their reference.

Table 2: Object size related bitstream elements

bitstream element	reference
object_size_idx	Clause 5.6.1.2.1
object_size_bits	Clause 5.6.1.2.2
object_width_bits	Clause 5.6.1.2.3
object_depth_bits	Clause 5.6.1.2.4
object_height_bits	Clause 5.6.1.2.5

5.2.3 Priority

The priority property is the data that is provided as *priority* at the decoder interface.

The priority property shall be set to *object_priority*. It imposes an ordering by importance where higher priority indicates higher importance and is bounded by [0; 1].

Table 3 lists the related bitstream elements and their reference.

Table 3: Object priority related bitstream elements

bitstream element	reference
b_default_priority	Clause 5.6.1.3.1
object_priority_bits	Clause 5.6.1.3.2

5.2.4 Gain

The gain property is the data that is provided as *gain* at the decoder interface.

The gain property value shall be set to *object_gain*. The gain property can be used to apply a custom gain value to an object. It is bounded by $[-\infty\text{dB}; +15\text{dB}]$.

Table 4 lists the related bitstream elements and their reference.

Table 4: Object gain related bitstream elements

bitstream element	reference
object_gain_idx	Clause 5.6.1.4.1
object_gain_bits	Clause 5.6.1.4.2

5.2.5 Channel lock

The channel lock property is the data that is provided as *channel_lock* at the decoder interface.

Channel lock is a Boolean property that shall be set to *b_object_snap*. Channel lock can be used to constrain rendering of an object to a single speaker, providing a non-diffuse, timbre-neutral reproduction. True indicates that the object rendering is constrained to a single speaker; false indicates that panning may be used.

Table 5 lists the related bitstream element and its reference.

Table 5: Object snap related bitstream elements

bitstream element	reference
b_object_snap	Clause 5.6.1.5.1

5.2.6 Zone constraints

The zone constraints property is the data that is provided in *zone_constraints_update* at the decoder interface.

The list *zone_constraints* specifies zone constraints (include or exclude) for the following zones:

- Screen zone
- Side zone
- Surround zone
- Back zone
- Centre-and-back zone
- Top-Bottom zone

NOTE: Zones may be defined by a list of speakers as listed in table A.7, or by a sub-volume of the room, as specified in table B.19.

Based on the values of *zone_constraints_idx* and *b_enable_elevation*, the decoder shall create a *zone_constraints* list that indicates the zone constraints (include or exclude) for each zone.

EXAMPLE: If *zone_constraints_idx*=2 and *b_enable_elevation* is false, the Side zone and the Top-Bottom zone are excluded. The *zone_constraints* list for this case is listed in table 6.

Table 6: zone_constraints list when zone_constraints_idx=2 and b_enable_elevation is false

Zone	Zone constraints
Screen zone	include
Side zone	exclude
Surround zone	include
Back zone	include
Centre-and-back zone	include
Top-Bottom zone	exclude

Table 7 lists the related bitstream elements and their reference.

Table 7: Object zone constraints related bitstream elements

bitstream element	reference
zone_constraints_idx	Clause 5.6.1.6.1
b_enable_elevation	Clause 5.6.1.6.2

5.2.7 Object Divergence

The object divergence property is the data that is provided as *object_divergence* at the decoder interface.

Object divergence is a property that shall be set to the value of *object_divergence*. Divergence is used to convert one object into two objects, where the energy is spread along the X-Axis.

Table 8 lists the related bitstream element and its reference.

Table 8: Object divergence related bitstream elements

bitstream element	reference
object_div_mode	Clause 5.6.6.3.2
object_div_table	Clause 5.6.6.3.3
object_div_code	Clause 5.6.6.3.4

5.2.8 Object Trim

The object trim property is the data that is provided as *object_trim* at the decoder interface.

Object trim is a property that shall be set to the transmitted trim values listed in table 9. Object trim can be used to lower the level of out-of-screen elements that are included in the mix. This can be desirable when immersive mixes are reproduced in layouts with few loudspeakers.

Table 9 lists the related bitstream element and its reference.

Table 9: Object trim related bitstream elements

bitstream element	reference
warp_mode	Clause 5.6.5.1
global_trim_mode	Clause 5.6.5.2
b_default_trim	Clause 5.6.5.3
b_disable_trim	Clause 5.6.5.4
trim_balance_presence	Clause 5.6.5.5
trim_centre	Clause 5.6.5.6
trim_surround	Clause 5.6.5.7
trim_height	Clause 5.6.5.8
bal3D_Y_sign_tb_code	Clause 5.6.5.9
bal3D_Y_amount_tb	Clause 5.6.5.10
bal3D_Y_sign_lis_code	Clause 5.6.5.11
bal3D_Y_amount_lis	Clause 5.6.5.12

5.3 Property update information

5.3.1 Introduction

The Property Update Information contains the data that is provided as *timing_data* at the decoder interface.

The OAMD bitstream supports multiple updates of the object properties per codec frame. The bitstream contains timing information corresponding to these updates. In the context of this clause, *previous* and *subsequent* refer to the temporal dimension (i.e. the "subsequent update" is an update for the same object, at a later time).

EXAMPLE: Three sequential update blocks *previous*, *current* and *subsequent* have the start times:

$$\text{start_time}_{\text{previous}} < \text{start_time}_{\text{current}} < \text{start_time}_{\text{subsequent}}$$

5.3.2 Timing of property updates

The timing of one transmitted property update specifies its start time, along with that its context with preceding or subsequent updates and the temporal duration for an interpolation process between successive updates.

The OAMD bitstream syntax supports up to eight property updates per object in each codec frame (frame). The timing of one update is identical for all objects, i.e. the number of signalled updates or the start and stop time of each property update is identical for all objects. The metadata contained in the *md_update_info* block carries the signalled timing data applicable to all updates for all transmitted objects. The contained instances of the *block_update_info* block contain metadata that signals the timing data of the corresponding specific update.

In the following paragraphs the *ramp_duration* value for smoothing is introduced first, the values of *sample_offset* and *block_offset_factor* are introduced afterward for calculating the value of *start_sample*. Finally, the calculation of *frame_offset* is specified.

The metadata contained in the *md_update_info* block indicates the value of *ramp_duration* that specifies a time period in audio samples for an interpolation from signalled object property values of the previous property update to values of the current update.

Figure 4 shows the ramp duration for three sequential property updates n , $n+1$ and $n+2$ for one object. The three property updates have the *start_sample* values t_n , t_{n+1} and t_{n+2} . The corresponding *ramp_duration* values are rd_n , rd_{n+1} and rd_{n+2} . The points of time md_n , md_{n+1} and md_{n+2} are the end points of the interpolation process where the signalled values for the object properties are reached after the time period of *ramp_duration*.

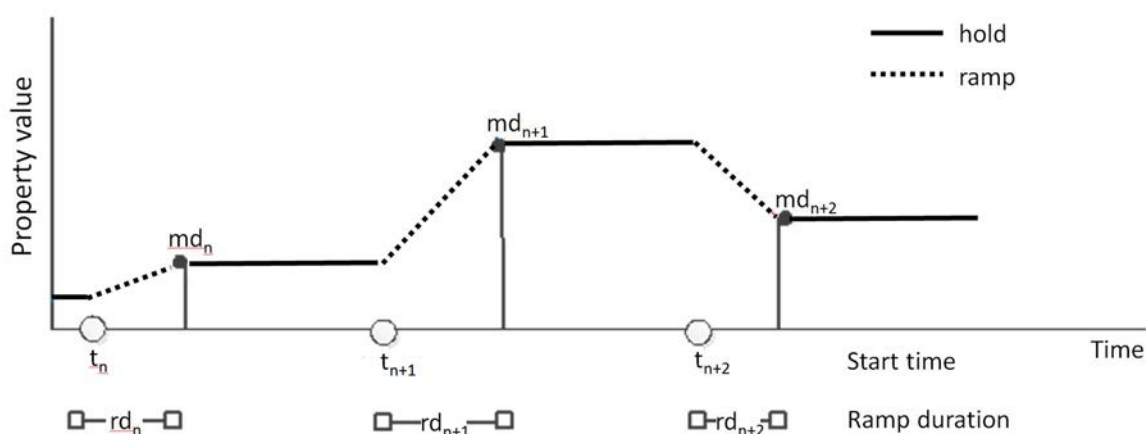
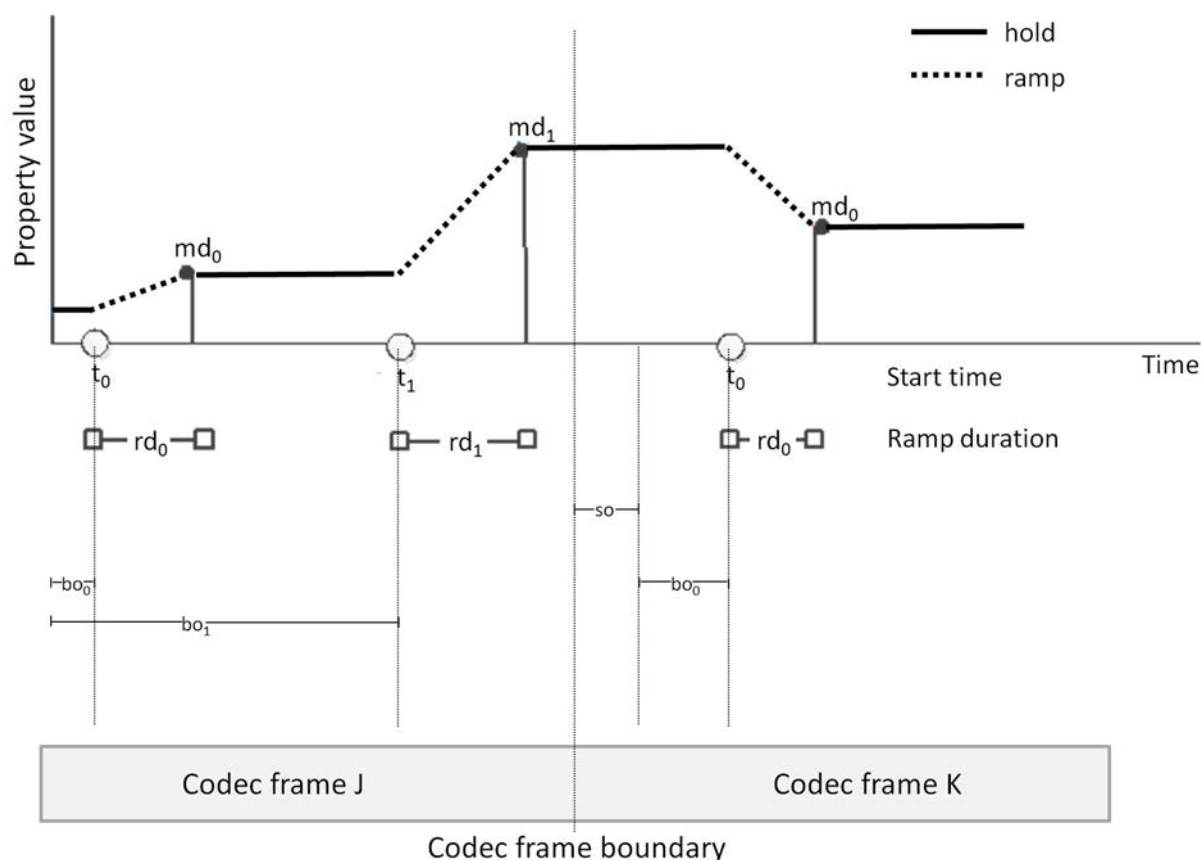


Figure 4: Temporal context of the ramp duration for three sequential property updates

For each property update the timing metadata contains one value for *block_offset_factor* that indicates a time period in samples as offset from a time point *sample_offset* common for all property updates. The value of *sample_offset* is a temporal offset in samples to the first PCM audio sample that the data in the OAMD payload applies to, as specified in ETSI TS 102 366 [1], clauses H.2.2.3.1 and H.2.2.3.2.

Figure 5 shows the temporal context of the start time for two sequential property updates md_0 and md_1 in a codec frame J and one property update md_0 in the following codec frame K . The *start_sample* values t_n shall be determined by the following equation: $t_n = so + 32 \times bo_n$. In this equation so is the value of *sample_offset* and bo_n is the value of *block_offset_factor* for the corresponding property update.



NOTE: For codec frame J the value so for *sample_offset* is zero.

Figure 5: Temporal context of the start time for three sequential property updates

In the processing of each codec frame the decoder shall add the value 1 536 (the codec transform size in samples) to *frame_offset*.

Table 10 lists the related bitstream elements and their reference.

Table 10: Property update timing related bitstream elements

bitstream element	reference
<code>sample_offset_code</code>	Clause 5.6.2.1
<code>sample_offset_idx</code>	Clause 5.6.2.2
<code>num_obj_info_blocks_bits</code>	Clause 5.6.2.4
<code>block_offset_factor_bits</code>	Clause 5.6.2.5
<code>ramp_duration_code</code>	Clause 5.6.2.5
<code>b_use_ramp_duration_idx</code>	Clause 5.6.2.6
<code>ramp_duration_idx</code>	Clause 5.6.2.8
<code>ramp_duration_bits</code>	Clause 5.6.2.9

5.4 Object audio metadata structure

The OAMD bitstream contains metadata updates. Each update contains the metadata is updated; timing information is shared between objects and updates.

Figure 6 shows the OAMD bitstream structure.

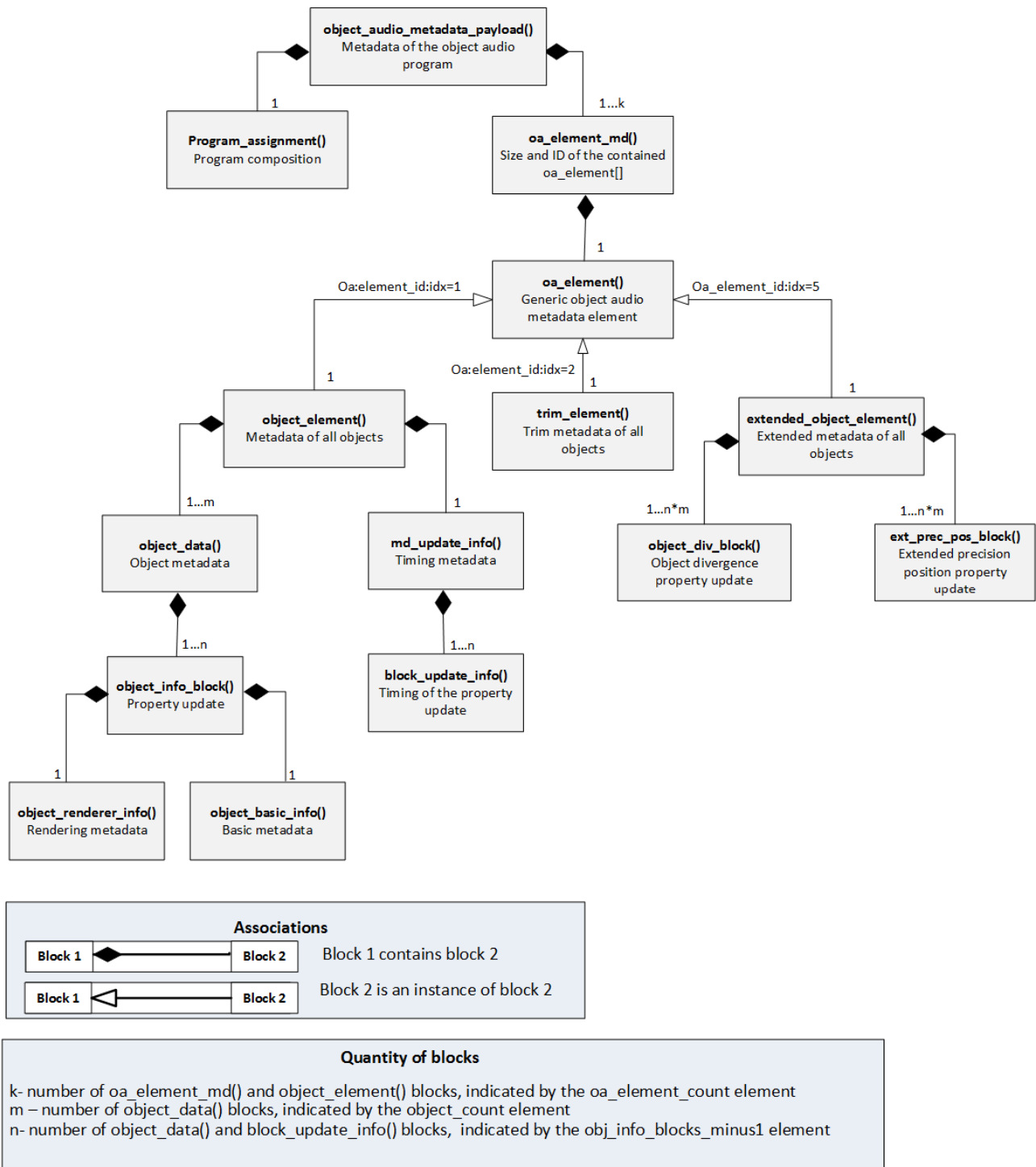


Figure 6: OAMD bitstream structure

Table 11 lists the blocks contained in the OAMD bitstream.

Table 11: OAMD bitstream blocks

Block	Contents	See also
object_audio_metadata_payload	The OAMD payload (this is the top level block)	
program_assignment	Metadata indicating the OAMD content description	
oa_element_md	Metadata indicating the size and identification of the oa_element	
oa_element	A generic object-based audio metadata element	
object_element	Property updates for all objects	
object_data	All property updates for one object	
md_update_info	Sample offset information common to all contained block_update_info elements	Clause 5.3
block_update_info	Timing information for each property update	Clause 5.3
object_info_block	One property update for one object	Clause 5.3
object_basic_info	Gain and priority	Clause 5.2.4 and clause 5.2.3
object_render_info	Position, size, channel lock and zone constraints	Clause 5.2.1, clause 5.2.2, clause 5.2.5 and clause 5.2.6
trim_element	Trim metadata	Clause 5.2.8
extended_object_element	Property updates for the extended metadata (divergence and high precision position)	Clause 5.6.6.4.3, clause 5.6.6.4.4, clause 5.6.6.4.5
obj_div_block	Divergence	Clause 5.2.7
ext_prec_pos_block	High precision position	

5.5 Bitstream syntax

5.5.1 variable_bits_max

Syntax	No of bits
<pre> variable_bits_max(n, max_num_groups) { value = 0; num_group = 1; read; n value += read; b_read_more; 1 if (max_num_groups > num_group) { if (b_read_more) { value <<= n; value += (1 << n); } while (b_read_more) { read; n value += read; b_read_more; 1 if (num_group >= max_num_groups) { break(); } if (b_read_more) { value <<= n; value += (1 << n); num_group += 1; } } } } </pre>	

Syntax	No of bits
<pre> return value; } </pre>	

5.5.2 object_audio_metadata_payload

Syntax	No of bits
<pre> object_audio_metadata_payload() { oa_md_version_bits; 2 if (oa_md_version_bits == 0x3) { oa_md_version_bits_ext; 3 oa_md_version_bits += oa_md_version_bits_ext; } object_count_bits; 5 if (object_count_bits == 0x1F) { object_count_bits_ext; 7 object_count_bits += object_count_bits_ext; } program_assignment(); b_alternate_object_data_present; 1 oa_element_count_bits; 4 if (oa_element_count_bits == 0xF) { oa_element_count_bits_ext; 5 oa_element_count_bits += oa_element_count_bits_ext; } for (i = 0; i < oa_element_count_bits; i++) { oa_element_md(); } padding; VAR } </pre>	

5.5.3 program_assignment

Syntax	No of bits
<pre> program_assignment() { b_dyn_object_only_program; 1 if (b_dyn_object_only_program) { b_lfe_present; 1 } else { content_description[]; 4 if (content_description[3]) { b_bed_chan_distribute; 1 b_multiple_bed_instances_present; 1 if (b_multiple_bed_instances_present) { num_bed_instances_bits; 3 } for (beds = 0; beds < num_bed_instances; beds++) { b_lfe_only; 1 if (!b_lfe_only) { b_standard_chan_assign; 1 if (b_standard_chan_assign) { bed_channel_assignment[]; 10 } else { nonstd_bed_channel_assignment[]; 17 } } } } } } </pre>	

Syntax	No of bits
if (content_description[2]) { intermediate_spatial_format_idx ;	3
}	
if (content_description[1]) { num_dynamic_objects_bits ;	5
if (num_dynamic_objects_bits == 0x1F) { num_dynamic_objects_bits_ext ;	7
num_dynamic_objects_bits += num_dynamic_objects_bits_ext; }	
}	
if (content_description[0]) { reserved_data_size_bits ;	4
reserved_data(); padding ;	VAR
}	
}	
}	

5.5.4 oa_element_md

Syntax	No of bits
oa_element_md() { oa_element_id_idx ;	4
oa_element_size_bits = variable_bits_max(4,4); if (b_alternate_object_data_present) { alternate_object_data_id_idx ;	4
}	
b_discard_unknown_element ;	1
oa_element(); padding ;	VAR
}	

5.5.5 object_element

Syntax	No of bits
object_element() { md_update_info(); b_reserved_data_not_present ;	1
if (!reserved_data_not_present) { reserved ;	5
}	
for (j = 0; j < object_count; j++) { object_data(); }	
}	

5.5.6 md_update_info

Syntax	No of bits
md_update_info() { sample_offset_code ;	2
if (sample_offset_code == 0b01) { sample_offset_idx ;	2
}	

Syntax	No of bits
<pre> else { if (sample_offset_code == 0b10) { sample_offset_bits; 5 } } num_obj_info_blocks_bits; 3 for (blk = 0; blk < num_obj_info_blocks; blk++) { block_update_info(blk); } </pre>	

5.5.7 block_update_info

Syntax	No of bits
<pre> block_update_info() { block_offset_factor_bits; 6 ramp_duration_code; 2 if (ramp_duration_code == 0b11) { b_use_ramp_duration_idx; 1 if (b_use_ramp_duration_idx) { ramp_duration_idx; 4 } } else { ramp_duration_bits; 11 } } </pre>	

5.5.8 object_data

Syntax	No of bits
<pre> object_data() { for (blk = 0; blk < num_obj_info_blocks; blk++) { object_info_block(blk); } } </pre>	

5.5.9 object_info_block

Syntax	No of bits
<pre> object_info_block(blk) { b_object_not_active; 1 if (b_object_not_active) { object_basic_info_status_idx = 0b00; } else { if (blk == 0) { object_basic_info_status_idx = 0b01; } else { object_basic_info_status_idx; 2 } } if ((object_basic_info_status_idx == 0b01) (object_basic_info_status_idx == 0b11)) { object_basic_info(); } if (b_object_not_active) { object_render_info_status_idx = 0b00; } else { if (!b_object_in_bed_or_isf) { if (blk == 0) { object_render_info_status_idx = 0b01; } else { object_render_info_status_idx; 2 } } else { object_render_info_status_idx = 0b00; } } if ((object_render_info_status_idx == 0b01) (object_render_info_status_idx == 0b11)) { object_render_info(); } b_additional_table_data_exists; 1 if (b_additional_table_data_exists) { additional_table_data_size_bits; 4 additional_table_data(); padding; VAR } } </pre>	

5.5.10 object_basic_info

Syntax	No of bits
<pre> object_basic_info() { if (object_basic_info_status_idx == 0b01) { object_basic_info[] = {true, true}; } else { object_basic_info[]; 2 } if (object_basic_info[1]) { object_gain_idx; 2 if (object_gain_idx == 0b10) { object_gain_bits; 6 } } } </pre>	

Syntax	No of bits
<pre> } if (object_basic_info[0]) { b_default_object_priority; 1 if (!b_default_object_priority) { object_priority_bits; 5 } } } </pre>	

5.5.11 object_render_info

Syntax	No of bits
<pre> object_render_info() { if (object_render_info_status_idx == 0b01) { obj_render_info[] = {true, true, true, true}; } else { obj_render_info[]; 4 } if (obj_render_info[0]) { if (blk == 0) { b_differential_position_specified = FALSE; } else { b_differential_position_specified; 1 } if (b_differential_position_specified) { diff_pos3D_X_bits; 3 diff_pos3D_Y_bits; 3 diff_pos3D_Z_bits; 3 } else { pos3D_X_bits; 6 pos3D_Y_bits; 6 pos3D_Z_sign_bits; 1 pos3D_Z_bits; 4 } b_object_distance_specified; 1 if (b_object_distance_specified) { b_object_at_infinity; 1 if (b_object_at_infinity) { object_distance = inf; } else { distance_factor_idx; 4 } } } if (obj_render_info[1]) { zone_constraints_idx; 3 b_enable_elevation; 1 } if (obj_render_info[2]) { object_size_idx; 2 if (object_size_idx == 0b01) { object_size_bits; 5 } else { if (object_size_idx == 0b10) { object_width_bits; 5 object_depth_bits; 5 object_height_bits; 5 } } } } </pre>	

Syntax	No of bits
<pre> } } if (obj_render_info[3]) { b_object_use_screen_ref; 1 if (b_object_use_screen_ref) { screen_factor_bits; 3 depth_factor_idx; 2 } else { screen_factor_bits = 0; } } b_object_snap; 1 } </pre>	

5.5.12 trim_element

Syntax	No of bits
<pre> trim_element() { warp_mode; 2 reserved; 2 global_trim_mode; 2 if (global_trim_mode == 0b10) { for (cfg = 0; cfg < NUM_TRIM_CONFIGS; cfg++) { b_default_trim; 1 if (b_default_trim == 0) { b_disable_trim; 1 if (b_disable_trim == 0) { trim_balance_presence[]; 5 if (trim_balance_presence[4]) { trim_centre; 4 } if (trim_balance_presence[3]) { trim_surround; 4 } if (trim_balance_presence[2]) { trim_height; 4 } if (trim_balance_presence[1]) { bal3D_Y_sign_tb_code; 1 bal3D_Y_amount_tb; 4 } if (trim_balance_presence[0]) { bal3D_Y_sign_lis_code; 1 bal3D_Y_amount_lis; 4 } } } } } b_disable_trim_per_obj; 1 if (b_disable_trim_per_obj) { for (obj = 0; obj < object_count; obj++) { b_disable_trim; 1 } } } </pre>	

5.5.13 extended_object_element

Syntax	No of bits
<pre> extended_object_element() { b_obj_div_block; 1 if (b_obj_div_block) { for (obj = 0; obj < object_count; obj++) { for (blk = 0; blk < num_obj_info_blocks; blk++) { obj_div_block(obj, b_obj_not_active, obj_type); } } } b_ext_prec_pos_block; 1 if (b_ext_prec_pos_block) { for (obj = 0; obj < object_count; obj++) { for (blk = 0; blk < num_obj_info_blocks; blk++) { ext_prec_pos_block(obj, b_obj_not_active, obj_type); } } } } </pre>	

5.5.14 obj_div_block

Syntax	No of bits
<pre> obj_div_block(obj_id, b_obj_not_active, obj_type) { if (b_obj_not_active) { object_divergence = 0; } else { if (obj_type == DYNAMIC) { b_object_divergence; 1 if (b_object_divergence) { object_div_mode; 2 if (object_div_mode == 0) { object_div_table; 2 } if (object_div_mode == 2 object_div_mode == 3) { object_div_code; 6 } else { object_divergence = 0; } } } } } </pre>	

5.5.15 ext_prec_pos_block

Syntax	No of bits
<pre> ext_prec_pos_block(obj_id, b_obj_not_active, obj_type) { if (b_obj_not_active) { b_ext_prec_pos = false; } else { if (obj_type == DYNAMIC) { b_ext_prec_pos; 1 } } } </pre>	

Syntax	No of bits
if (b_ext_prec_pos) {	
ext_prec_pos_presence[];	3
if (ext_prec_pos_presence[2]) {	
ext_prec_pos3D_X;	2
}	
if (ext_prec_pos_presence[1]) {	
ext_prec_pos3D_Y;	2
}	
if (ext_prec_pos_presence[0]) {	
ext_prec_pos3D_Z;	2
}	
}	
}	
}	

5.6 Bitstream description

5.6.0 Object audio metadata content description

5.6.0.1 oa_md_version_bits

The `oa_md_version_bits` element is an unsigned integer that determines the OAMD syntax version.

5.6.0.2 object_count_bits

The `object_count_bits` codeword indicates the value of *object_count*.

The value of *object_count* is determined by the following equation: $object_count = object_count_bits + 1$. In this equation, the bits of the `object_count_bits` element are interpreted as an unsigned integer. *object_count* indicates the total number of objects in the bitstream.

5.6.0.3 b_alternate_object_data_present

The `b_alternate_object_data_present` flag indicates whether each `oa_element` block contains an `alternate_object_data_id_idx` element.

5.6.0.4 oa_element_count_bits

The `oa_element_count_bits` unsigned integer determines the number of `oa_element` blocks contained in the `object_audio_metadata_payload` block.

5.6.0.5 b_dyn_object_only_program

The `b_dyn_object_only_program` flag indicates whether the bitstream contains one or more dynamic objects plus an optional LFE channel (when true), or it contains a combination of one or more bed instances, intermediate spatial format and one or more dynamic objects (when false).

5.6.0.6 b_lfe_present

The `b_lfe_present` flag indicates whether a bitstream that otherwise contains only dynamic objects also contains an LFE channel.

5.6.0.7 content_description[]

The `content_description[]` array indicates the object types present in the bitstream.

Each element of the `content_description` array is a flag that indicates whether one or more objects of the assigned object type are present in the bitstream. Table 11a lists the object types for the `content_description[]` array elements.

Table 11a: Object types for `content_description` array elements

<code>content_description[]</code> array element	assigned object type
3	object(s) with speaker-anchored coordinate(s) (bed objects)
2	intermediate spatial format (ISF)
1	object(s) with room-anchored or screen-anchored coordinates
0	reserved

5.6.0.8 `b_bed_chan_distribute`

The `b_bed_chan_distribute` flag indicates whether bed channels (i.e. objects with a speaker-anchored position) are intended to be distributed to multiple appropriate loudspeakers.

5.6.0.9 `b_multiple_bed_instances_present`

The `b_multiple_bed_instances_present` flag indicates whether the bitstream contains multiple bed instances.

If the `b_multiple_bed_instances_present` flag is false, it indicates that `num_bed_instances = 1`.

5.6.0.10 `num_bed_instances_bits`

The `num_bed_instances_bits` codeword indicates the value of `num_bed_instances`.

The value of `num_bed_instances` is determined by the following equation: $\text{num_bed_instances} = \text{num_bed_instances_bits} + 2$. In this equation, the bits of `num_bed_instances_bits` are interpreted as an unsigned integer.

5.6.0.11 `intermediate_spatial_format_idx`

The `intermediate_spatial_format_idx` index indicates the intermediate spatial format (ISF) type of the associated objects.

The ISF type indicated by `intermediate_spatial_format_idx` is shown in table 11b.

Table 11b: Intermediate spatial format

<code>intermediate_spatial_format_idx</code>	ISF type (SR notation)	objects present (MULZ order)	Number of objects
0	SR3.1.0.0	M1 M2 M3 U1	4
1	SR5.3.0.0	M1 M2 M3 M4 M5 U1 U2 U3	8
2	SR7.3.0.0	M1 M2 M3 M4 M5 M6 M7 U1 U2 U3	10
3	SR9.5.0.0	M1 M2 M3 M4 M5 M6 M7 M8 M9 U1 U2 U3 U4 U5	14
4	SR7.5.3.0	M1 M2 M3 M4 M5 M6 M7 U1 U2 U3 U4 U5 L1 L2 L3	15
5	SR15.9.5.1	M1 M2 M3 M4 M5 M6 M7 M8 M9 M10 M11 M12 M13 M14 M15 U1 U2 U3 U4 U5 U6 U7 U8 U9 L1 L2 L3 L4 L5 Z1	30
6, 7	Reserved		

NOTE 1: SR refers to a stacked ring format used for intermediate spatial format objects.
NOTE 2: MULZ refers to the order in which audio signals for ISF objects occur.

5.6.0.12 num_dynamic_objects_bits

The `num_dynamic_objects_bits` codeword indicates the value of `num_dynamic_objects`.

The value of `num_dynamic_objects` is determined by the following equation: $\text{num_dynamic_objects} = \text{num_dynamic_objects_bits} + 1$. In this equation, the bits of `num_dynamic_objects_bits` are interpreted as unsigned integer.

5.6.1 Audio object properties

5.6.1.1 Position

5.6.1.1.1 Void

5.6.1.1.2 Void

5.6.1.1.3 b_standard_chan_assign

The `b_standard_chan_assign` flag indicates whether the `bed_channel_assignment` is indicated by the `bed_channel_assignment []` array (if true) or by the `nonstd_bed_channel_assignment []` array (when false).

5.6.1.1.4 bed_channel_assignment[]

The `bed_channel_assignment []` array of flags indicates the `bed_channel_assignment`.

The `bed_channel_assignment` is a list of channel labels. Each element of the `bed_channel_assignment []` array is a flag that indicates whether the corresponding channel labels or pair of channel labels shall be contained in the `bed_channel_assignment` list.

Table 12 lists how elements of the `bed_channel_assignment []` array relate to channel labels.

Channel labels in the `bed_channel_assignment` list shall be ordered like the `bed_channel_assignment []` array elements, starting with bit 0 (if present). If the number of channel labels is 2, the channel labels shall be ordered as shown in column two.

Table 12: Channel labels contained in the `bed_channel_assignment` list indicated by the `bed_channel_assignment[]` array elements

<code>bed_channel_assignment []</code> array index	Speaker label(s)	Number of speaker labels
9	RC_L/RC_R	2
8	RC_C	1
7	RC_LFE	1
6	RC_LS/RC_RS	2
5	RC_LB/RC_RB	2
4	RC_TFL/RC_TFR	2
3	RC_TSL/RC_TSR	2
2	RC_TBL/RC_TBR	2
1	RC_LW/RC_RW	2
0	RC_LFE2	1

5.6.1.1.5 nonstd_bed_channel_assignment[]

The `nonstd_bed_channel_assignment []` array indicates the `bed_channel_assignment`.

The `bed_channel_assignment` is a list of channel labels. Each element of the `nonstd_bed_channel_assignment []` array is a flag that indicates whether the corresponding channel label shall be contained in the `bed_channel_assignment` list.

Table 13 lists how elements of the `bed_channel_assignment []` array relate to channel labels.

Channel labels in the *bed_channel_assignment* list shall be ordered like the *bed_channel_assignment []* array elements, starting with index 0.

Table 13: Channel labels contained in the *bed_channel_assignment* list indicated by the *nonstd_bed_channel_assignment[]* array elements

<i>non_std_bed_channel_assignment []</i> array index	Channel label(s)
16	RC_L
15	RC_R
14	RC_C
13	RC_LFE
12	RC_LS
11	RC_RS
10	RC_LB
9	RC_RB
8	RC_TFL
7	RC_TFR
6	RC_TSL
5	RC_TSR
4	RC_TBL
3	RC_TBR
2	RC_LW
1	RC_RW
0	RC_LFE2

5.6.1.1.6 *b_lfe_only*

The *b_lfe_only* flag indicates whether the *bed_channel_assignment* contains one LFE channel and no other channels.

5.6.1.1.7 *b_differential_position_specified*

The *b_differential_position_specified* flag indicates how the position values *pos3D_X*, *pos3D_Y* and *pos3D_Z* are signalled in the bitstream.

Table 14 specifies how the values of *pos3D_X*, *pos3D_Y* and *pos3D_Z* are signalled in the bitstream.

Table 14: Signalling of *pos3D_X*, *pos3D_Y* and *pos3D_Z*

<i>b_differential_position_specified</i>	signalling
0	<i>pos3D_X</i> , <i>pos3D_Y</i> and <i>pos3D_Z</i> are indicated by <i>pos3D_X_bits</i> , <i>pos3D_Y_bits</i> , <i>pos3D_Z_sign_bits</i> and <i>pos3D_Z_bits</i> (no differential coding)
1	<i>pos3D_X</i> , <i>pos3D_Y</i> and <i>pos3D_Z</i> are indicated by <i>diff_pos3D_X_bits</i> , <i>diff_pos3D_Y_bits</i> and <i>diff_pos3D_Z_bits</i> (differential coding)

5.6.1.1.8 *pos3D_X_bits*

The *pos3D_X_bits* codeword indicates the value of *pos3D_X*.

pos3D_X indicates the x-coordinate value for the position of the object.

The value of *pos3D_X* shall be determined by the following equation:

$$\text{pos3D}_X = \min \left(1, \frac{\text{pos3D}_X_bits}{62} + \frac{\text{ext_prec_pos3D}_X}{62 \times 5} \right).$$

In this equation, the bits of *pos3D_X_bits* are interpreted as an unsigned integer.

NOTE: The value of *ext_prec_pos3D_X* is specified in clause 5.6.6.4.3.

5.6.1.1.9 pos3D_Y_bits

The `pos3D_Y_bits` codeword indicates the value of $pos3D_Y$.

$pos3D_Y$ indicates the y-coordinate value for the position of the object.

The value of $pos3D_Y$ shall be determined by the following equation:

$$pos3D_Y = \min \left(1; \frac{pos3D_Y_bits}{62} + \frac{ext_prec_pos3D_Y}{62 \times 5} \right),$$

where the bits of `pos3D_Y_bits` are interpreted as an unsigned integer.

NOTE: The value of $ext_prec_pos3D_Y$ is specified in clause 5.6.6.4.4.

5.6.1.1.10 pos3D_Z_sign_bits

The `pos3D_Z_sign_bits` codeword indicates the value of $pos3D_Z_sign$.

$pos3D_Z_sign$ is used to determine whether the z-coordinate for the position of the object is positive or negative.

The $pos3D_Z_sign$ value shall be determined by the following equation:

$$pos3D_Z_sign = \begin{cases} -1, & \text{when } pos3D_Z_sign_bits = 0 \\ +1, & \text{else} \end{cases}$$

5.6.1.1.11 pos3D_Z_bits

The `pos3D_Z_bits` codeword indicates the value of $pos3D_Z$.

$pos3D_Z$ indicates the z-coordinate value for the position of the object.

The value of $pos3D_Z$ shall be determined by the following equation:

$$pos3D_Z = pos3D_Z_sign \times \frac{pos3D_Z_bits}{15} + \frac{ext_prec_pos3D_Z}{15 \times 5}$$

The bits of `pos3D_Z_bits` are interpreted as an unsigned integer and the value of $pos3D_Z_sign$ is specified in clause 5.6.1.1.10.

NOTE: The value of $ext_prec_pos3D_Z$ is specified in clause 5.6.6.4.5.

5.6.1.1.12 diff_pos3D_X_bits

The `diff_pos3D_X_bits` codeword indicates the value of $pos3D_X$, taking into account the previous standard precision value of $pos3D_X$ (differential coding).

The $pos3D_X$ value shall be determined by the following equation:

$$pos3D_X = \max \left(0; \min \left(1; \frac{pos3D_X_bits_{prev}}{62} + \frac{diff_pos3D_X_bits}{62} + \frac{ext_prec_pos3D_X}{62 \times 5} \right) \right)$$

In this equation, the bits of `diff_pos3D_X_bits` are interpreted as a signed integer.

The $pos3D_X_bits_{prev}$ value is the standard precision position value coded in the previous metadata update block.

NOTE: The previous metadata update block is defined in clause 5.3.

5.6.1.1.13 diff_pos3D_Y_bits

The `diff_pos3D_Y_bits` codeword indicates the value of $pos3D_Y$, taking into account the previous standard precision value of $pos3D_Y$ (differential coding).

The $pos3D_Y$ value shall be determined by the following equation:

$$\text{pos3D}_Y = \max\left(0; \min\left(1; \frac{\text{pos3D}_Y_{\text{bits}_{\text{prev}}}}{62} + \frac{\text{diff_pos3D}_Y_{\text{bits}}}{62} + \frac{\text{ext_prec_pos3D}_Y}{62 \times 5}\right)\right)$$

In this equation, the bits of `diff_pos3D_Y_bits` are interpreted as a signed integer.

The `pos3D_Y_bitsprev` value is the standard precision position value coded in the previous metadata update block.

NOTE: The previous metadata update block is defined in clause 5.3.

5.6.1.1.14 `diff_pos3D_Z_bits`

The `diff_pos3D_Z_bits` codeword indicates the value of `pos3D_Z`, taking into account the previous value of `pos3D_Z` (differential coding).

The `pos3D_Z` value shall be determined by the following equation:

$$\text{pos3D}_Z = \max\left(-1; \min\left(1; \frac{\text{pos3D}_Z_{\text{bits}_{\text{prev}}}}{15} + \frac{\text{diff_pos3D}_Z_{\text{bits}}}{15} + \frac{\text{ext_prec_pos3D}_Z}{15 \times 5}\right)\right)$$

In this equation, the bits of `diff_pos3D_Z_bits` are interpreted as a signed integer.

The `pos3D_Z_bitsprev` value is the standard precision position value coded in the previous metadata update block.

NOTE: The previous metadata update block is defined in clause 5.3.

5.6.1.1.15 `b_object_distance_specified`

The `b_object_distance_specified` flag indicates whether the position of an object is outside of the room boundaries.

5.6.1.1.16 `b_object_at_infinity`

The `b_object_at_infinity` flag indicates whether the object distance from the listening position is equal to infinity (when true) or is indicated by the `distance_factor_idx` element (when false).

5.6.1.1.17 `distance_factor_idx`

The `distance_factor_idx` index indicates the value of `distance_factor`.

The value of `distance_factor` shall be determined as specified in table 15.

Table 15: `distance_factor` value indicated by the `distance_factor_idx` element

<code>distance_factor_idx</code>	<code>distance_factor</code>
0	1,1
1	1,3
2	1,6
3	2,0
4	2,5
5	3,2
6	4,0
7	5,0
8	6,3
9	7,9
10	10,0
11	12,6
12	15,8
13	20,0
14	25,1
15	50,1

5.6.1.1.18 `b_object_use_screen_ref`

The `b_object_use_screen_ref` flag indicates whether the signalled values of `pos3D_X`, `pos3D_Y` and `pos3D_Z` are related to the screen (when true) or to the room (when false).

If the `b_object_use_screen_ref` flag is true, the `screen_factor_bits` element and the `depth_factor_idx` element follow in the bitstream. If the `b_object_use_screen_ref` flag is false, `screen_factor` = 0.

5.6.1.1.19 `screen_factor_bits`

The `screen_factor_bits` unsigned integer indicates the value of `screen_factor`.

The value of `screen_factor` shall be determined by the following equation:

$$\text{screen_factor} = (\text{screen_factor_bits} + 1) / 8$$

5.6.1.1.20 `depth_factor_idx`

The `depth_factor_idx` index indicates the value of `depth_factor`.

The value of the `depth_factor` shall be determined as specified in table 16.

Table 16: The value of `depth_factor` indicated by the `depth_factor_idx` element

<code>depth_factor_idx</code>	<code>depth_factor</code>
0	0,25
1	0,5
2	1
3	2

5.6.1.2 Size

5.6.1.2.1 `object_size_idx`

The `object_size_idx` index indicates the values of `object_width`, `object_depth` and `object_height`.

Table 17 lists the values of `object_width`, `object_depth`, and `object_height`.

Table 17: Values of `object_width`, `object_depth` and `object_height`

<code>object_size_idx</code>	<code>object_width</code>	<code>object_depth</code>	<code>object_height</code>
0	0	0	0
1	$\frac{\text{object_size_bits}}{31}$	$\frac{\text{object_size_bits}}{31}$	$\frac{\text{object_size_bits}}{31}$
2	$\frac{\text{object_width_bits}}{31}$	$\frac{\text{object_depth_bits}}{31}$	$\frac{\text{object_height_bits}}{31}$
3	Reserved		

5.6.1.2.2 `object_size_bits`

The `object_size_bits` codeword indicates the value of `object_width`, `object_depth` and `object_height`.

The values shall be determined by the following equation:

$$\text{object_width} = \text{object_depth} = \text{object_height} = \frac{\text{object_size_bits}}{31}$$

In this equation the bits of `object_size_bits` are interpreted as an unsigned integer.

5.6.1.2.3 object_width_bits

The `object_width_bits` codeword indicates the value of *object_width*.

The value of *object_width* shall be determined by the following equation:

$$\text{object_width} = \text{object_width_bits} /_{31}$$

In this equation, the bits of `object_width_bits` are interpreted as an unsigned integer.

5.6.1.2.4 object_depth_bits

The `object_depth_bits` codeword indicates the value of *object_depth*.

The value of *object_depth* shall be determined by the following equation:

$$\text{object_depth} = \text{object_depth_bits} /_{31}$$

In this equation, the bits of `object_depth_bits` are interpreted as an unsigned integer.

5.6.1.2.5 object_height_bits

The `object_height_bits` codeword indicates the value of *object_height*.

The value of *object_height* shall be determined by the following equation:

$$\text{object_height} = \text{object_height_bits} /_{31}$$

In this equation, the bits of `object_height_bits` are interpreted as an unsigned integer.

5.6.1.3 Priority

5.6.1.3.1 b_default_object_priority

The `b_default_object_priority` flag indicates whether the value of *object_priority* shall default to 1,0 (when true) or is indicated by the `object_priority_bits` element (when false).

The value of *object_priority* is in [0; 1], where *object_priority* in [0; 1[is signalled as specified in clause 5.6.1.3.2.

5.6.1.3.2 object_priority_bits

The `object_priority_bits` codeword indicates the value of the *object_priority*.

The value of *object_priority* shall be determined by the following equation:

$$\text{object_priority} = \text{object_priority_bits} /_{32}$$

In this equation, the bits of `object_priority_bits` are interpreted as an unsigned integer. The value of *object_priority* is in [0; 1], where *object_priority* = 1 is signalled as specified in clause 5.6.1.3.1.

5.6.1.4 Gain

5.6.1.4.1 object_gain_idx

The `object_gain_idx` index indicates the value of *object_gain*.

object_gain shall be derived from `object_gain_idx` as specified in table 18.

Table 18: Value of object_gain

object_gain_idx	object_gain
0	0 dB
1	$-\infty$ dB
2	indicated by the <code>object_gain_bits</code> element
3	<code>object_gain</code> of the previous object in this metadata update block, or a default of 0 dB if the current object is the first object

5.6.1.4.2 object_gain_bits

The `object_gain_bits` unsigned integer indicates the value of `object_gain`.

The value of `object_gain` shall be determined as specified in table 19.

Table 19: Determination of object_gain indicated by object_gain_bits

object_gain_bits	object_gain [dB]
0 - 14	15 – <code>object_gain_bits</code> ; <code>object_gain</code> is in [1; 15]
15 - 63	14 – <code>object_gain_bits</code> ; <code>object_gain</code> is in [-49; -1]

NOTE: The value `object_gain` = 0 dB can't be signalled by `object_gain_bits`, but can be signalled by `object_gain_idx` = 0.

5.6.1.5 Channel lock

5.6.1.5.1 b_object_snap

The `b_object_snap` flag indicates the channel lock property.

5.6.1.6 Zone constraints

5.6.1.6.1 zone_constraints_idx

The `zone_constraints_idx` index indicates zone constraints for the horizontal zones.

Horizontal zones are marked to be included or excluded as listed in table 20.

NOTE: Constraints for the Top-Bottom zone are documented in clause 5.6.1.6.2.

Table 20: Zone constraints indicated by the zone_constraints_idx element

zone_constraints_idx	Zone constraints
0	No constraints
1	Back zone excluded (all other horizontal zones included)
2	Side zone excluded (all other horizontal zones included)
3	Centre-and-back zone included (all other horizontal zones excluded)
4	Only screen zone included (all other horizontal zones excluded)
5	Only surround zone included (all other horizontal zones excluded)
67	Reserved

5.6.1.6.2 b_enable_elevation

The `b_enable_elevation` flag indicates the zone constraints for the Top-Bottom zone.

Semantics for the `b_enable_elevation` element are listed in table 21.

Table 21: Zone constraints indicated by `b_enable_elevation`

<code>b_enable_elevation</code>	Zone constraints
true	Top-Bottom zone included
false	Top-Bottom zone excluded

5.6.2 Timing metadata

5.6.2.1 `sample_offset_code`

The `sample_offset_code` index indicates the value of `sample_offset`.

Table 22 lists the value of `sample_offset` indicated by the `sample_offset_code` element.

Table 22: Signalling of `sample_offset`

<code>sample_offset_code</code>	<code>sample_offset</code>
0	0
1	indicated by the following <code>sample_offset_idx</code> element
2	indicated by the following <code>sample_offset_bits</code> element
3	Reserved

5.6.2.2 `sample_offset_idx`

The `sample_offset_idx` index indicates the value of `sample_offset`.

Table 23 lists the value of `sample_offset` indicated by the `sample_offset_idx` element.

Table 23: Value of `sample_offset`

<code>sample_offset_idx</code>	<code>sample_offset</code> (in samples)
0	8
1	16
2	18
3	24

5.6.2.3 `sample_offset_bits`

The `sample_offset_bits` unsigned integer determines the value of `sample_offset`.

`sample_offset` is in a range [0; 31].

5.6.2.4 `num_obj_info_blocks_bits`

The `num_obj_info_blocks_bits` codeword indicates the value of `num_obj_info_blocks`.

The `num_obj_info_blocks` value is determined by the following equation:

$$\text{num_obj_info_blocks} = \text{num_obj_info_blocks_bits} + 1$$

In this equation, the bits of `num_obj_info_blocks_bits` are interpreted as an unsigned integer.

5.6.2.5 `block_offset_factor_bits`

The `block_offset_factor_bits` unsigned integer indicates the `block_offset_factor` value.

5.6.2.6 ramp_duration_code

The `ramp_duration_code` index indicates the value of `ramp_duration`.

Table 24 lists the value of `ramp_duration` indicated by the `ramp_duration_code` element:

Table 24: Value of ramp_duration

<code>ramp_duration_code</code>	<code>ramp_duration</code>
0	0
1	512
2	1 536
3	Indicated by the <code>b_use_ramp_duration_idx</code> element

5.6.2.7 b_use_ramp_duration_idx

The `b_use_ramp_duration_idx` flag indicates whether the value of `ramp_duration` is indicated by the `ramp_duration_idx` element (when true) or by the `ramp_duration_bits` element (when false).

5.6.2.8 ramp_duration_idx

The `ramp_duration_idx` index indicates the value of `ramp_duration`.

Table 25 lists the value of `ramp_duration` indicated by the corresponding table index.

Table 25: Value of ramp_duration

<code>ramp_duration_idx</code>	<code>ramp_duration</code> (in samples)
0	32
1	64
2	128
3	256
4	320
5	480
6	1 000
7	1 001
8	1 024
9	1 600
10	1 601
11	1 602
12	1 920
13	2 000
14	2 002
15	2 048

5.6.2.9 ramp_duration_bits

The `ramp_duration_bits` unsigned integer determines the value of `ramp_duration`.

`ramp_duration` is in the range of [0; 2 047].

5.6.3 Void

5.6.4 Additional metadata

5.6.4.1 reserved_data_size_bits

The `reserved_data_size_bits` codeword indicates the value of `reserved_data_size`.

The *reserved_data_size* indicates the length of the *reserved_data* element plus the padding element in bytes and can be calculated by the following equation:

$$\text{reserved_data_size} = \text{reserved_data_size_bits} + 1$$

In this equation, the bits of the *reserved_data_size_bits* element are interpreted as an unsigned integer.

5.6.4.2 oa_element_id_idx

The *oa_element_id_idx* index indicates the type of the following *oa_element* element.

Table 26 lists the type of the *oa_element* element, indicated by the corresponding table index.

Table 26: The type of the oa_element indicated by oa_element_id_idx

oa_element_id_idx	Type of the oa_element element
0	reserved
1	object_element
2	trim_element
3	reserved
4	reserved
5	extended_object_element
6-15	reserved

5.6.4.3 oa_element_size_bits

The *oa_element_size_bits* codeword indicates the value of *oa_element_size*.

The *oa_element_size* indicates the total length in bytes of the following subsequent elements:

- *alternate_object_data_id_idx*
- *b_discard_unknown_element*
- *oa_element*
- padding

The value of *oa_element_size* is determined by the following equation:

$$\text{oa_element_size} = \text{oa_element_size_bits} + 1$$

In this equation, the bits of the *oa_element_size_bits* element are interpreted as an unsigned integer.

5.6.4.4 alternate_object_data_id_idx

The *alternate_object_data_id_idx* index indicates the type of the alternative data for the corresponding *oa_element*.

The type of the alternative data for the corresponding *oa_element* element depends on the type of the *oa_element* element (indicated by the *oa_element_id_idx* element). For *oa_element_id_idx* = 1, table 27 lists the type of the alternative data for the *object_element* element.

Table 27: The type of the alternative data for the object_element element indicated by alternate_object_data_id_idx

alternate_object_data_id_idx	Type of the alternative data for the object_element element
0	Default
1-15	Reserved
NOTE: The type of the alternative data for the <i>object_element</i> element currently supports one default value only, all other values are reserved for future use cases.	

5.6.4.5 `b_discard_unknown_element`

The `b_discard_unknown_element` flag indicates whether the intention is to discard the corresponding `oa_element` during a transcoding process, if the value of the `oa_element_id_idx` element is unknown.

5.6.4.6 `b_object_not_active`

The `b_object_not_active` flag indicates whether the object's audio essence is silent.

5.6.4.7 `object_basic_info_status_idx`

The `object_basic_info_status_idx` index indicates how the values of the elements contained in the `object_basic_info` block are determined.

Table 28 lists how the values of the elements contained in the `object_basic_info` block shall be determined.

Table 28: Values of the elements contained in the `object_basic_info` block

<code>object_basic_info_status_idx</code>	Action	Element values
0	Default	<ul style="list-style-type: none"> • <code>object_priority=0</code> • <code>object_gain=-∞</code> dB
1	Full update	All values are signalled in the <code>object_basic_info</code> block
2	Full reuse	No values signalled, all values are equal to the corresponding values of the previous metadata update
3	Mixed update/reuse	Some values are signalled in the <code>object_basic_info</code> block and some values are equal to the corresponding values of the previous metadata update (see clause 5.6.4.12)

5.6.4.8 `b_object_in_bed_or_ISF`

The `b_object_in_bed_or_ISF` helper flag shall be set if the corresponding object is contained in a bed or is an ISF object.

Whether an object is contained in a bed or is and ISF object can be determined from the order of objects and from the OAMD content description, specified in clause 5.6.0.

The objects are ordered in the bitstream as follows:

- 1) Objects contained in a bed
- 2) ISF objects
- 3) Dynamic objects (not contained in a bed nor ISF related)

The OAMD content description specifies the number of bed instances as `num_bed_instances`, the number of ISF objects `intermediate_spatial_format_idx`, and the number of dynamic objects in `num_dynamic_objects`. Objects in the first two classes shall be marked with `b_object_in_bed_instance_or_ISF = true`.

5.6.4.9 `object_render_info_status_idx`

The `object_render_info_status_idx` index indicates how the values of the `object_render_info` elements are determined.

Table 29 lists how the values of the elements contained in the `object_render_info` block shall be determined.

Table 29: Values of `object_render_info` elements

<code>object_render_info_status_idx</code>	Action	Values <code>object_render_info</code> elements
0	Default	<ul style="list-style-type: none"> • <code>pos3D_X=0,5</code> • <code>pos3D_Y=0,5</code> • <code>pos3D_Z=0</code> • <code>width=0</code> • <code>depth=0</code> • <code>height=0</code> • <code>zone_constraints_idx=0</code> • <code>b_enable_elevation=true</code> • <code>b_use_screen_ref=false</code> • <code>b_snap=false</code>
1	Full update	All values are signalled in the <code>object_render_info</code> block
2	Full reuse	No values signalled, all values are equal to the corresponding values of the previous metadata update
3	Mixed update/reuse	As indicated by clause 5.6.4.13: some values are signalled in the <code>object_render_info</code> block and some values are equal to the corresponding values of the previous metadata update

5.6.4.10 `b_additional_table_data_exists`

The `b_additional_table_data_exists` flag indicates whether the `additional_table_data_size_bits` element and the `additional_table_data` block follow in the bitstream.

5.6.4.11 `additional_table_data_size_bits`

The `additional_table_data_size_bits` codeword indicates the value of `additional_table_data_size`.

The value of `additional_table_data_size` is determined by the following equation:

$$\text{additional_table_data_size} = \text{additional_table_data_size_bits} + 1$$

In this equation, the bits of the `additional_table_data_size_bits` element are interpreted as an unsigned integer. The value of `additional_table_data_size` indicates the total length of the following `additional_table_data` block and the padding element in bytes.

5.6.4.12 `obj_basic_info[]`

The `obj_basic_info[]` array indicates whether the `object_gain_idx` and `b_default_object_priority` elements are present in the bitstream.

Each element of the `obj_basic_info[]` array is a flag that indicates that a corresponding element is present in the bitstream. Table 30 lists the correspondence between bitstream element and elements of the `obj_basic_info[]` array.

Table 30: Bitstream elements indicated by the `obj_basic_info[]` array

<code>obj_basic_info[]</code> array index	Corresponding bitstream element
1	<code>object_gain_idx</code>
0	<code>b_default_object_priority</code>

5.6.4.13 `obj_render_info[]`

The `obj_render_info[]` array indicates the bitstream elements contained in the `object_render_info` block.

Each element of the `obj_render_info[]` array is a flag that indicates whether corresponding elements are present in the bitstream. Table 31 lists the correspondence between bitstream elements and elements of the `obj_basic_info` array.

Table 31: Bitstream elements indicated by the obj_render_info[] array elements

obj_render_info[] array index	Corresponding bitstream elements
3	b_differential_position_specified, pos3D_X_bits, pos3D_Y_bits, pos3D_Z_sign_bits, pos3D_Z_bits, diff_pos3D_X_bits, diff_pos3D_Y_bits, diff_pos3D_Z_bits, b_object_distance_specified, b_object_at_inifity, and distance_factor_idx
2	zone_constraints_idx and b_enable_elevation
1	object_size_idx, object_size_bits, object_width_bits, object_depth_bits, and object_height_bits
0	b_object_use_screen_ref, screen_factor_bits, and depth_factor_idx

5.6.4.14 padding

The padding element is a sequence of zero bits. The number of padding bits corresponds to the size value of the block.

5.6.5 Trim

5.6.5.1 warp_mode

The warp_mode element is a codeword that indicates an object position adjustment before rendering as specified in table 32.

Table 32: Object position adjustment indicated by warp_mode

warp_mode	Object position adjustment
0b00	No object position adjustment.
0b01	The <i>object_position_Y</i> value shall be multiplied by a factor of 2.
0b1X	Reserved.

5.6.5.2 global_trim_mode

The global_trim_mode element is a codeword that indicates the trim mode as specified in table 33. The global trim mode is applicable to all trim configurations.

Table 33: Global trim mode indicated by global_trim_mode

global_trim_mode	Global trim mode	Balance control
0	<i>default_trim</i>	Disabled
1	<i>disable_trim</i>	Disabled
2	<i>custom_trim</i> (see note)	Indicated by: <ul style="list-style-type: none"> • fb_balance_hb_direction • fb_balance_hb_amount • fb_balance_surr_direction • fb_balance_surr_amount
3	reserved	reserved
NOTE: The global trim mode may be overwritten by the per-trim-configuration elements b_default_trim and/or b_disable_trim. b_default_trim is described in clause 5.6.5.3 and b_disable_trim is described in clause 5.6.5.4		

5.6.5.3 b_default_trim

The b_default_trim flag indicates whether the trim_mode is set to *default_trim* for all objects in the corresponding trim configuration.

NOTE: If b_disable_trim_per_obj is true, the transmitted information to disable trim for individual objects may override the setting for individual objects in the trim configuration.

5.6.5.4 b_disable_trim

The `b_disable_trim` flag indicates whether the `trim_mode` is set to `disable_trim` for all objects in the corresponding trim configuration, or, if transmitted per object (by `b_disable_trim_per_obj`) for the corresponding object.

5.6.5.5 trim_balance_presence[]

If true, the Boolean elements of this array indicates that corresponding bitstream elements for trim and/or balance processing are transmitted.

Table 34 lists the correspondence between elements of `trim_balance_presence[]` and bitstream elements of the `trim_element`.

Table 34: trim_balance_presence[] elements

trim_balance_presence element index	Transmitted bitstream elements
4	trim_centre
3	trim_surround
2	trim_height
1	fb_balance_ohfl_direction, fb_balance_ohfl_amount
0	fb_balance_surr_direction, fb_balance_surr_amount

5.6.5.6 trim_centre

The `trim_centre` codeword indicates the `trim_centre` value as specified in table 35.

Table 35: trim_centre

trim_centre	trim_centre in dB
0	+6
1	+3
2	+1,5
3	+0,75
4	-0,75
5	-1,5
6	-3
7	-4,5
8	-6
9	-7,5
10	-9
11	-10,5
12	-12
13	-13,5
14	-16
15	-36

5.6.5.7 trim_surround

The `trim_surround` codeword indicates the `trim_surround` value as specified in table 36.

Table 36: trim_surround

trim_surround	trim_surround in dB
0 - 3	reserved
4	-0,75
5	-1,5
6	-3
7	-4,5
8	-6
9	-7,5
10	-9
11	-10,5
12	-12
13	-13,5
14	-16
15	-36

5.6.5.8 trim_height

The `trim_height` codeword indicates the *trim_height* value as specified in table 37.

Table 37: trim_height

trim_height	trim_height in dB
0 - 3	reserved
4	-0,75
5	-1,5
6	-3
7	-4,5
8	-6
9	-7,5
10	-9
11	-10,5
12	-12
13	-13,5
14	-16
15	-36

5.6.5.9 bal3D_Y_sign_tb_code

The `bal3D_Y_sign_tb_code` codeword indicates the direction of balance along the Y-axis to be applied in both the top and bottom planes as specified in table 38.

Table 38: bal3D_Y_sign_tb indicated by bal3D_Y_sign_tb_code

bal3D_Y_sign_tb_code	bal3D_Y_sign_tb	Meaning
0	-1	The balance is towards the front of the room.
1	1	The balance is towards the back of the room.

5.6.5.10 bal3D_Y_amount_tb

The `bal3D_Y_amount_tb` codeword indicates the amount of balance along the Y-axis to be applied in both the top and bottom planes, determined as:

$$\text{bal3D_Y_tb} = \text{bal3D_Y_sign_tb} \times \frac{\text{bal3D_Y_amount_tb} + 1}{16}$$

NOTE: *bal3D_Y_sign_tb* is specified in clause 5.6.5.9.

5.6.5.11 bal3D_Y_sign_lis_code

The `bal3D_Y_sign_lis_code` codeword indicates the direction of balance along the Y-axis to be applied in the listener plane ($z = 0$) as specified in table 39.

Table 39: bal3D_Y_sign_lis indicated by bal3D_Y_sign_lis_code

bal3D_Y_sign_lis_code	bal3D_Y_sign_lis	Meaning
0	-1	The balance is towards the front of the room.
1	1	The balance is towards the back of the room.

5.6.5.12 bal3D_Y_amount_lis

The `bal3D_Y_amount_lis` codeword indicates the amount of balance along the Y-axis to be applied in the listener plane ($z = 0$), determined as:

$$\text{bal3D_Y_lis} = \text{bal3D_Y_sign_lis} \times \frac{\text{bal3D_Y_amount_lis} + 1}{16}$$

NOTE: *bal3D_Y_sign_lis* is specified in clause 5.6.5.11.

5.6.6 extended_object_element

5.6.6.1 b_obj_div_block

The `b_obj_div_block` flag indicates whether an `obj_div_block` element is present in the bitstream per metadata update block.

5.6.6.2 b_ext_prec_pos_block

The `b_ext_prec_pos_block` flag indicates whether an `ext_prec_pos_block` element is present in the bitstream per metadata update block.

5.6.6.3 obj_div_block

5.6.6.3.1 b_object_divergence

The `b_object_divergence` flag indicates whether object divergence metadata is present in the bitstream.

5.6.6.3.2 object_div_mode

The `object_div_mode` element indicates how the value of *object_divergence* is transmitted, as shown in table 40.

Table 40: object_div_mode

object_div_mode	Description
0	indicated by <code>object_div_table</code> .
1	reuse <i>object_divergence</i> as transmitted in the previous <code>obj_info_block</code> .
2	indicated by <code>object_div_code</code> .
3	Reserved.

5.6.6.3.3 object_div_table

The `object_div_table` element indicates the value of *object_divergence* as shown in table 41.

Table 41: object_div_table

object_div_table	object_divergence
0	0,500755
1	0,608529
2	0,704833
3	1,0

5.6.6.3.4 object_div_code

The `object_div_code` indicates the value of `object_divergence` as shown in table 42.

Table 42: object_div_code

object_div_code	object_divergence	object_div_code	object_divergence
0	reserved	32	0,704833
1	0	33	0,733123
2	0,004026	34	0,75932
3	0,00716	35	0,783416
4	0,012731	36	0,805451
5	0,020173	37	0,825506
6	0,028485	38	0,843686
7	0,04021	39	0,860112
8	0,050582	40	0,874914
9	0,063601	41	0,888222
10	0,079914	42	0,900168
11	0,100299	43	0,910875
12	0,125666	44	0,920461
13	0,140532	45	0,929035
14	0,157027	46	0,936698
15	0,175282	47	0,943544
16	0,195417	48	0,949656
17	0,217536	49	0,955112
18	0,241718	50	0,95998
19	0,268002	51	0,964322
20	0,296377	52	0,968195
21	0,326766	53	0,974729
22	0,359017	54	0,979923
23	0,392895	55	0,98405
24	0,428081	56	0,98733
25	0,464184	57	0,989935
26	0,500755	58	0,992874
27	0,537316	59	0,994955
28	0,573389	60	0,996817
29	0,608529	61	0,99821
30	0,642346	62	0,998993
31	0,674524	63	1

5.6.6.4 ext_prec_pos_block

5.6.6.4.1 b_ext_prec_pos

The `b_ext_prec_pos` flag indicates whether extended precision position metadata is present in the bitstream.

5.6.6.4.2 ext_prec_pos_presence[]

If true, the Boolean elements of this array indicates that corresponding extended precision metadata elements are transmitted. If any extended precision metadata element is not transmitted its value shall be 0.

Table 43 lists the correspondence between elements of `ext_prec_pos_presence []` and bitstream elements of the `ext_prec_pos_block` element.

Table 43: extp_pos_presence elements

<code>ext_prec_pos_presence</code> index	Transmitted bitstream elements
2	<code>ext_prec_pos3D_X</code>
1	<code>ext_prec_pos3D_Y</code>
0	<code>ext_prec_pos3D_Z</code>

5.6.6.4.3 `ext_prec_pos3D_X`

The `ext_prec_pos3D_X` indicates the extended precision position value to be used for calculation of `pos3D_X` as specified in clause 5.6.1.1.8 and clause 5.6.1.1.12. The extended precision value is shown in table 44.

Table 44: ext_prec_pos3D_X

<code>ext_prec_pos3D_X</code>	Semantics
0	1
1	2
2	-1
3	-2

5.6.6.4.4 `ext_prec_pos3D_Y`

The `ext_prec_pos3D_Y` indicates the extended precision value to be used for calculation of `pos3D_Y` as specified in clause 5.6.1.1.9 and clause 5.6.1.1.13. The extended precision value is shown in table 45.

Table 45: ext_prec_pos3D_Y

<code>ext_prec_pos3D_Y</code>	Semantics
0	1
1	2
2	-1
3	-2

5.6.6.4.5 `ext_prec_pos3D_Z`

The `ext_prec_pos3D_Z` indicates the extended precision value to be used for calculation of `pos3D_Z` as specified in clause 5.6.1.1.11 and clause 5.6.1.1.14. The extended precision value is shown in table 46.

Table 46: ext_prec_pos3D_Z

<code>ext_prec_pos3D_Z</code>	Semantics
0	1
1	2
2	-1
3	-2

6 Joint object coding

6.1 Introduction

The JOC tool is a post-processor to the E-AC-3 decoder. It enables decoding of up to 16 OBA essences from a channel-based E-AC-3 bitstream.

The JOC decoder performs a quadrature mirror filter bank domain matrix operation to reconstruct the output objects. The coefficients of the reconstruction matrix are controlled by the JOC side information in the bitstream.

NOTE: Clause 7.1 specifies the quadrature mirror filter bank domain.

6.2 Bitstream syntax

6.2.1 joc

Syntax	No of bits
<pre>joc() { joc_header(); joc_info(); joc_data(); if (joc_ext_config > 0) { joc_ext_data(); } padding_bits; 0...7 }</pre>	

6.2.2 joc_header

Syntax	No of bits
<pre>joc_header() { joc_dmx_config_idx; 3 joc_num_objects_bits; 6 joc_ext_config_idx; 3 }</pre>	

6.2.3 joc_info

Syntax	No of bits
<pre>joc_info() { joc_clipgain_x_bits; 3 joc_clipgain_y_bits; 5 joc_seq_count_bits; 10 for (obj = 0; obj < joc_num_objects; obj++) { b_joc_obj_present[obj]; 1 if (b_joc_obj_present[obj]) { joc_num_bands_idx[obj]; 3 b_joc_sparse[obj]; 1 joc_num_quant_idx[obj]; 1 joc_data_point_info(obj); } } }</pre>	

6.2.4 joc_data_point_info

Syntax	No of bits
<pre>joc_data_point_info(obj) { joc_slope_idx[obj]; 1 joc_num_dpoints_bits[obj]; 1 if (joc_slope_idx[obj] == 1) { for (dp = 0; dp < joc_num_dpoints[obj]; dp++) { joc_offset_ts_bits[obj,dp]; 5 } } }</pre>	

6.2.5 joc_data

Syntax	No of bits
<pre>joc_data() { for (obj = 0; obj < joc_num_objects; obj++) { if (b_joc_obj_present[obj]) { for (dp = 0; dp < joc_num_dpoints[obj]; dp++) { if (b_joc_sparse[obj] == 1) { joc_channel_idx[0]; 3 joc_huff_code = get_joc_huff_code(joc_num_channels, IDX); for (pb = 1; pb < joc_num_bands; pb++) { joc_hcw; VAR joc_channel_idx[pb] = huff_decode(joc_huff_code, joc_hcw); } joc_huff_code = get_joc_huff_code(joc_num_quant_idx[obj], VEC); for (pb = 0; pb < joc_num_bands; pb++) { joc_hcw; VAR joc_vec[pb] = huff_decode(joc_huff_code, joc_hcw); } } else { joc_huff_code = get_joc_huff_code(joc_num_quant_idx[obj], MTX); for (ch = 0; ch < joc_num_channels; ch++) { for (pb = 0; pb < joc_num_bands; pb++) { joc_hcw; VAR joc_mtx[pb] = huff_decode(joc_huff_code, joc_hcw); } } } } } } }</pre>	

6.3 Bitstream description

6.3.1 joc

6.3.1.1 joc overview

The `joc` block is the top-level element that contains all bitstream elements of the JOC side information.

6.3.2 `joc_header`

6.3.2.1 `joc_header` overview

The `joc_header` block contains bitstream elements that indicate the JOC downmix configuration, the number of processed audio objects and the type of extensional JOC configuration data (if present in the bitstream).

6.3.2.2 `joc_dmx_config_idx`

The `joc_dmx_config_idx` index indicates the JOC downmix configuration.

Table 47 specifies the JOC downmix configuration indicated by `joc_dmx_config_idx`.

Table 47: JOC downmix channel configuration

<code>joc_dmx_config_idx</code>	Downmix configuration	Downmix channel
0	5.X	L, R, C, (LFE), Ls, Rs
1	7.X	L, R, C, (LFE), Ls, Rs, Lb, Rb
2	5.X + 2	L, R, C, (LFE), Ls, Rs, Tfl, Tfr
3	5.X with 90 degree phase shift	L, R, C, (LFE), Ls, Rs
4	5.X + 2 with 90 degree phase shift	L, R, C, (LFE), Ls, Rs, Tfl, Tfr
5...7	reserved	

NOTE: If the LFE channel is present, this audio channel is not processed by the JOC decoder, but bypassed only.

6.3.2.3 `joc_num_channels`

The `joc_num_channels` helper variable indicates the number of channels in the JOC downmix.

The value of `joc_num_channels` depends on the `joc_dmx_config_idx` index as listed in table 48.

Table 48: Number of downmix channels

<code>joc_dmx_config_idx</code>	<code>joc_num_channels</code>
0	5
1	7
2	7
3	5
4	7
5...7	reserved

6.3.2.4 `joc_num_objects_bits`

The `joc_num_objects_bits` unsigned integer indicates the value of `joc_num_objects`.

The value of `joc_num_objects` is determined by the following equation:

$$\text{joc_num_objects} = \text{joc_num_objects_bits} + 1$$

The maximum value for `joc_num_objects_bits` shall be 15.

6.3.2.5 `joc_ext_config_idx`

The `joc_ext_config_idx` index indicates the type of extensional configuration data that is present in the bitstream.

Table 49 specifies the extensional configuration data indicated by `joc_ext_config_idx`.

Table 49: JOC extensional configuration data

<code>joc_ext_config_idx</code>	Extensional configuration data type
0	no extensional configuration data present
1 ... 7	reserved

NOTE: Currently all extensional configuration data types are reserved for future use.

6.3.3 `joc_info`

6.3.3.1 `joc_info` overview

The `joc_info` block contains several bitstream elements per object that indicate the presence, quantization, frequency- and time resolution of the coded JOC parameters for the corresponding object.

6.3.3.2 `joc_clipgain_x_bits`, `joc_clipgain_y_bits`

The `joc_clipgain_x_bits` and `joc_clipgain_y_bits` unsigned integers indicate the value of `joc_clipgain`.

The value of `joc_clipgain` is determined by the following equation:

$$\text{joc_clipgain} = \left(1 + \frac{\text{joc_clipgain_y_bits}}{32} \times 2^{(\text{joc_clipgain_x_bits}-4)} \right)$$

The value of `joc_clipgain` is in [1; 8,75].

6.3.3.3 `joc_seq_count_bits`

The `joc_seq_count_bits` unsigned integer determines the value `joc_seq_count` that is the state of a frame sequence counter.

The frame sequence counter is used for splice detection in the decoder. It is incremented by one every consecutive frame (up to 1 023). When the maximum value is reached, the counter restarts with the value 1 in the following frame. The value 0 indicates the first frame in the bitstream or the first frame after a splice.

6.3.3.4 `b_joc_object_present`

The `b_joc_obj_present` flag indicates whether JOC side information is present in the bitstream for the corresponding audio object.

6.3.3.5 `joc_num_bands_idx`

The `joc_num_bands_idx` index indicates the value of `joc_num_bands`.

Table 50 specifies the value of `joc_num_bands` indicated by `joc_num_bands_idx`.

Table 50: Number of frequency bands for the JOC side information

<code>joc_num_bands_idx</code>	<code>joc_num_bands</code>
0	1
1	3
2	5
3	7
4	9
5	12
6	15
7	23

6.3.3.6 b_joc_sparse

The `b_joc_sparse` flag indicates whether the JOC side information is coded in sparse mode.

6.3.3.7 joc_num_quant_idx

The `joc_num_quant_idx` index indicates the value of `joc_num_quant`.

The value of `joc_num_quant` is the number of quantization steps, used for the coding of JOC side information parameters.

Table 51 specifies the value of `joc_num_quant` indicated by `joc_num_quant_idx`.

Table 51: Number of quantization steps for the JOC side information

<code>joc_num_quant_idx</code>	<code>joc_num_quant</code>
0	96
1	192

6.3.4 joc_data_point_info

6.3.4.1 joc_data_point_info overview

The `joc_data_point_info` block contains bitstream elements that indicate the temporal extension of the JOC side information. The side information comprises the number of transmitted data points and the temporal interpolation processing.

6.3.4.2 joc_slope_idx

The `joc_slope_idx` index indicates an interpolation type.

The description of the interpolation type indicated by `joc_slope_idx` is listed in table 52.

Table 52: Description of the interpolation type signalled by `joc_slope_idx`

<code>joc_slope_select</code>	Interpolation type description
0	smooth (linear interpolation)
1	steep (transition, no interpolation)

NOTE: Clause 6.6.5 specifies smooth and steep interpolation processing.

6.3.4.3 joc_num_dpoints_bits

The `joc_num_dpoints_bits` unsigned integer indicates the number of JOC data points `joc_num_dpoints`.

The value of `joc_num_dpoints` is determined by the following equation:

$$\text{joc_num_dpoints} = \text{joc_num_dpoints_bits} + 1$$

6.3.4.4 joc_offset_ts_bits

The `joc_offset_ts_bits` unsigned integer indicates the quadrature mirror filter bank timeslot offset value `joc_offset_ts`.

The offset value `joc_offset_ts` for the corresponding data point is determined by the following equation:

$$\text{joc_offset_ts} = \text{joc_offset_ts_bits} + 1$$

6.3.5 `joc_data`

6.3.5.1 `joc_data` overview

The `joc_data` block contains bitstream elements that indicate the value of `joc_idx`, `joc_vec` or `joc_mtx`.

6.3.5.2 `joc_channel_idx`

The `joc_channel_idx` index indicates the input channel for the corresponding parameter band.

Table 53 lists the input channel indicated by `joc_channel_idx` for the two different cases `joc_num_channels = 5` and `joc_num_channels = 7`.

Table 53: JOC input channel for `joc_num_channels = 5` or `joc_num_channels = 7`

<code>joc_channel_idx</code>	Input channel if <code>joc_num_channels = 5</code>	Input channel if <code>joc_num_channels = 7</code>
0	Left	Left
1	Right	Right
2	Centre	Centre
3	Left Surround	Left Surround
4	Right Surround	Right Surround
5	n.a.	Left Back
6	n.a.	Right Back

NOTE: The `joc_channel_idx` index is only present when `joc_sparse_idx = 1`.

6.3.5.3 `joc_hcw`

The `joc_hcw` Huffman codeword indicates the value of `joc_channel_idx`, `joc_vec` or `joc_mtx`, when decoded using the corresponding code.

6.4 Joint object coding decoder interfaces

6.4.1 Input

The `joc_num_channels` quadrature mirror filter bank matrices are input to the JOC decoder.

$\mathbf{Qin}_{\text{JOC},(1, 2, \dots, \text{joc_num_channels})}$

joc_num_channels complex valued quadrature mirror filter bank matrices corresponding to the number of input channels to be processed by the JOC decoder.

NOTE: The $\mathbf{Qin}_{\text{JOC}}$ matrices each consist of *num_qmf_timeslots* columns and *num_qmf_subbands* rows.

6.4.2 Output

The `joc_num_objects` quadrature mirror filter bank matrices are output of the JOC decoder.

$\mathbf{Qout}_{\text{JOC},(1, 2, \dots, \text{joc_num_objects})}$

joc_num_objects complex valued quadrature mirror filter bank matrices corresponding to the number of output objects to be reconstructed by the JOC decoder.

NOTE: The $\mathbf{Qout}_{\text{JOC}}$ matrices each consist of *num_qmf_timeslots* columns and *num_qmf_subbands* rows.

6.4.3 Control

Control parameters of the JOC decoder are coded in the JOC side information.

The parameters for the JOC reconstruction process are coefficients of a reconstruction matrix. To calculate these coefficients the decoder has an interface for temporal data points of coded matrix coefficients and additional parameters to control the decoding, dequantization and the interpolation process.

6.5 Parameter band mapping

For the JOC reconstruction process, the parameter bands of the JOC side information are mapped to the quadrature mirror filter bank subbands.

The parameters contained in the JOC side information are transmitted per parameter band. The number of parameter bands is indicated by *joc_num_bands*, as specified in clause 6.3.3.5.

The mapping of grouped quadrature mirror filter bank subbands to JOC parameter bands is listed in table 54. The columns specify different mappings depending on the value of *joc_num_bands* (1 to 23).

Table 54: Mapping of quadrature mirror filter bank subbands to JOC parameter bands

QMF subband	JOC parameter band mapping dependent on <i>joc_num_bands</i>							
	23	15	12	9	7	5	3	1
0	0	0	0	0	0	0	0	0
1	1	1	1	1	1	1	0	0
2	2	2	2	2	2	1	0	0
3	3	3	3	3	2	2	1	0
4	4	4	4	3	3	2	1	0
5	5	5	4	4	3	2	1	0
6	6	6	5	4	3	2	1	0
7	7	7	5	5	3	2	1	0
8	8	8	6	5	4	2	1	0
9	9	9	6	6	4	3	1	0
10	10	9	6	6	4	3	1	0
11	11	10	7	6	4	3	1	0
12 - 13	12	10	7	6	4	3	1	0
14 - 15	13	11	8	7	5	3	2	0
16 - 17	14	11	8	7	5	3	2	0
18 - 19	15	12	9	7	5	3	2	0
20 - 22	16	12	9	7	5	3	2	0
23 - 25	17	13	10	8	6	4	2	0
26 - 29	18	13	10	8	6	4	2	0
30 - 34	19	13	10	8	6	4	2	0
35 - 40	20	14	11	8	6	4	2	0
41 - 47	21	14	11	8	6	4	2	0
48 - 63	22	14	11	8	6	4	2	0

6.6 Joint object coding decoder

6.6.1 Introduction

The JOC decoder consecutively decodes, dequantizes and interpolates the JOC side information, and reconstructs the output objects using the processed side information.

The consecutive processing steps are specified as follows:

- 1) Decoding of the JOC bitstream elements as specified in clause 6.6.2
- 2) Dequantization of the JOC parameters as specified in clause 6.6.4
- 3) Interpolation of JOC parameters as specified in clause 6.6.5
- 4) Reconstruction of the output objects as specified in clause 6.6.6

6.6.2 Differential decoding of side information

For each object *obj* in [0; *joc_num_objects*-1], the JOC decoder shall decode the quantized coefficients for the reconstruction matrix *joc_mix_mtx_q* from the JOC bitstream elements.

In pseudo code notation, the decoding process for *b_joc_sparse*[*obj*] == 1 is specified as:

Pseudocode 2

```
// input: arrays joc_channel_idx[obj][dp][pb] and joc_vec[obj][dp][pb]
// output: array joc_mix_mtx_q[obj][dp][ch][pb]
if (b_joc_obj_present[obj]) {
    nquant = (joc_num_quant_idx[obj] == 0) ? 96 : 192;
    for (dp = 0; dp < joc_num_dpoints; dp++) {
        offset = (joc_num_quant_idx[obj] == 0) ? 50 : 100;
        for (pb = 0; pb < joc_num_bands; pb++) {
            if (pb == 0) {
                joc_channel_idx_mod = joc_channel_idx[obj][dp][pb];
            }
            else {
                joc_channel_idx_mod = (joc_channel_idx[obj][dp][pb-1] + joc_channel_idx[obj][dp][pb]) % joc_num_channels;
            }
            for (ch = 0; ch < joc_num_channels; ch++) {
                if (ch == joc_channel_idx_mod) {
                    if (pb == 0) {
                        joc_mix_mtx_q[obj][dp][ch][pb] = (offset + joc_vec[obj][dp][pb]) % nquant;
                    }
                    else {
                        joc_mix_mtx_q[obj][dp][ch][pb] = (joc_mix_mtx_q[obj][dp][ch][pb-1] + joc_vec[obj][dp][pb]) % nquant;
                    }
                }
            }
            else {
                joc_mix_mtx_q[obj][dp][ch][pb] = offset;
            }
        }
    }
}
}
```

In pseudo code notation, the decoding process for *b_joc_sparse*[*obj*] == 0 is specified as:

Pseudocode 3

```
// input: array joc_mtx[obj][dp][ch][pb]
// output: array joc_mix_mtx_q[obj][dp][ch][pb]
if (b_joc_obj_present[obj]) {
    nquant = (joc_num_quant_idx[obj] == 0) ? 96 : 192;
    for (dp = 0; dp < joc_num_dpoints; dp++) {
        offset = (joc_num_quant_idx[obj] == 0) ? 48 : 96;
        for (ch = 0; ch < joc_num_channels; ch++) {
            joc_mix_mtx_q[obj][dp][ch][0] = (offset + joc_mtx[obj][dp][ch][pb]) % nquant;
            for (pb = 1; pb < joc_num_bands[obj]; pb++) {
                joc_mix_mtx_q[obj][dp][ch][pb] = (joc_mix_mtx_q[obj][dp][ch][pb-1] + joc_mtx[obj][dp][ch][pb]) % nquant;
            }
        }
    }
}
}
```

6.6.3 Huffman decoding of side information

The Huffman tables define huffman codewords implicitly.

To decode quantized side information values, the JOC decoder shall decode the huffman codewords into values specified in clause A.1.

The decoding process for `huff_decode(joc_huff_code, joc_hcw)` is specified as:

Pseudocode 4

```

huff_decode(joc_huff_code, joc_hcw)
{
    node = 0;
    next_bit = 0;
    do
    {
        next_bit = get_bit(joc_hcw);
        node = joc_huff_code[node][next_bit];
    }
    while (node > 0);

    return (-node-1);
}

```

The function `get_bit()` shall read one bit out of the codeword given as argument, starting with the MSB and pointing to the next bit for the following call.

The function `joc_get_huff_code(mode, type)` shall get the huffman code table `joc_huff_code[][]` as specified in clause A.1.

6.6.4 Dequantization of side information

The JOC decoder shall calculate the dequantized coefficients of the matrix `joc_mix_mtx_dq` from the quantized coefficients of the matrix `joc_mix_mtx_q`.

In pseudo code notation the calculation is specified as:

Pseudocode 5

```

for (obj=0; obj < joc_num_objects; obj++) {
    nquant = (joc_num_quant_idx[obj] == 0) ? 96 : 192;
    for (dp=0; dp < joc_num_dpoints; dp++) {
        for (ch=0; ch < joc_num_channels; ch++) {
            for (pb=0; pb < joc_num_bands; pb++) {
                joc_mix_mtx_dq[obj][dp][ch][pb] = (joc_mix_mtx_q[obj][dp][ch][pb] - nquant / 2) *
                820 / (4096 * (1 + joc_num_quant_idx[obj]));
            }
        }
    }
}

```

NOTE: If `joc_num_quant_idx[obj] = 0` for one object `obj`, the values corresponding to this object are dequantized into the range [-9,6; 9,4]; otherwise, the range is [-9,6; 9,5].

6.6.5 Temporal interpolation of side information

The JOC decoder shall calculate an interpolated matrix `joc_mix_mtx_interp`.

In pseudo code notation, the calculation of `joc_mix_mtx_interp` is specified as:

Pseudocode 6

```

for (obj=0; obj < joc_num_objects; obj++) {
  for (ch=0; ch < joc_num_channels; ch++) {
    for (sb=0; sb < num_qmf_subbands; sb++) {
      for (ts=0; ts < num_qmf_timeslots; ts++) {
        if (joc_slope_idx[obj] == 0) {
          if (joc_num_dpoints == 1) {
            delta = joc_mix_mtx_dq[obj][0][ch][sb_to_pb(sb)] - joc_mix_mtx_prev[obj][ch][
sb];
            joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_prev[obj][ch][sb] +
              (ts+1)*delta/num_qmf_timeslots;
          }
          else {
            ts_2 = floor(num_qmf_timeslots/2);
            if (ts < ts_2) {
              delta = joc_mix_mtx_dq[obj][0][ch][sb_to_pb(sb)] - joc_mix_mtx_prev[obj][ch
] [sb];
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_prev[obj][ch][sb] +
                (ts+1)*delta/ts_2;
            }
            else {
              delta = joc_mix_mtx_dq[obj][1][ch][sb_to_pb(sb)] -
                joc_mix_mtx_dq[obj][0][ch][sb_to_pb(sb)];
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_dq[obj][0][ch][sb_to_pb(s
b)] +
                (ts-ts_2+1)*delta/(num_qmf_timeslots-
ts_2);
            }
          }
        }
        else {
          if (joc_num_dpoints == 1) {
            if (ts < joc_offset_ts[obj][0]) {
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_prev[obj][ch][sb];
            }
            else {
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_dq[obj][0][ch][sb];
            }
          }
          else {
            if (ts < joc_offset_ts[obj][0]) {
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_prev[obj][ch][sb];
            }
            else if (ts < joc_offset_ts[obj][1]) {
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_dq[obj][0][ch][sb];
            }
            else {
              joc_mix_mtx_interp[obj][ts][ch][sb] = joc_mix_mtx_dq[obj][1][ch][sb];
            }
          }
        }
      }
    }
  }
  joc_mix_mtx_prev[obj][ch][sb] =
  joc_mix_mtx_dq[obj][joc_num_dpoints-1][ch][sb_to_pb(sb)];
}
}
}

```

The function *sb_to_pb(subband)* shall return the parameter band value corresponding to the quadrature mirror filter bank subband given as an input argument as specified in clause 6.5.

EXAMPLE: If *joc_num_bands* = 15 and the input to *sb_to_pb(subband)* is the subband value 24, *sb_to_pb(24)* returns the value 13.

Before decoding the first E-AC-3 frame, all elements of the *joc_mix_mtx_prev* matrix shall be 0.

6.6.6 Reconstruction of the output objects

The JOC decoder shall calculate the output objects from the input channels utilizing the matrix *joc_mix_mtx_interp*.

Input and output are specified as follows:

Output objects

$$z_{obj}(ts, sb) \in \mathbf{Q}_{out, JOC, obj} \text{ for } obj = 0, \dots, j_{oc_num_objects} - 1$$

NOTE 1: In pseudocode $z_{obj}(ts, sb)$ is addressed as $z[obj][ts][sb]$.

Input channels

$$x_{ch}(ts, sb) \in \mathbf{Q}_{in, JOC, ch} \text{ for } ch = 0, \dots, j_{oc_num_channels} - 1$$

NOTE 2: In pseudocode $x_{ch}(ts, sb)$ is addressed as $x[ch][ts][sb]$.

In pseudo code notation, the calculation of the output objects $z_{obj}(ts, sb)$ from the input channels $x_{ch}(ts, sb)$ is specified as:

Pseudocode 7

```

for (obj=0; obj < joc_num_objects; obj++) {
  for (ch=0; ch < joc_num_channels; ch++) {
    for (ts=0; tp < num_qmf_timeslots; ts++) {
      for (sb=0; sb < num_qmf_subbands; sb++) {
        z[obj][ts][sb] += x[ch][ts][sb] * joc_mix_mtx_interp[obj][ch][ts][sb];
      }
    }
  }
}

```

7 Quadrature mirror filter bank domain processing

7.1 Introduction

To enable alias suppressed frequency-domain audio processing, a complex quadrature mirror filter bank analysis/synthesis transform pair can be employed.

The quadrature mirror filter bank analysis transforms a real-valued time-domain input signal into a number of spectral subband signals, each of which represents a decimated signal in that subband.

NOTE: When the transform is complex-valued, the output is oversampled by a factor of two compared to a regular cosine modulated quadrature mirror filter bank analysis.

The quadrature mirror filter bank synthesis is the reverse operation of the analysis. It transforms subband signals into a time-domain signal.

Typically, the analysis filter feeds into a history buffer taking the form of a $n_{timeslots} \times n_{subbands}$ matrix; processing proceeds on the history buffer which then feeds into the synthesis transform.

7.2 Complex analysis processing

The analysis filter transforms n time domain samples into n complex frequency-domain subband samples.

The analysis transform maintains a state buffer $qana_filt$ of n_{qmf_length} real-valued samples.

NOTE: In the following, it is assumed that real and imaginary parts are interleaved.

- 1) Update the input buffer $qana_filt$ by shifting out n old samples.

Pseudocode 8

```

for (j = n_qmf_length-1; j >= n; j--)
{
  qana_filt[j] = qana_filt[j-n];
}

```

- 2) Update the input buffer $qana_filt$ by shifting in n new time-domain samples.

Pseudocode 9

```
for (j = n-1; j >= 0; j--)
{
    qana_filt[j] = pcm[n-1-j];
}

```

- 3) Compute vector z by pairwise multiplying the elements of $qana_filt$ by window coefficients vector $QWIN[]$.

Pseudocode 10

```
for (j = 0; j < n_qmf_length; j++)
{
    z[j] = qana_filt[j] * QWIN[j];
}

```

- 4) Compute vector u as a summation over z

Pseudocode 11

```
for (j = 0; j < 2*n; j++)
{
    u[j] = 0;
    for (k = 0; k <= (n_qmf_length/(2*n))-1; k++)
    {
        u[j] += z[j + k*2*n];
    }
}

```

- 5) Compute n new subband samples of vector Q by the complex-valued matrix multiplication $Q = M \cdot u$, where the following equation applies: $M_{kj} = \exp\left(\frac{i \times \pi \times (k+1/2) \times (j-1/2)}{n}\right)$, $\begin{cases} 0 \leq k < n \\ 0 \leq j < 2 \times n \end{cases}$

Pseudocode 12

```
for (sb = 0; sb < n; sb++)
{
    /* note that Q[sb] is a complex datatype */
    Q[sb] = 0;
    for (j = 0; j < 2*n; j++)
    {
        Q[sb] += u[j] * exp(i*pi*(sb+0.5)*(j-0.5)/n);
    }
}

```

7.3 Complex synthesis processing

The synthesis filter transforms n complex frequency-domain subband samples $Q[]$ into n real-valued time-domain samples.

The synthesis transform maintains a state buffer $qsyn_filt$ of $2 \times n_qmf_length$ real-valued samples.

- 1) Update the state buffer $qsyn_filt$ by shifting out $2 \times n$ old samples.

Pseudocode 13

```
/* shift samples by 2*n */
for (j = 2*n_qmf_length-1; j >= 2*n; j--)
{
    qsyn_filt[j] = qsyn_filt[j-2*n];
}

```

- 2) Compute $2*n$ new real-valued samples by multiplying the complex-valued subband samples $Q[l]$ by the matrix \mathbf{N} , where the following equation applies: $N_{j,k} = \frac{1}{n} \times \exp\left(\frac{i \times \pi \times (k+1/2) \times (j-2 \times n+1/2)}{n}\right)$, $\begin{cases} 0 \leq k < n \\ 0 \leq j < 2 \times n \end{cases}$. Store the samples in the state buffer.

Pseudocode 14

```

for (j = 0; j < 2*n; j++)
{
    qsyn_filt[j] = 0;
    for (sb = 0; sb < n; sb++)
    {
        exponent = i*pi/(4*n)*(2*sb + 1)*(2*j - 2*n - 1);
        qsyn_filt[j] += real(Q[sb]/n * exp(exponent));
    }
}

```

- 3) Extract samples from *qsyn_filt* to create the *n_qmf_length*-element vector *g*.

Pseudocode 15

```

for (j = 0; j < n_qmf_length/(2*n); j++)
{
    for (sb = 0; sb < n; sb++)
    {
        g[2*n*j + sb] = qsyn_filt[4*n*j + sb];
        g[2*n*j + n + sb] = qsyn_filt[4*n*j + 3*n + sb];
    }
}

```

- 4) Compute vector *w* by element-wise multiplication of vector *g* by window *QWIN*[].

Pseudocode 16

```

for (j = 0; j < n_qmf_length; j++)
{
    w[j] = g[j] * QWIN[j];
}

```

- 5) Calculate *n* new output samples by summation of samples from vector *w*.

Pseudocode 17

```

for (ts = 0; ts < n; ts++)
{
    pcm[ts] = 0;
    for (j = 0; j < n_qmf_length/n; j++)
    {
        pcm[ts] += w[n*j + ts];
    }
}

```

7.4 Filter bank coefficients

The quadrature mirror filter bank is configured by the number *n* of QMF subband and the filter length *n_qmf_length*.

The quadrature mirror filter bank in the present document uses *n* = 64 subbands, and a filter length of *n_qmf_length* = 640 (that is, 10 complex coefficients per subband). Table *QWIN* in the file *ts_103420v010201p0.zip* contains the coefficients.

8 Enhanced AC-3 decoding

8.1 Requirements on Enhanced AC-3 decoding

To decode OBA as specified in the present document, an E-AC-3 decoder, as specified in ETSI TS 102 366 [1] shall be used to decode the channel-based downmix from the incoming bitstream. The following additional requirements apply:

- The E-AC-3 decoder shall pass the EMDF payload for JOC metadata to the decoder specified in the present document.
- The E-AC-3 decoder shall pass the EMDF payload for OAMD metadata to the decoder specified in the present document.
- The E-AC-3 decoder shall decode the independent substream and, if present, all the dependent substreams, as specified in ETSI TS 102 366 [1], clause E.2.8.2, and pass the decoded audio to the decoder specified in the present document.

8.2 Requirements on EMDF container

To be backward compatible, the payloads for OAMD and JOC side information shall be carried in the EMDF container.

If the enhanced AC-3 bitstreams contains one or more dependent substreams, the EMDF container encompassing the payloads for OAMD and JOC side information shall be carried in the last dependent substream of the bitstream.

Table 55 lists normative requirements for the EMDF payloads.

Table 55: Payload restrictions for OAMD and JOC

	OAMD	JOC
payload_id	11	14
frequency	1/frame	1/frame

Table 56 lists normative requirements for the EMDF payload configuration data, as specified in ETSI TS 102 366 [1], clause H.2.2.3.

Table 56: Payload configuration data

Payload configuration data element	Value
duratione	0
groupide	1
groupid	equal for OAMD payload and JOC payload
codecdatæ	1
discard_unknown_payload	0
create_duplicate	0
remove_duplicate	0
priority	0
proc_allowed	0

8.3 Extensions contained in the addbsi bitstream field

8.3.1 Syntax

For bitstreams conforming to the present document, the `addbsi` field in the same substream as the EMDF container encompassing the payloads for OAMD and JOC side information contains the following elements in given order:

- 1) reserved - 7 bits

- 2) `flag_ec3_extension_type_a` - 1 bit
- 3) `complexity_index_type_a` - 8 bit

NOTE: The `addbsi` field is defined in ETSI TS 102 366 [1], clauses 4.3.2 and 4.4.2.31.

8.3.2 Semantics

8.3.2.1 `flag_ec3_extension_type_a`

The element `flag_ec3_extension_type_a` is a flag that, if set to true, indicates the enhanced AC-3 extension as defined in the present document.

8.3.2.2 `complexity_index_type_a`

The element `complexity_index_type_a` is an unsigned integer that indicates the decoding complexity of the enhanced AC-3 extension defined in the present document. The value of this field shall be equal to the total number of bed objects, ISF objects and dynamic objects indicated by the parameters in the `program_assignment` section of the object audio metadata payload. The maximum value of this field shall be 16.

Annex A (normative): Tables

A.1 JOC Huffman code tables

Table A.1: JOC Huffman code `joc_huff_tree_coarse_generic`

Code table name	<code>joc_huff_code_coarse_generic</code>
Mode	0
Type	MTX

Table A.2: JOC Huffman code `joc_huff_tree_fine_generic`

Code table name	<code>joc_huff_code_fine_generic</code>
Mode	1
Type	MTX

Table A.3: JOC Huffman code `joc_huff_tree_coarse_coeff_sparse`

Code table name	<code>joc_huff_code_coarse_coeff_sparse</code>
Mode	0
Type	VEC

Table A.4: JOC Huffman code `joc_huff_tree_fine_coeff_sparse`

Code table name	<code>joc_huff_code_fine_coeff_sparse</code>
Mode	1
Type	VEC

Table A.5: JOC Huffman code `joc_huff_tree_5ch_pos_index_sparse`

Code table name	<code>joc_huff_code_5ch_pos_index_sparse</code>
Mode	5
Type	IDX

Table A.6: JOC Huffman code `joc_huff_tree_7ch_pos_index_sparse`

Code table name	<code>joc_huff_code_7ch_pos_index_sparse</code>
Mode	7
Type	IDX

A.2 Speaker Zones

Table A.7: Speaker to zone assignment

Speaker	Zone
L	Screen
R	Screen
C	Screen
Ls	Surround, Back/Side (note 2)
Rs	Surround, Back/Side (note 2)
Lb	Back
Rb	Back
Tfl	Top-Bottom
Tfr	Top-Bottom
Tbl	Top-Bottom
Tbr	Top-Bottom
Tsl	Top-Bottom
Tsr	Top-Bottom
Tfc	Top-Bottom
Tbc	Top-Bottom
Tc	Top-Bottom
Cb	Surround, Back
Lw	Side
Rw	Side
Lscr	Screen
Rscr	Screen

NOTE 1: The centre-and-back zone is a union of the back zone with the centre speaker.
NOTE 2: Depending on the representation speaker configuration: Back for 5.X(.X) or less, Side otherwise.

Annex B (informative): Conversion to ADM format

B.1 Introduction

The present annex specifies a conversion to ADM Recommendation ITU-R BS.2076 [i.1] that can be used as a post processing step to the normative decoding process, specified in the present document.

Metadata updates, specified in clause 4.4, are input to the conversion process.

NOTE: The result of the conversion of one metadata update is the combination of the individual conversions, defined in this annex.

The conversion is specified in tables providing information on how to determine the values of the ADM elements and attributes. These values can either be fixed or calculated using the metadata specified in clause 4.4 as input.

EXAMPLE 1: Table B.1 provides the information on the determination of the value for attributes of *admExampleElement* for the case that the value should be set to a fixed value and for the case that the value should be calculated using the fictive value *input_x* as input. Additionally, the table provides the information on the determination of the value for a sub-element of *admExampleElement* and for an attribute of this sub-element.

Table B.1: Determination of values in the *admExampleElement* element

Element name	Attribute name	Value
<i>admExampleElement</i>	<i>exampleAttributeOne</i>	1,0 (fixed value)
<i>admExampleElement</i>	<i>exampleAttributeTwo</i>	$3 \times \text{input_x}$ (calculation using one value as input)
<i>admExampleSubElement</i>		$12 \times \text{input_x}$ (calculation using one value as input)
<i>admExampleSubElement</i>	<i>exampleAttributeThree</i>	3,0 (fixed value)

The values of attributes and sub-elements of the following ADM elements are the output of the conversion process:

- *audioChannelFormat* specified in Recommendation ITU-R BS.2076 [i.1], clause 5.3.
- *audioBlockFormat* specified in Recommendation ITU-R BS.2076 [i.1], clause 5.4.
- *audioProgrammeReferenceScreen* specified in Recommendation ITU-R BS.2076 [i.1], clause 5.8.3.
- *audioPackFormat* specified in Recommendation ITU-R BS.2076 [i.1], clause 5.5.

The number of required ADM elements and sub-elements is as follows:

- The number of *audioChannelFormat* elements is equal to the number of objects. All metadata updates for one audio object (object) are contained in one *audioChannelFormat* element.

EXAMPLE 2: The conversion of object-audio metadata for 12 objects requires 12 *audioChannelFormat* elements.

- The number of *audioBlockFormat* elements is equal to the number of all updates for all objects. The *audioChannelFormat* element contains one or more *audioBlockFormat* elements, where each contains one update of the properties for the corresponding object.

EXAMPLE 3: If each of the 12 objects has 8 updates of its properties, the conversion requires 96 *audioBlockFormat* elements. Each of the 12 *audioChannelFormat* elements contains references to 8 *audioBlockFormat* elements.

- The number of *audioProgrammeReferenceScreen* elements is one. The specification of the reference screen size is equal for all objects.

EXAMPLE 4: One instance of the *audioProgrammeReferenceScreen* element specifies the reference screen size for all of the 8 updates of the 12 objects.

- The number of *audioPackFormat* elements is in the range [1; number of objects]. The *audioPackFormat* element groups one or more *audioChannelFormat* elements and defines a common value for *importance* for the group (see clause B.2.3). The number of required *audioPackFormat* elements depends on how many different values for *priority* are present.

EXAMPLE 5: In the first update all of the 12 objects have the same value for *priority*, so all *audioChannelFormat* elements can be grouped to one *audioPackFormat* element. On the second update 6 objects have a different value from the other 6 objects, but both values are different from the first update. This means two new *audioPackFormat* elements are required. All together three *audioPackFormat* elements are required for these two updates.

B.2 Audio object properties

B.2.1 Position

B.2.1.1 Introduction

The conversion of the metadata contained in the *position()* block depends on the value of its element *anchor*.

B.2.1.2 Room related position metadata

Conversion of the position metadata elements if *anchor* = room.

Table B.2: Determination of values in the audioChannelFormat element

Element name	Attribute name	Value
audioChannelFormat	typeDefinition	Objects
audioChannelFormat	typeLabel	0003

Table B.3: Determination of values in the audioBlockFormat element

Element name	Attribute name	Value
cartesian		1
position	coordinate="X"	$2 \times (\min(0; \max(1; x)) - 0,5)$
position	coordinate="Y"	$2 \times (0,5 - \min(0; \max(1; y)))$
position	coordinate="Z"	$\min(0; \max(1; z))$
NOTE: The values for (x; y; z) are contained in the <i>coordinates</i> element of the <i>position()</i> block.		

B.2.1.3 Screen related position metadata

Conversion of the position metadata elements if *anchor* = screen.

Table B.4: Determination of values in the audioChannelFormat element

Element name	Attribute name	Value
audioChannelFormat	typeDefinition	Objects
audioChannelFormat	typeLabel	0003

Table B.5: Determination of values in the audioBlockFormat element:

Element name	Attribute name	Value
cartesian		1
screenRef		1
position	coordinate="X"	$2 \times (\min(0; \max(1; x)) - 0,5)$
position	coordinate="Y"	$2 \times (0,5 - \min(0; \max(1; y)))$
position	coordinate="Z"	$\min(0; \max(1; z))$

NOTE: The values for (x; y; z) are contained in the *coordinates* element of the *position()* block.

Table B.6: Determination of values in the audioProgrammeReferenceScreen element

Element name	Attribute name	Value
aspectRatio		1,78
screenCentrePosition	coordinate="X"	0
screenCentrePosition	coordinate="Y"	0
screenCentrePosition	coordinate="Z"	1
screenWidth	coordinate="X"	$2 \times \text{ref_screen_ratio}$

B.2.1.4 Speaker-related position metadata

Conversion of the position metadata elements if anchor = speaker.

Table B.7: Determination of values in the audioChannelFormat element

Element name	Attribute name	Value
audioChannelFormat	typeDefinition	DirectSpeakers
audioChannelFormat	typeLabel	0001
audioChannelFormat	audioChannelFormatName	as specified in table B.9
audioChannelFormat	audioChannelFormatID	as specified in table B.9

Table B.8: Determination of values in the audioBlockFormat element

Element name	Attribute name	Value
cartesian		1
speakerLabel		as specified in table B.10
position	coordinate="X"	as specified in table B.10
position	coordinate="Y"	as specified in table B.10
position	coordinate="Z"	as specified in table B.10

Table B.9: audioChannelFormatID and audioChannelFormatName for speaker identifiers

Speaker identifier	audioChannelFormatID	audioChannelFormatName
Left (L)	AC_00011001	RoomCentricLeft
Right (R)	AC_00011002	RoomCentricRight
Center (C)	AC_00011003	RoomCentricCenter
Low-frequency Effects (LFE)	AC_00011004	RoomCentricLFE
Left Surround (Ls)	AC_00011005	RoomCentricLeftSurround
Right Surround (Rs)	AC_00011006	RoomCentricRightSurround
Left Back (Lb)	AC_00011007	RoomCentricLeftBack
Right Back (Rb)	AC_00011008	RoomCentricRightBack
Top Front Left (Tfl)	AC_00011009	RoomCentricTopFrontLeft
Top Front Right (Tfr)	AC_0001100a	RoomCentricTopFrontRight
Top Side Left (Tsl)	AC_0001100b	RoomCentricTopSideLeft
Top Side Right (Tsr)	AC_0001100c	RoomCentricTopSideRight
Top Back Left (Tbl)	AC_0001100d	RoomCentricTopBackLeft
Top Back Right (Tbr)	AC_0001100e	RoomCentricTopBackRight
Left Front Wide (Lw)	AC_0001100f	RoomCentricLeftWide
Right Front Wide (Rw)	AC_00011010	RoomCentricRightWide
Low-frequency Effects 2 (LFE2)	AC_00011011	RoomCentricLFE2

NOTE 1: The speaker identifier is contained in the *coordinates* element of the *position()* block.
NOTE 2: The listed audioChannelFormatID and audioChannelFormatName entries are custom definitions for ADM, as specified in Recommendation ITU-R BS.2076 [i.1], section 6.

Table B.10: speakerLabel and position attributes for speaker identifiers

Speaker identifier	speakerLabel	position.coordinate="X"	position.coordinate="Y"	position.coordinate="Z"
Left (L)	RC_L	-1	1	0
Right (R)	RC_R	1	1	0
Center (C)	RC_C	0	1	0
Low-frequency Effects (LFE)	RC_LFE	-1	1	-1
Left Surround (Ls)	RC_LS	-1	0	0
Right Surround (Rs)	RC_RS	1	0	0
Left Back (Lb)	RC_LB	-1	-1	0
Right Back (Rb)	RC_RB	1	-1	0
Top Front Left (Tfl)	RC_TFL	-1	1	1
Top Front Right (Tfr)	RC_TFR	1	1	1
Top Side Left (Tsl)	RC_TSL	-1	0	1
Top Side Right (Tsr)	RC_TSR	1	0	1
Top Back Left (Tbl)	RC_TBL	-1	-1	1
Top Back Right (Tbr)	RC_TBR	1	-1	1
Left Front Wide (Lw)	RC_LW	-1	0,677419	0
Right Front Wide (Rw)	RC_RW	1	0,677419	0
Low-frequency Effects 2 (LFE2)	RC_LFE2	1	1	-1

NOTE: The speaker identifier is contained in the *coordinates* element of the *position()* block.

B.2.2 Size

Table B.11: Requirements on the audioChannelFormat element

Element name	Attribute name	Value
audioChannelFormat	typeDefinition	Objects
audioChannelFormat	typeLabel	0003

Table B.12: Requirements on the audioBlockFormat element

Element name	Attribute name	Value
cartesian		1
width		width
depth		depth
height		height

B.2.3 Priority

Table B.13: Requirements on the audioPackFormat element

Element name	Attribute name	Value
audioPackFormat	importance	round(10×priority)

B.2.4 Gain

The gain value should be applied to the object audio essence.

B.2.5 Channel lock

Table B.14: Requirements on the audioChannelFormat element

Element name	Attribute name	Value
audioChannelFormat	typeDefinition	Objects
audioChannelFormat	typeLabel	0003

Table B.15: Requirements on the audioBlockFormat element

Element name	Attribute name	Value
channelLock		channel_lock
channelLock	maxDistance	0,4

B.2.6 Zone constraints

Table B.16: Requirements on the audioChannelFormat element

Element name	Attribute name	Value
audioChannelFormat	typeDefinition	Objects
audioChannelFormat	typeLabel	0003

Table B.17: Requirements on the audioBlockFormat element

Element name	Attribute name	Value
cartesian		1
zoneExclusion		1

Based on the zone constraints the `zoneExclusion` element should contain one or more zone sub-elements as specified in table B.18.

Table B.18: Mapping of zone constraints to ADM Zone elements

Zone constraints	Number of zone elements	Value(s) of zone element(s)
Back zone excluded	1	• 'ZM1'
Side zone excluded	2	• 'ZM2_Left' • 'ZM2_Right'
All horizontal zones excluded, except centre-and-back zone	4	• 'ZM3_ScreenLeft' • 'ZM3_SideLeft' • 'ZM3_ScreenRight' • 'ZM3_SideRight'
All horizontal zones excluded, except screen zone	1	• 'ZM4'
All horizontal zones excluded, except surround zone	1	• 'ZM5'
Top-Bottom zone excluded (independent from horizontal zones)	1	• 'ZU' • 'ZB'

Each zone sub-element should contain the six attributes *minX*, *maxX*, *minY*, *maxY*, *minZ* and *maxZ* as specified in table B.19.

Table B.19: Attributes of ADM zone elements

Zone	minX	maxX	minY	maxY	minZ	maxZ
ZM1	-1	1	-1	-0,41934	-0,49900	0,49900
ZM2_Left	-1	-0,75806	-0,41934	0,83871	-0,49900	0,49900
ZM2_Right	0,75806	1	-0,41934	0,83871	-0,49900	0,49900
ZM3_ScreenLeft	-1	-0,16129	0,5	1	-0,49900	0,49900
ZM3_SideLeft	-1	-0,51611	-0,70700	0,49999	-0,49900	0,49900
ZM3_ScreenRight	0,16129	1	0,5	1	-0,49900	0,49900
ZM3_SideRight	0,5611	1	-0,70700	0,49999	-0,49900	0,49900
ZM4	-1	1	-1	0,83871	-0,49900	0,49900
ZM5	-1	1	0,5	1	-0,49900	0,49900
ZU	-1	1	-1	1	0,49950	1
ZB	-1	1	-1	1	-1	-0,49950

B.3 Timing metadata

Table B.20: Requirements on the audioBlockFormat element:

Element name	Attribute name	Value
audioBlockFormat	rtime	HH:MM:SS.sssss, where seconds = $\frac{\text{frame_offset} + \text{start_time}}{f_s}$.
audioBlockFormat	duration	HH:MM:SS.sssss, where seconds = $\frac{\text{start_time}_{\text{subseq}} - \text{start_time}}{f_s}$.
NOTE 1: The values of HH, MM and SS.sssss are calculated as follows: $\text{HH} = \left\lfloor \frac{\text{seconds}}{3\,600} \right\rfloor$, $\text{MM} = \text{mod}\left(\left\lfloor \frac{\text{seconds}}{60} \right\rfloor, 60\right)$, SS.sssss = $\text{mod}(\text{seconds} \cdot 60)$.		
NOTE 2: f_s is the sampling frequency of the audio essence.		
NOTE 3: $\text{start_time}_{\text{subseq}}$ is the <i>start_time</i> value of the subsequent metadata update.		

Annex C (normative): Bit streams in the ISO based media file format

C.1 Introduction

Bit streams conforming to the present document are stored in enhanced AC-3 tracks and the MIME codecs parameter is *ec-3* as specified in ETSI TS 102 366 [1].

C.2 General

Media tracks shall conform to the enhanced AC-3 track definition in ETSI TS 102 366 [1], clause F.1 and to the enhanced AC-3 sample definition in ETSI TS 102 366 [1], clause F.2.

The syntax and semantics of the *EC3SpecificBox* that shall be used for bit streams conform to the present document is defined in clause C.3.

NOTE: Decoders conforming to ETSI TS 102 366 [1] can parse the *EC3SpecificBox* as defined in clause C.3. Syntax and semantics are identical, except added bits in the end, which decoders conform to ETSI TS 102 366 [1] will skip as reserved bits.

C.3 EC3SpecificBox

C.3.1 EC3SpecificBox

Syntax	No of bits
EC3SpecificBox() { BoxHeader.Size; 32 BoxHeader.Type; 32 data_rate; 13 num_ind_sub; 3 for (i = 0; i < num_ind_sub + 1; i++) { fscod; 2 bsid; 5 reserved; 1 asvc; 1 bsmod; 3 acmod; 3 lfeon; 1 reserved; 3 num_dep_sub; 4 if (num_dep_sub > 0) { chan_loc; 9 } else { reserved; 1 } } reserved; 7 flag_ec3_extension_type_a; 1 complexity_index_type_a; 8 reserved; n * 8 }	
NOTE: <i>n</i> is the number of bytes to complete the size of the box given by BoxHeader.Size.	

C.3.2 Semantics

C.3.2.1 General

Semantics of the contained elements are described in ETSI TS 102 366 [1], clause F.6.2.

C.3.2.2 `flag_ec3_extension_type_a`

The element `flag_ec3_extension_type_a` is a flag that, if set to true, indicates the enhanced AC-3 extension as defined in the present document.

C.3.2.3 `complexity_index_type_a`

The element `complexity_index_type_a` is an unsigned integer that indicates the decoding complexity of the enhanced AC-3 extension defined in the present document. The value of this field shall be equal to the total number of bed objects, ISF objects and dynamic objects indicated by the parameters in the `program_assignment` section of the object audio metadata payload. The maximum value of this field shall be 16.

Annex D (normative): Bit streams in MPEG DASH

D.1 Introduction

This annex describes the requirements and recommendations for delivering streams using the MPEG Dynamic Adaptive Streaming over HTTP (DASH) standard (see ISO/IEC 23009-1 [3]) in conjunction with the ISO base media file format, specifically referencing audio streams within the MPEG DASH media presentation description file.

D.2 Media Presentation Description (MPD)

D.2.1 General

Media Presentation Description files compliant to the present document shall conform to the requirements on MPD for enhanced AC-3 bitstreams defined in ETSI TS 102 366 [1], clause I.1. The value of the *@codecs* attribute is *ec-3*.

Additionally, the following applies:

- for signalling presence of the enhanced AC-3 extension as defined in the present document a DASH supplemental property descriptor as specified in clause D.2.2.1 should be used, and
- for signalling complexity of the enhanced AC-3 extension as defined in the present document a DASH supplemental property descriptor as specified in clause D.2.2.2 should be used.

D.2.2 Descriptors

D.2.2.1 Extension type

Presence of the enhanced AC-3 extension as defined in the present document is signalled with a DASH supplemental property descriptor using the *schemeIdUri* tag: *dolby.com,2018:dash:EC3_ExtensionType:2018*.

The value of this DASH descriptor shall be the three character string *JOC*.

D.2.2.2 Extension complexity index

Complexity of the enhanced AC-3 extension as defined in the present document is signalled with a DASH supplemental property descriptor using the *schemeIdUri*

tag: *dolby.com,2018:dash:EC3_ExtensionComplexityIndex:2018*.

The value of this DASH descriptor shall be decimal representation of the eight-bit element *complexity_index_type_a* in the *EC3SpecificBox* of an enhanced AC-3 audio track.

D.2.3 Example Media Presentation Description

```
<?xml version="1.0" encoding="UTF-8"?>
<MPD xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:dolby="http://www.dolby.com/ns/online/DASH" xmlns="urn:mpeg:dash:schema:mpd:201
1"
  xsi:schemaLocation="urn:mpeg:dash:schema:mpd:2011 DASH-MPD.xsd"
  type="dynamic"
  minimumUpdatePeriod="PT2S"
  timeShiftBufferDepth="PT30M"
  availabilityStartTime="2011-12-25T12:30:00"
  publishTime="2011-12-25T12:30:00"
```



```

minBufferTime="PT4S"
profiles="urn:mpeg:dash:profile:isoff-live:2011">
<BaseURL>http://cdn1.example.com/</BaseURL>
<BaseURL>http://cdn2.example.com/</BaseURL>
<Period id="2">
  <!-- Video -->
  <AdaptationSet mimeType="video/mp4" codecs="avc1.4D401F" frameRate="30000/1001"
    segmentAlignment="true" startWithSAP="1">
    <BaseURL>video/</BaseURL>
    <SegmentTemplate timescale="90000" media="$Bandwidth$/$Number$.m4s" initializ
ation="$Bandwidth$/0.mp4">
      <SegmentTimeline>
        <S t="0" d="180180" r="12"/>
      </SegmentTimeline>
    </SegmentTemplate>
    <Representation id="v0" width="320" height="240" bandwidth="250000" />
    <Representation id="v1" width="640" height="480" bandwidth="500000" />
    <Representation id="v2" width="960" height="720" bandwidth="1000000" />
  </AdaptationSet>

  <!-- Object-based immersive audio AdaptationSet -->
  <AdaptationSet mimeType="audio/mp4" codecs="ec-
3" lang="en" segmentAlignment="true" startWithSAP="1">
    <Role schemeIdUri="urn:mpeg:dash:role:2011" value="main" />
    <SegmentTemplate timescale="48000" media="audio/en_main/$Bandwidth$/$Number$.
m4s"
      initialization="audio/en_main/$Bandwidth$/0.mp4">
      <SegmentTimeline>
        <S t="0" d="96000" r="11"/>
      </SegmentTimeline>
    </SegmentTemplate>
    <Representation id="a1" bandwidth="256000">
      <AudioChannelConfiguration schemeIdUri="urn:mpeg:mpegB:cicp:ChannelConfig
uration" value="6"/>
      <!-- alternative
      <AudioChannelConfiguration schemeIdUri="tag:dolby.com,2014:dash:audio_cha
nnel_configuration:2011" value="F801"/>
      -->
      <SupplementalProperty schemeIdUri="tag:dolby.com,2018:dash:EC3_ExtensionT
ype:2018" value="JOC"/>
      <SupplementalProperty schemeIdUri="tag:dolby.com,2018:dash:EC3_ExtensionC
omplexityIndex:2018" value="12"/>
    </Representation>
  </AdaptationSet>
</Period>
</MPD>

```

Annex E (normative): Object-based audio Common Media Application Format (CMAF) profiles

E.1 Introduction

This clause defines a CMAF profile with normative provisions if files written according to annex C of the present document are to be compliant with ISO/IEC 23000-19 [2].

E.2 Media tracks

Media tracks shall conform to ISO/IEC 23000-19 [2], sections 6, 7, 8, 10.1 and 10.2.

Additionally, Media tracks shall conform to ETSI TS 102 366 [1], clauses J.1.3, J.1.4, and J.1.5.

E.3 Elementary streams

The elementary stream shall contain exactly one independent substream (i.e. I0) and may contain one dependent substream (D0), but shall not contain more than one dependent substream.

The `acmod` and possibly present `chanmap` parameter shall indicate one of the channel configurations listed as downmix configurations in table 47.

The `numblkscod` parameter shall always be 3, indicating 6 audio blocks per frame.

E.4 Switching sets

common media application format switching sets shall conform to ETSI TS 102 366 [1], clause J.2.

E.5 Core object-based audio media profile

The `FileTypeBox` compatibility brand shall be `cea0` and should be used to indicate media tracks that conform to this media profile.

History

Document history		
V1.1.1	July 2016	Publication
V1.2.1	October 2018	Publication