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*Technical Specification*

**LTE;  
Evolved Universal Terrestrial Radio Access (E-UTRA);  
LTE Positioning Protocol (LPP)  
(3GPP TS 36.355 version 9.2.1 Release 9)**

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## Foreword

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# Foreword

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# 1 Scope

The present document contains the definition of the LTE Positioning Protocol (LPP).

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# 2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

- References are either specific (identified by date of publication, edition number, version number, etc.) or non-specific.
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- [1] 3GPP TR 21.905: "Vocabulary for 3GPP Specifications".
- [2] 3GPP TS 36.305: "Stage 2 functional specification of User Equipment (UE) positioning in E-UTRAN".
- [3] 3GPP TS 23.271: "Functional stage 2 description of Location Services (LCS)".
- [4] IS-GPS-200, Revision D, Navstar GPS Space Segment/Navigation User Interfaces, March 7<sup>th</sup>, 2006.
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- [9] Global Navigation Satellite System GLONASS Interface Control Document, Version 5.1, 2008.
- [10] Specification for the Wide Area Augmentation System (WAAS), US Department of Transportation, Federal Aviation Administration, DTFA01-96-C-00025, 2001.
- [11] RTCM-SC104, RTCM Recommended Standards for Differential GNSS Service (v.2.3), August 20, 2001.
- [12] 3GPP TS 36.331: "Evolved Universal Terrestrial Radio Access (E-UTRA); Radio Resource Control (RRC); Protocol specification".
- [13] 3GPP TS 25.331: " Radio Resource Control (RRC); Protocol Specification".
- [14] 3GPP TS 44.031: "Location Services (LCS); Mobile Station (MS) - Serving Mobile Location Centre (SMLC) Radio Resource LCS Protocol (RRLP)".
- [15] 3GPP TS 23.032: "Universal Geographical Area Description (GAD)".
- [16] 3GPP TS 36.211: "Evolved Universal Terrestrial Radio Access (E-UTRA); Physical Channels and Modulation".
- [17] 3GPP TS 36.214: "Evolved Universal Terrestrial Radio Access (E-UTRA); Physical layer – Measurements".

- [18] 3GPP TS 36.133: "Evolved Universal Terrestrial Radio Access (E-UTRA); Requirements for support of radio resource management".
- [19] 3GPP TS 23.003: "Numbering, addressing and identification".

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## 3 Definitions and Abbreviations

### 3.1 Definitions

For the purposes of the present document, the terms and definitions given in [1], [2] and [3] apply. Other definitions are provided below.

**Location Server:** a physical or logical entity (e.g. E-SMLC or SUPL SLP) that manages positioning for a target device by obtaining measurements and other location information from one or more positioning units and providing assistance data to positioning units to help determine this. An Location Server may also compute or verify the final location estimate.

**Reference Source:** a physical entity or part of a physical entity that provides signals (e.g. RF, acoustic, infra-red) that can be measured (e.g. by a Target Device) in order to obtain the location of a Target Device.

**Target Device:** the device that is being positioned (e.g. UE or SUPL SET).

**Observed Time Difference Of Arrival (OTDOA):** The time interval that is observed by a target device between the reception of downlink signals from two different cells. If a signal from cell 1 is received at the moment  $t_1$ , and a signal from cell 2 is received at the moment  $t_2$ , the OTDOA is  $t_2 - t_1$ .

### 3.2 Abbreviations

For the purposes of the present document, the following abbreviations apply.

ADR	Accumulated Delta-Range
A-GNSS	Assisted-GNSS
ARFCN	Absolute Radio Frequency Channel Number
BTS	Base Transceiver Station (GERAN)
CID	Cell-ID (positioning method)
CNAV	Civil Navigation
ECEF	Earth-Centered, Earth-Fixed
ECGI	Evolved Cell Global Identifier
ECI	Earth-Centered-Inertial
E-CID	Enhanced Cell-ID (positioning method)
EGNOS	European Geostationary Navigation Overlay Service
E-SMLC	Enhanced Serving Mobile Location Centre
E-UTRAN	Enhanced Universal Terrestrial Radio Access Network
EOP	Earth Orientation Parameters
EPDU	External Protocol Data Unit
FDMA	Frequency Division Multiple Access
FEC	Forward Error Correction
FTA	Fine Time Assistance
GAGAN	GPS Aided Geo Augmented Navigation
GLONASS	GLObal'naya NAVigatsionnaya Sputnikovaya Sistema (Engl.: Global Navigation Satellite System)
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
ICD	Interface Control Document
IOD	Issue of Data
IS	Interface Specification
LPP	LTE Positioning Protocol
LPPa	LTE Positioning Protocol Annex
LSB	Least Significant Bit
MO-LR	Mobile Originated Location Request

MSAS	Multi-functional Satellite Augmentation System
MSB	Most Significant Bit
msd	mean solar day
MT-LR	Mobile Terminated Location Request
NAV	Navigation
NICT	National Institute of Information and Communications Technology
NI-LR	Network Induced Location Request
OTDOA	Observed Time Difference Of Arrival
PRC	Pseudo-Range Correction
PRS	Positioning Reference Signals
PDU	Protocol Data Unit
PZ-90	Parametry Zemli 1990 Goda – Parameters of the Earth Year 1990
QZS	Quasi Zenith Satellite
QZSS	Quasi-Zenith Satellite System
QZST	Quasi-Zenith System Time
RF	Radio Frequency
RRC	Range-Rate Correction Radio Resource Control
RSRP	Reference Signal Received Power
RSRQ	Reference Signal Received Quality
RSTD	Reference Signal Time Difference
RU	Russia
SBAS	Space Based Augmentation System
SET	SUPL Enabled Terminal
SFN	System Frame Number
SLP	SUPL Location Platform
SUPL	Secure User Plane Location
SV	Space Vehicle
TLM	Telemetry
TOD	Time Of Day
TOW	Time Of Week
UDRE	User Differential Range Error
ULP	User Plane Location Protocol
USNO	US Naval Observatory
UT1	Universal Time No.1
UTC	Coordinated Universal Time
WAAS	Wide Area Augmentation System
WGS-84	World Geodetic System 1984

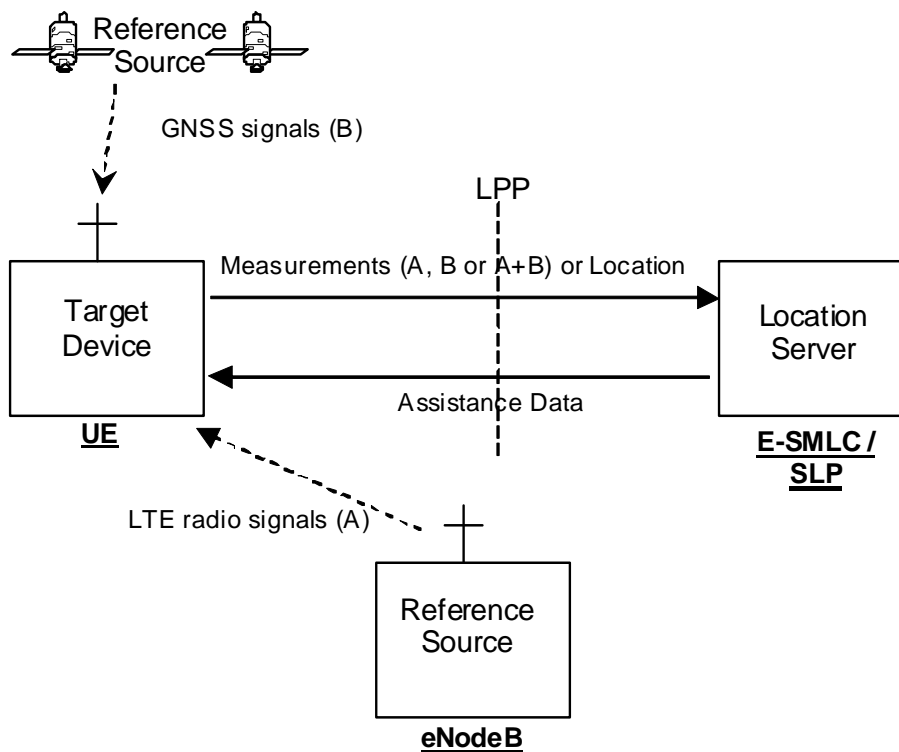
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## 4 Functionality of Protocol

### 4.1 General

#### 4.1.1 LPP Configuration

LPP is used point-to-point between a location server (E-SMLC or SLP) and a target device (UE or SET) in order to position the target device using position-related measurements obtained by one or more reference sources. Figure 4.1.1-1 shows the configuration as applied to the control- and user-plane location solutions for E-UTRAN (as defined in [2] and [3]).



**Figure 4.1.1-1: LPP Configuration for Control- and User-Plane Positioning in E-UTRAN**

## 4.1.2 LPP Sessions and Transactions

An LPP session is used between a Location Server and the target device in order to obtain location related measurements or a location estimate or to transfer assistance data. A single LPP session is used to support a single location request (e.g. for a single MT-LR, MO-LR or NI-LR). Multiple LPP sessions can be used between the same endpoints to support multiple different location requests (as required by [3]). Each LPP session comprises one or more LPP transactions with each LPP transaction performing a single operation (capability exchange, assistance data transfer, or location information transfer). In E-UTRAN the LPP transactions are realized as LPP procedures. The instigator of an LPP session will always instigate the first LPP transaction, but subsequent transactions may be instigated by either end. LPP transactions within a session may occur serially or in parallel. LPP transactions are indicated at the LPP protocol level with a transaction ID in order to associate messages with one another (e.g., request and response).

Messages within a transaction are linked by a common transaction identifier.

## 4.1.3 LPP Position Methods

Internal LPP positioning methods and associated signalling content are defined in this specification.

This version of the specification defines OTDOA, A-GNSS, and E-CID positioning methods.

## 4.1.4 LPP Messages

Each LPP transaction involves the exchange of one or more LPP messages between the location server and the target device. The general format of an LPP message consists of a set of common fields followed by a body. The body (which may be empty) contains information specific to a particular message type. Each message type contains information specific to one or more positioning methods and/or information common to all positioning methods.

The common fields are as follows:

Field	Role
Transaction ID	Identify messages belonging to the same transaction
Transaction End Flag	Indicate when a transaction (e.g. one with periodic responses) has ended
Ack	Enable an optional transport level acknowledgement of a received message (FFS)

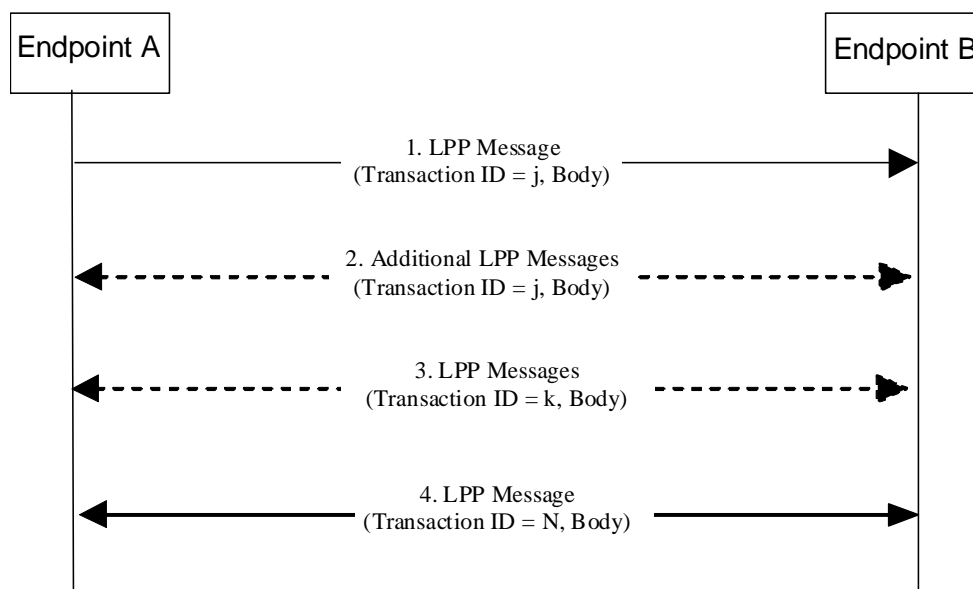
It is FFS if additional fields (e.g. session ID) are required for explicit modelling of an LPP session.

The following message types are defined:

- Request Capabilities;
- Provide Capabilities;
- Request Assistance Data;
- Provide Assistance Data;
- Request Location Information;
- Provide Location Information;
- Abort;
- Error.

## 4.2 Common LPP Session Procedure

The purpose of this procedure is to support an LPP session comprising a sequence of LPP transactions. The procedure is described in Figure 4.2-1.



**Figure 4.2-1 LPP Session Procedure**

1. Endpoint A, which may be either the target or the server, initiates an LPP session by sending an LPP message for an initial LPP transaction  $j$  to the other endpoint B (which has an opposite role to A).
2. Endpoints A and B may exchange further messages to continue the transaction started in step 1.
3. Either endpoint may instigate further transactions by sending additional LPP messages.
4. A session is terminated by a final transaction  $N$  in which LPP messages will be exchanged between the two endpoints.

Within each transaction, all constituent messages shall contain the same transaction identifier. The last message sent in each transaction shall have the field "Transaction end indicator" set to TRUE. Transactions that occur in parallel shall use different transaction IDs; transaction IDs for completed transactions may be reused at any time after the final message of the previous transaction with the same ID is known to have been received..

## 4.3 LPP Transport

### 4.3.1 Transport Layer Requirements

LPP requires reliable, in sequence delivery of LPP messages from the underlying transport layers. If the transport layer is reliable and provides in-sequence delivery (e.g., SUPL), no additional support for reliable transfer of messages is needed at the LPP level. However, LPP provides its own support for reliable in sequence delivery of LPP messages in the case of an underlying transport layer that is not fully reliable. This section describes the transport capabilities that are available within LPP.

### 4.3.2 LPP Duplicate Detection

A sender may include a sequence number in some or all LPP messages sent for a particular location session. The sequence number shall be distinct for different LPP messages in the same location session – e.g. may start at zero in the first LPP message and increase monotonically in each succeeding LPP message.

A receiver records the most recent received sequence number for each location session. If a message is received carrying the same sequence number as that last received for the associated location session, it shall be discarded. Otherwise (i.e. if the sequence number is different or if no sequence number was previously received or if no sequence number is included), the message shall be processed.

Sending and receiving sequence numbers shall be deleted in a server when the associated location session is terminated and shall be deleted in a target device when there has been no activity for a particular location session for 10 minutes.

NOTE: For LPP control plane use, a target device can be aware of a location session from information provided at the NAS level for downlink transport of an LPP message.

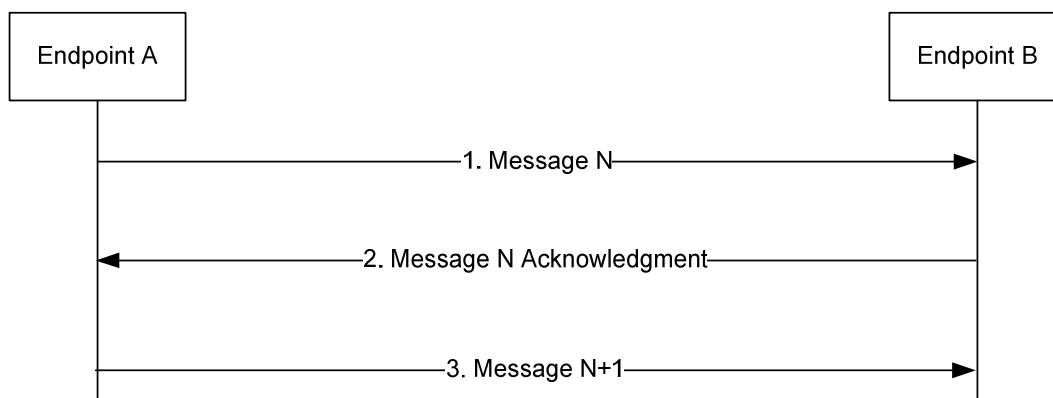
### 4.3.3 LPP Acknowledgment

#### 4.3.3.1 General

Each LPP message may carry an acknowledgment request indicator and/or an acknowledgement indicator. Upon reception of an LPP message which includes a request for acknowledgment, a receiver returns an acknowledgement response that includes the same sequence number if the message being acknowledged contains a sequence number. An acknowledgment is returned for each received LPP message including any duplicate. Once a sender receives an acknowledgment for an LPP message and provided any included sequence number is matching, it is permitted to send the next LPP message. No message reordering is needed at the receiver since this stop and wait method of sending ensures that messages normally arrive in the correct order.

#### 4.3.3.2 Procedure related to Acknowledgment

Figure 4.3.3.2-1 shows the procedure related to acknowledgment.



**Figure 4.3.3.2-1: LPP Acknowledgment procedure**

1. Endpoint A sends an LPP message N to Endpoint B and includes a request for acknowledgment.
2. If LPP message N is received (regardless of whether the message body can be correctly decoded), Endpoint B returns an acknowledgment for message N. The acknowledgment contains the same sequence number as that in message N if included.
3. When the acknowledgment for LPP message N is received and provided any included sequence number matches that in message N, Endpoint A sends the next LPP message N+1 to Endpoint B when this message is available.

**Editor's Note:** For step 3, it is assumed that LPP retransmission is used to ensure that either an acknowledgment is eventually received or all LPP activity for the location session is aborted. If LPP retransmission is not used, an additional mechanism is needed to detect and recover from message and acknowledgment loss (i.e. to avoid LPP transmission becoming blocked).

## 4.3.4 LPP Retransmission

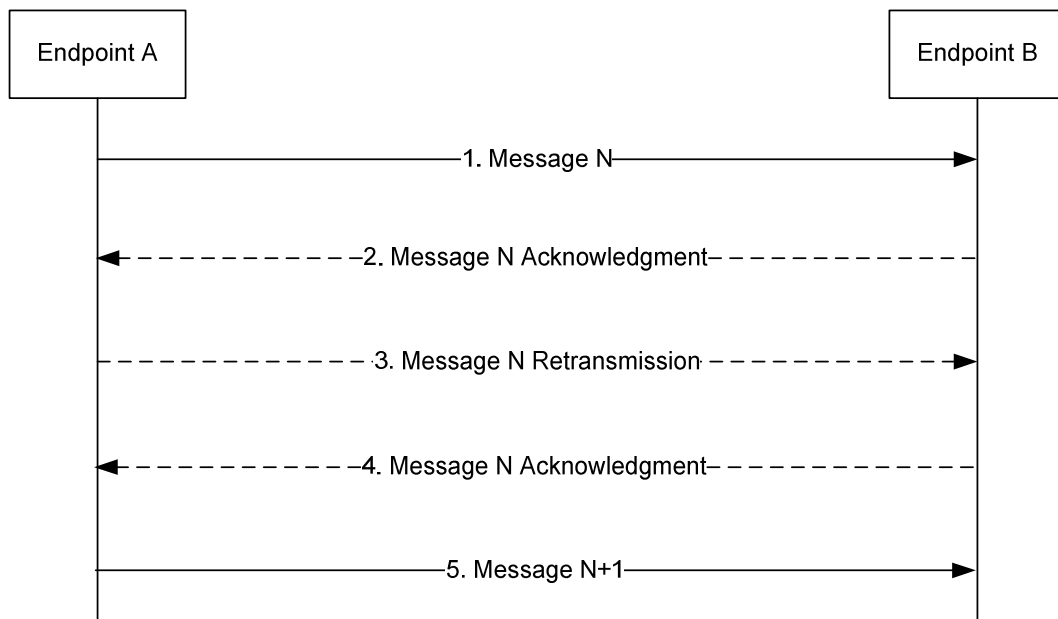
### 4.3.4.1 General

This capability builds on the acknowledgment and duplicate detection capabilities. When an LPP message which requires acknowledgement is sent and not acknowledged, it is resent by the sender following a timeout period up to three times. If still unacknowledged after that, the sender aborts all LPP activity for the associated session. The timeout period is determined by the sender implementation but shall not be less than a minimum value of [FFS].

### 4.3.4.2 Procedure related to Retransmission

Figure 4.3.4.2-1 shows the procedure related to retransmission when combined with acknowledgment and duplicate detection.





**Figure 4.3.4.2-1: LPP Retransmission procedure**

1. Endpoint A sends an LPP message N to Endpoint B for a particular location session and includes a request for acknowledgment.
2. If LPP message N is received (regardless of whether the message body can be correctly decoded), Endpoint B returns an acknowledgment for message N. If the acknowledgment is received by Endpoint A (such that the acknowledged message can be identified and any included sequence numbers are matching), Endpoint A skips steps 3 and 4.
3. If the acknowledgment in step 2 is not received after a timeout period, Endpoint A retransmits LPP message N and includes the same sequence number as in step 1 if a sequence number was included in step 1.
4. If LPP message N in step 3 is received (regardless of whether the message body can be correctly decoded and whether or not the message is considered a duplicate), Endpoint B returns an acknowledgment. Steps 3 and 4 may be repeated one or more times if the acknowledgment in step 3 is not received after a timeout period by Endpoint A. If the acknowledgment in step 4 is still not received after sending three retransmissions, Endpoint A aborts all procedures and activity associated with LPP support for the particular location session.
5. Once an acknowledgment in step 2 or step 4 is received, Endpoint A sends the next LPP message N+1 for the location session to Endpoint B when this message is available.

## 5 LPP Procedures

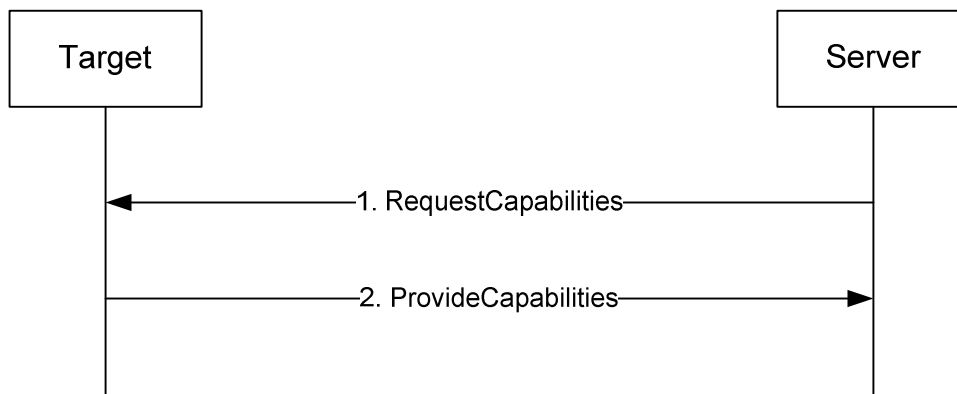
### 5.1 Procedures related to capability transfer

The purpose of the procedures that are grouped together in this section is to enable the transfer of capabilities from the target device to the server. Capabilities in this context refer to positioning and protocol capabilities related to LPP and the positioning methods supported by LPP.

These procedures instantiate the Capability Transfer transaction from 3GPP TS 36.305 [2].

#### 5.1.1 Capability Transfer procedure

The Capability Transfer procedure is shown in Figure 5.1.1-1.

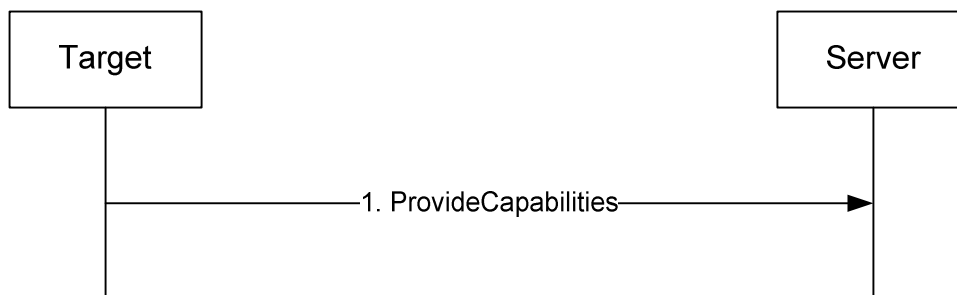


**Figure 5.1.1-1: LPP Capability Transfer procedure**

1. The server sends a *RequestCapabilities* message to the target. The server may indicate the types of capability needed.
2. The target responds with a *ProvideCapabilities* message to the server. The capabilities shall correspond to any capability types specified in step 1. This message carries an end transaction indication.

### 5.1.2 Capability Indication procedure

The Capability Indication procedure allows the target to provide unsolicited capabilities to the server and is shown in Figure 5.1.2-1.



**Figure 5.1.2-1: LPP Capability Indication procedure**

1. The target sends a *ProvideCapabilities* message to the server. This message carries an end transaction indication.

### 5.1.3 Reception of LPP Request Capabilities

Upon receiving a *RequestCapabilities* message, the target device shall generate a *ProvideCapabilities* message as a response.

The target device shall:

- 1> for each positioning method for which a request for capabilities is included in the message:
  - 2> if the target device supports this positioning method:
    - 3> include the capabilities of the device for that supported positioning method in the response message;
- 1> set the IE *LPP-TransactionID* in the response message to the same value as the IE *LPP-TransactionID* in the received message;
- 1> deliver the response message to lower layers for transmission.

## 5.1.4 Transmission of LPP Provide Capabilities

When triggered to transmit a *ProvideCapabilities* message, the target device shall:

- 1> for each positioning method whose capabilities are to be indicated:
  - 2> set the corresponding IE to include the device's capabilities;
- 1> deliver the response to lower layers for transmission.

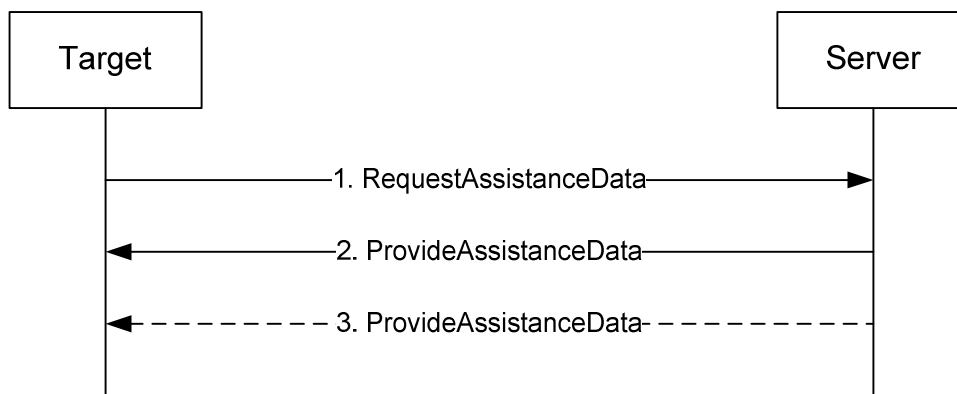
## 5.2 Procedures related to Assistance Data Transfer

The purpose of the procedures in this section is to enable the target to request assistance data from the server to assist in positioning, and to enable the server to transfer assistance data to the target in the absence of a request.

These procedures instantiate the Assistance Data Transfer transaction from 3GPP TS 36.305 [2].

### 5.2.1 Assistance Data Transfer procedure

The Assistance Data Transfer procedure is shown in Figure 5.2.1-1.

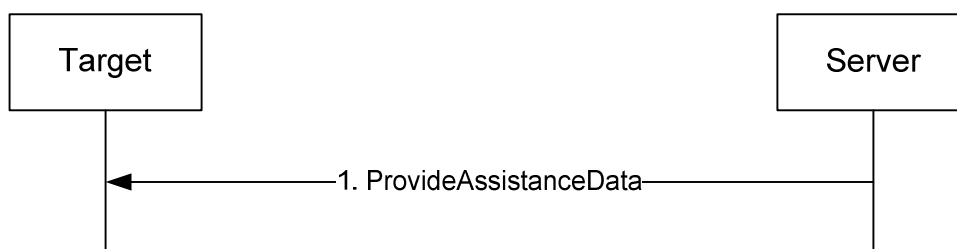


**Figure 5.2.1-1: LPP Assistance data transfer procedure**

1. The target sends a *RequestAssistanceData* message to the server.
2. The server responds with a *ProvideAssistanceData* message to the target containing assistance data. The transferred assistance data should match or be a subset of the assistance data requested in step 1.
3. The server may transmit one or more additional *ProvideAssistanceData* messages to the target containing further assistance data. The transferred assistance data should match or be a subset of the assistance data requested in step 1. The last message carries an end transaction indication.

### 5.2.2 Assistance Data Delivery procedure

The Assistance Data Delivery procedure allows the server to provide unsolicited assistance data to the target and is shown in Figure 5.2.2-1.



**Figure 5.2.2-1: LPP Assistance data transfer procedure**

1. The server sends a *ProvideAssistanceData* message to the target containing assistance data. This message may contain an end transaction indication.

### 5.2.3 Transmission of LPP Request Assistance Data

When triggered to transmit a *RequestAssistanceData* message, the target device shall:

- 1> set the IEs for the positioning-method-specific request for assistance data to request the data indicated by upper layers.

### 5.2.4 Reception of LPP Provide Assistance Data

Upon receiving a *ProvideAssistanceData* message, the target device shall:

- 1> for each positioning method contained in the Body:
  - 2> deliver the related assistance data to upper layers.

## 5.3 Procedures related to Location Information Transfer

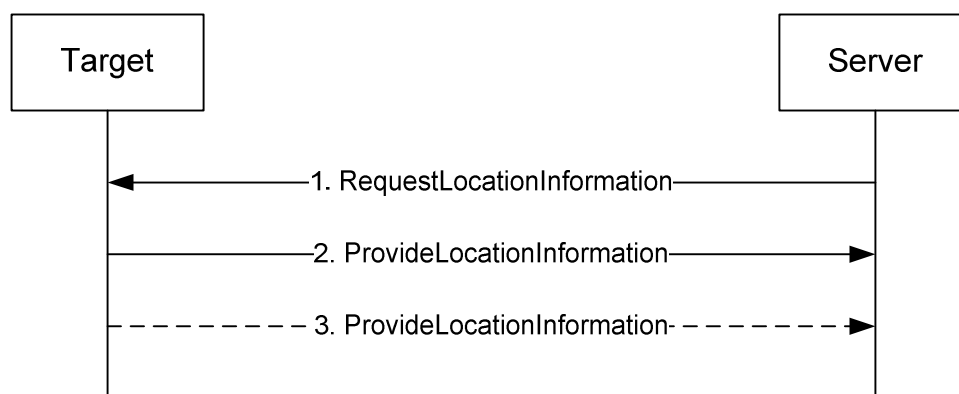
The purpose of the procedures in this section is to enable the server to request location measurement data and/or a location estimate from the target, and to enable the target to transfer location measurement data and/or a location estimate to a server in the absence of a request.

These procedures instantiate the Location Information Transfer transaction in 3GPP TS 36.305 [2].

NOTE: The service layer (e.g. NAS or OMA SUPL ULP) would be used to transfer information associated with a location request from a target to a server (MO-LR).

### 5.3.1 Location Information Transfer procedure

The Location Information Transfer procedure is shown in Figure 5.3.1-1.



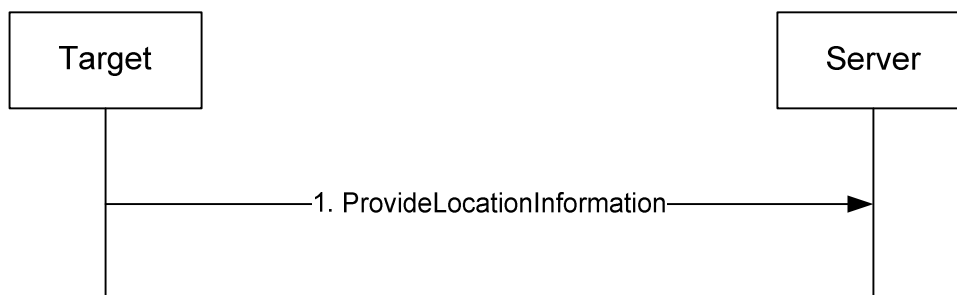
**Figure 5.3.1-1: LPP Location Information transfer procedure**

1. The server sends a *RequestLocationInformation* message to the target to request location information, indicating the type of location information needed and potentially the associated QoS.
2. The target sends a *ProvideLocationInformation* message to the server to transfer location information. The location information transferred should match or be a subset of the location information requested in step 1 unless the server explicitly allows additional location information. This message may carry an end transaction indication.
3. If requested in step 1, the target sends additional *ProvideLocationInformation* messages to the server to transfer location information. The location information transferred should match or be a subset of the location

information requested in step 1 unless the server explicitly allows additional location information. The last message carries an end transaction indication.

### 5.3.2 Location Information Delivery procedure

The Location Information Delivery allows the target to provide unsolicited location information to the server and procedure is shown in Figure 5.3.2-1.



**Figure 5.3.2-1: LPP Location Information Delivery procedure**

1. The target sends a *ProvideLocationInformation* message to the server to transfer location information. This message may carry an end transaction indication.

### 5.3.3 Reception of Request Location Information

Upon receiving a *RequestLocationInformation* message, the target device shall:

- 1> if the requested information is compatible with the target device capabilities and configuration:
  - 2> include the requested information in a *ProvideLocationInformation* message;
  - 2> set the IE *LPP-TransactionID* in the response to the same value as the IE *LPP-TransactionID* in the received message;
  - 2> deliver the *ProvideLocationInformation* message to lower layers for transmission.
- 1> otherwise:
  - 2> if one or more positioning methods are included that the target device does not support:
    - 3> Continue to process the message as if it contained only information for the supported positioning methods.
    - 3> Handle the signaling content of the not supported positioning methods by LPP error detection as in 5.4.3.

### 5.3.4 Transmission of Provide Location Information

When triggered to transmit *ProvideLocationInformation* message, the target device shall:

- 1> for each positioning method contained in the message:
  - 2> set the corresponding IE to include the available location information;
- 1> deliver the response to lower layers for transmission.

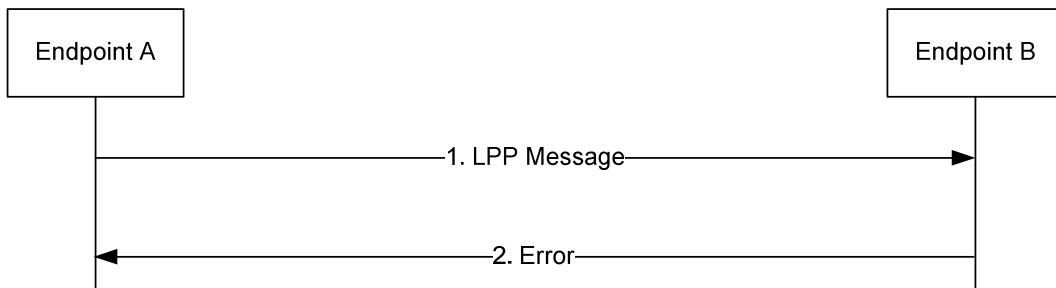
## 5.4 Error Handling Procedures

### 5.4.1 General

This sub-clause describes how a receiving entity (target device or location server) behaves in cases when it receives erroneous or unexpected data or detects that certain data are missing.

### 5.4.2 Procedures related to Error Indication

Figure 5.4.2-1 shows the procedure related to Error indication.



**Figure 5.4.2-1: LPP Error Indication procedure**

1. Endpoint A sends an LPP message to Endpoint B.
2. Endpoint B determines that the LPP message in step 1 contains an error and is not an LPP Error or Abort message. Endpoint B returns an *Error* message to Endpoint A indicating the error or errors and discards the message in step 1.

### 5.4.3 LPP Error Detection

Upon receiving any LPP message, the receiving entity shall attempt to decode the message and verify the presence of any errors prior to using the following procedure:

- 1> if decoding errors are encountered:
  - 2> if decoding cannot determine the *LPP-TransactionID*:
    - 3> discard the message and stop error detection.
  - 2> if decoding can determine that the message is not an LPP *Error* or *Abort* message:
    - 3> return an LPP *Error* message to the sender and include the received *LPP-TransactionID* and type of error;
    - 3> discard the message and stop error detection;
- 1> if the message is a duplicate of previously received message
  - 2> discard the message and stop error detection.
- 1> if the *LPP-TransactionID* matches the *LPP-TransactionID* for a procedure that is still ongoing for the same session and the message type is invalid for the current state of the procedure:
  - 2> abort the ongoing procedure;
  - 2> return an Error message to the sender and include the received transaction ID and type of error;
  - 2> discard the message and stop error detection.
- 1> if the message type is an LPP *RequestCapabilities* and some of the requested information is not supported:

- 2> return any information that can be provided in a normal response.
- 1> if the message type is an LPP *RequestAssistanceData*, or *RequestLocationInformation* and some or all of the requested information is not supported:
  - 2> return any information that can be provided in a normal response, which includes indications on other information that is not supported.

## 5.4.4 Reception of an LPP Error Message

Upon receiving an *Error* message, a device shall:

- 1> abort any ongoing procedure associated with the *LPP-TransactionID* indicated in the message.

The device may:

- 1> restart the aborted procedure taking into consideration the returned error information.

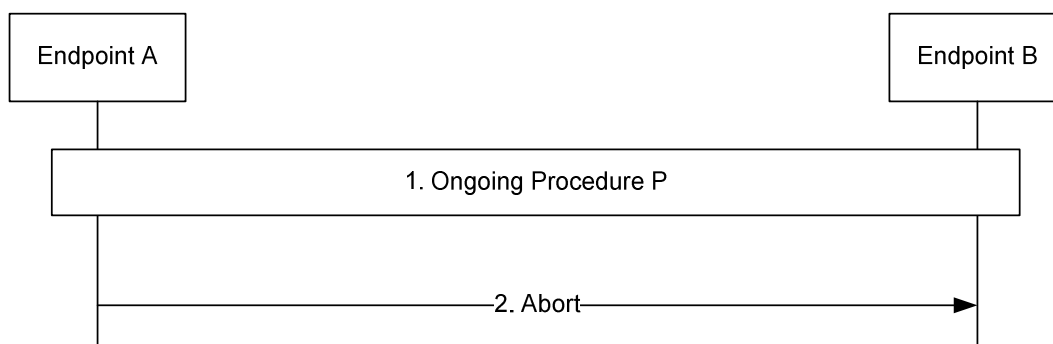
## 5.5 Abort Procedure

### 5.5.1 General

The purpose of the abort procedure is to allow the the target device or location server to abort an ongoing procedure due to some unexpected event – e.g. cancelation of a location request by an LCS client. It can also be used to stop an ongoing procedure – e.g. periodic location reporting from the target device.

### 5.5.2 Procedures related to Abort

Figure 5.5.2-1 shows the Abort procedure.



**Figure 5.5.2-1: LPP Abort procedure**

1. A procedure P is ongoing between endpoints A and B
2. Endpoint A determines that the procedure must be aborted and sends an *Abort* message to Endpoint B carrying the transaction ID for procedure P. Endpoint B aborts procedure P.

### 5.5.3 Reception of an LPP Abort Message

Upon receiving an *Abort* message, a device shall:

- 1> abort any ongoing procedure associated with the transaction ID indicated in the message.

## 6 Information Element Abstract Syntax Definition

### 6.1 General

The contents of each LPP message is specified in sub-clause 6.2 using ASN.1 to specify the message syntax and using tables when needed to provide further detailed information about the information elements specified in the message syntax. The syntax of the information elements that are defined as stand-alone abstract types is further specified in a similar manner in sub-clause 6.3.

The ASN.1 in this section uses the same format and coding conventions as described in Annex A of [12].

### 6.2 LPP PDU Structure

#### – *LPP-PDU-Definitions*

This ASN.1 segment is the start of the LPP PDU definitions.

```
-- ASN1START
LPP-PDU-Definitions DEFINITIONS AUTOMATIC TAGS ::=
BEGIN
-- ASN1STOP
```

#### – *LPP-Message*

The *LPP-Message* provides the complete set of information for an invocation or response pertaining to an LPP transaction.

```
-- ASN1START
LPP-Message ::= SEQUENCE {
    transactionID      LPP-TransactionID  OPTIONAL,  -- Need ON
    endTransaction     BOOLEAN,
    sequenceNumber     SequenceNumber     OPTIONAL,  -- Need ON
    acknowledgment     Acknowledgment     OPTIONAL,  -- Need ON
    lpp-MessageBody    LPP-MessageBody    OPTIONAL  -- Need ON
}

SequenceNumber ::= INTEGER (0..255)

Acknowledgment ::= SEQUENCE {
    ackRequested      BOOLEAN,
    ackIndicator      SequenceNumber      OPTIONAL
}
-- ASN1STOP
```

#### ***LPP-Message* field descriptions**

<b><i>sequenceNumber</i></b>	This field is included when LPP operates over the control plane and omitted otherwise.
<b><i>acknowledgment</i></b>	This field is included when LPP operates over the control plane and is omitted otherwise
<b><i>ackIndicator</i></b>	This field indicates the sequence number of the message being acknowledged.
<b><i>lpp-MessageBody</i></b>	This field is omitted in an LPP transport level ack
<b><i>transactionID</i></b>	This field is omitted if it is not available to the transmitting entity (e.g., in an <i>LPP-Error</i> message triggered by a message that could not be parsed).



## – *LPP-MessageBody*

The *LPP-MessageBody* identifies the type of an LPP message and contains all LPP information specifically associated with that type.

```
-- ASN1START
LPP-MessageBody ::= CHOICE {
  c1 CHOICE {
    requestCapabilities      RequestCapabilities,
    provideCapabilities      ProvideCapabilities,
    requestAssistanceData   RequestAssistanceData,
    provideAssistanceData   ProvideAssistanceData,
    requestLocationInformation RequestLocationInformation,
    provideLocationInformation ProvideLocationInformation,
    abort                    Abort,
    error                    Error,
    spare7 NULL, spare6 NULL, spare5 NULL, spare4 NULL,
    spare3 NULL, spare2 NULL, spare1 NULL, spare0 NULL
  },
  messageClassExtension SEQUENCE {}
}
-- ASN1STOP
```

## – *LPP-TransactionID*

The *LPP-TransactionID* identifies a particular LPP transaction and the initiator of the transaction.

```
-- ASN1START
LPP-TransactionID ::= SEQUENCE {
  initiator      Initiator,
  transactionNumber TransactionNumber,
  ...
}

Initiator ::= ENUMERATED {
  locationServer,
  targetDevice,
  ...
}

TransactionNumber ::= INTEGER (0..255)
-- ASN1STOP
```

## 6.3 Message Body IEs

### – *RequestCapabilities*

The *RequestCapabilities* message body in a LPP message is used by the location server to request the target device capability information for LPP and the supported individual positioning methods.

```
-- ASN1START
RequestCapabilities ::= SEQUENCE {
  criticalExtensions CHOICE {
    c1 CHOICE {
      requestCapabilities-r9 RequestCapabilities-r9-IEs,
      spare3 NULL, spare2 NULL, spare1 NULL
    },
    criticalExtensionsFuture SEQUENCE {}
  }
}

RequestCapabilities-r9-IEs ::= SEQUENCE {
  commonIEsRequestCapabilities CommonIEsRequestCapabilities OPTIONAL, -- Need ON
  a-gnss-RequestCapabilities A-GNSS-RequestCapabilities OPTIONAL,
  otdoa-RequestCapabilities OTDOA-RequestCapabilities OPTIONAL,
```

```

    ecid-RequestCapabilities          ECID-RequestCapabilities          OPTIONAL,
    epdu-RequestCapabilities          EPDU-Sequence                     OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP

```

#### **RequestCapabilities field descriptions**

##### **commonIEsRequestCapabilities**

This IE is provided for future extensibility and should not be included in this version of the protocol.

### – *ProvideCapabilities*

The *ProvideCapabilities* message body in a LPP message indicates the LPP capabilities of the target device to the location server.

```

-- ASN1START
ProvideCapabilities ::= SEQUENCE {
    criticalExtensions      CHOICE {
        c1                  CHOICE {
            provideCapabilities-r9      ProvideCapabilities-r9-IEs,
            spare3 NULL, spare2 NULL, spare1 NULL
        },
        criticalExtensionsFuture      SEQUENCE {}
    }
}

ProvideCapabilities-r9-IEs ::= SEQUENCE {
    commonIEsProvideCapabilities      CommonIEsProvideCapabilities          OPTIONAL,  -- Need ON
    a-gnss-ProvideCapabilities        A-GNSS-ProvideCapabilities          OPTIONAL,  -- Need ON
    otdoa-ProvideCapabilities         OTDOA-ProvideCapabilities          OPTIONAL,  -- Need ON
    ecid-ProvideCapabilities          ECID-ProvideCapabilities          OPTIONAL,  -- Need ON
    epdu-ProvideCapabilities          EPDU-Sequence                     OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP

```

#### **ProvideCapabilities field descriptions**

##### **commonIEsProvideCapabilities**

This IE is provided for future extensibility and should not be included in this version of the protocol.

### – *RequestAssistanceData*

The *RequestAssistanceData* message body in a LPP message is used by the target device to request assistance data from the location server.

```

-- ASN1START
RequestAssistanceData ::= SEQUENCE {
    criticalExtensions      CHOICE {
        c1                  CHOICE {
            requestAssistanceData-r9      RequestAssistanceData-r9-IEs,
            spare3 NULL, spare2 NULL, spare1 NULL
        },
        criticalExtensionsFuture      SEQUENCE {}
    }
}

RequestAssistanceData-r9-IEs ::= SEQUENCE {
    commonIEsRequestAssistanceData      CommonIEsRequestAssistanceData          OPTIONAL,  -- Need ON
    a-gnss-RequestAssistanceData        A-GNSS-RequestAssistanceData          OPTIONAL,  -- Need ON
    otdoa-RequestAssistanceData         OTDOA-RequestAssistanceData          OPTIONAL,  -- Need ON
    epdu-RequestAssistanceData          EPDU-Sequence                     OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP

```

## – *ProvideAssistanceData*

The *ProvideAssistanceData* message body in a LPP message is used by the location server to provide assistance data to the target device either in response to a request from the target device or in an unsolicited manner.

```
-- ASN1START
ProvideAssistanceData ::= SEQUENCE {
    criticalExtensions      CHOICE {
        c1                  CHOICE {
            provideAssistanceData-r9    ProvideAssistanceData-r9-IEs,
            spare3 NULL, spare2 NULL, spare1 NULL
        },
        criticalExtensionsFuture    SEQUENCE {}
    }
}

ProvideAssistanceData-r9-IEs ::= SEQUENCE {
    commonIEsProvideAssistanceData    CommonIEsProvideAssistanceData    OPTIONAL, -- Need ON
    a-gnss-ProvideAssistanceData      A-GNSS-ProvideAssistanceData      OPTIONAL, -- Need ON
    otdoa-ProvideAssistanceData        OTDOA-ProvideAssistanceData        OPTIONAL, -- Need ON
    epdu-Provide-Assistance-Data       EPDU-Sequence                      OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP
```

### ***ProvideAssistanceData* field descriptions**

#### ***commonIEsProvideAssistanceData***

This IE is provided for future extensibility and should not be included in this version of the protocol.

## – *RequestLocationInformation*

The *RequestLocationInformation* message body in a LPP message is used by the location server to request positioning measurements or a position estimate from the target device.

```
-- ASN1START
RequestLocationInformation ::= SEQUENCE {
    criticalExtensions      CHOICE {
        c1                  CHOICE {
            requestLocationInformation-r9    RequestLocationInformation-r9-IEs,
            spare3 NULL, spare2 NULL, spare1 NULL
        },
        criticalExtensionsFuture    SEQUENCE {}
    }
}

RequestLocationInformation-r9-IEs ::= SEQUENCE {
    commonIEsRequestLocationInformation    CommonIEsRequestLocationInformation    OPTIONAL, -- Need ON
    a-gnss-RequestLocationInformation      A-GNSS-RequestLocationInformation      OPTIONAL, -- Need ON
    otdoa-RequestLocationInformation        OTDOA-RequestLocationInformation        OPTIONAL, -- Need ON
    ecid-RequestLocationInformation         ECID-RequestLocationInformation         OPTIONAL, -- Need ON
    epdu-RequestLocationInformation         EPDU-Sequence                          OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP
```

### ***RequestLocationInformation* field descriptions**

#### ***commonIEsRequestLocationInformation***

This field specifies the location information type requested by the location server and optionally other configuration information associated with the requested location information. This field should always be included in this version of the protocol.

## – *ProvideLocationInformation*

The *ProvideLocationInformation* message body in a LPP message is used by the target device to provide positioning measurements or position estimates to the location server.

```
-- ASN1START
ProvideLocationInformation ::= SEQUENCE {
    criticalExtensions      CHOICE {
        c1                  CHOICE {
            provideLocationInformation-r9  ProvideLocationInformation-r9-IEs,
            spare3 NULL, spare2 NULL, spare1 NULL
        },
        criticalExtensionsFuture  SEQUENCE {}
    }
}

ProvideLocationInformation-r9-IEs ::= SEQUENCE {
    commonIEsProvideLocationInformation
        CommonIEsProvideLocationInformation  OPTIONAL,  -- Need ON
    a-gnss-ProvideLocationInformation  A-GNSS-ProvideLocationInformation  OPTIONAL,  -- Need ON
    otdoa-ProvideLocationInformation  OTDOA-ProvideLocationInformation  OPTIONAL,  -- Need ON
    ecid-ProvideLocationInformation  ECID-ProvideLocationInformation  OPTIONAL,  -- Need ON
    epdu-ProvideLocationInformation  EPDU-Sequence  OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP
```

## – *Abort*

The *Abort* message body in a LPP message carries a request to abort an ongoing LPP procedure.

```
-- ASN1START
Abort ::= SEQUENCE {
    criticalExtensions      CHOICE {
        c1                  CHOICE {
            abort-r9        Abort-r9-IEs,
            spare3 NULL, spare2 NULL, spare1 NULL
        },
        criticalExtensionsFuture  SEQUENCE {}
    }
}

Abort-r9-IEs ::= SEQUENCE {
    commonIEsAbort  CommonIEsAbort  OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP
```

## – *Error*

The *Error* message body in a LPP message carries information concerning a LPP message that was received with errors.

```
-- ASN1START
Error ::= CHOICE {
    error-r9  Error-r9-IEs,
    criticalExtensionsFuture  SEQUENCE {}
}

Error-r9-IEs ::= SEQUENCE {
    commonIEsError  CommonIEsError  OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP
```

**Editor's Note:** to ensure compatibility of an Error message between different versions of LPP, it is not expected that critical extensions will be used in future versions; hence only one method of supporting critical extensions is provided

## 6.4 Common IEs

Common IEs comprise IEs that are applicable to more than one LPP positioning method.

### 6.4.1 Common Lower-Level IEs

#### – *ARFCN-ValueEUTRA*

The IE *ARFCN-ValueEUTRA* is used to indicate the ARFCN of the E-UTRA carrier frequency, as defined in [12].

```
-- ASN1START
ARFCN-ValueEUTRA ::= INTEGER (0..65535)
-- ASN1STOP
```

#### – *CellGlobalIdEUTRA-AndUTRA*

The IE *CellGlobalIdEUTRA-AndUTRA* specifies the global Cell Identifier for E-UTRA or UTRA, the globally unique identity of a cell in E-UTRA or UTRA.

```
-- ASN1START
CellGlobalIdEUTRA-AndUTRA ::= SEQUENCE {
    plmn-Identity      SEQUENCE {
        mcc            SEQUENCE (SIZE (3)) OF INTEGER (0..9),
        mnc            SEQUENCE (SIZE (2..3)) OF INTEGER (0..9)
    },
    cellIdentity      CHOICE {
        eutra          BIT STRING (SIZE (28)),
        utra           BIT STRING (SIZE (32))
    },
    ...
}
-- ASN1STOP
```

#### ***CellGlobalIdEUTRA-AndUTRA* field descriptions**

##### ***plmn-Identity***

This field identifies the PLMN of the cell as defined in [12].

##### ***cellIdentity***

This field defines the identity of the cell within the context of the PLMN as defined in [12] and [13]. The size of the bit string allows for the 32-bit extended UTRAN cell ID; in case the cell ID is shorter, the first bits of the string are set to 0.

#### – *CellGlobalIdGERAN*

The IE *CellGlobalIdGERAN* specifies the global Cell Identifier for GERAN, the globally unique identity of a cell in GERAN.

```
-- ASN1START
CellGlobalIdGERAN ::= SEQUENCE {
    plmn-Identity      SEQUENCE {
        mcc            SEQUENCE (SIZE (3)) OF INTEGER (0..9),
        mnc            SEQUENCE (SIZE (2..3)) OF INTEGER (0..9)
    },
    locationAreaCode  BIT STRING (SIZE (16)),
    cellIdentity       BIT STRING (SIZE (16)),
}
-- ASN1STOP
```

```

}
...
}
-- ASN1STOP

```

#### **CellGlobalIdGERAN field descriptions**

<b><i>plmn-Identity</i></b>
This field identifies the PLMN of the cell.
<b><i>locationAreaCode</i></b>
This field is a fixed length code identifying the location area within a PLMN.
<b><i>cellIdentity</i></b>
This field specifies the cell Identifier which is unique within the context of the GERAN location area.

### – *Ellipsoid-Point*

The IE *Ellipsoid-Point* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```

-- ASN1START
Ellipsoid-Point ::= SEQUENCE {
    latitudeSign      ENUMERATED {north, south},
    degreesLatitude   INTEGER (0..8388607),           -- 23 bit field
    degreesLongitude  INTEGER (-8388608..8388607)  -- 24 bit field
}
-- ASN1STOP

```

### – *Ellipsoid-PointWithUncertaintyCircle*

The IE *Ellipsoid-PointWithUncertaintyCircle* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```

-- ASN1START
Ellipsoid-PointWithUncertaintyCircle ::= SEQUENCE {
    latitudeSign      ENUMERATED {north, south},
    degreesLatitude   INTEGER (0..8388607),           -- 23 bit field
    degreesLongitude  INTEGER (-8388608..8388607),  -- 24 bit field
    uncertainty       INTEGER (0..127)
}
-- ASN1STOP

```

### – *EllipsoidPointWithUncertaintyEllipse*

The IE *EllipsoidPointWithUncertaintyEllipse* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```

-- ASN1START
EllipsoidPointWithUncertaintyEllipse ::= SEQUENCE {
    latitudeSign      ENUMERATED {north, south},
    degreesLatitude   INTEGER (0..8388607),           -- 23 bit field
    degreesLongitude  INTEGER (-8388608..8388607),  -- 24 bit field
    uncertaintySemiMajor  INTEGER (0..127),
    uncertaintySemiMinor  INTEGER (0..127),
    orientationMajorAxis  INTEGER (0..179),
    confidence         INTEGER (0..100)
}
-- ASN1STOP

```

### – *EllipsoidPointWithAltitude*

The IE *EllipsoidPointWithAltitude* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
EllipsoidPointWithAltitude ::= SEQUENCE {
  latitudeSign      ENUMERATED {north, south},
  degreesLatitude   INTEGER (0..8388607),          -- 23 bit field
  degreesLongitude  INTEGER (-8388608..8388607),  -- 24 bit field
  altitudeDirection ENUMERATED {height, depth},
  altitude          INTEGER (0..32767)           -- 15 bit field
}
-- ASN1STOP
```

### – *EllipsoidPointWithAltitudeAndUncertaintyEllipsoid*

The IE *EllipsoidPointWithAltitudeAndUncertaintyEllipsoid* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
EllipsoidPointWithAltitudeAndUncertaintyEllipsoid ::= SEQUENCE {
  latitudeSign      ENUMERATED {north, south},
  degreesLatitude   INTEGER (0..8388607),          -- 23 bit field
  degreesLongitude  INTEGER (-8388608..8388607),  -- 24 bit field
  altitudeDirection ENUMERATED {height, depth},
  altitude          INTEGER (0..32767),           -- 15 bit field
  uncertaintySemiMajor    INTEGER (0..127),
  uncertaintySemiMinor    INTEGER (0..127),
  orientationMajorAxis    INTEGER (0..179),
  uncertaintyAltitude     INTEGER (0..127),
  confidence           INTEGER (0..100)
}
-- ASN1STOP
```

### – *EllipsoidArc*

The IE *EllipsoidArc* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
EllipsoidArc ::= SEQUENCE {
  latitudeSign      ENUMERATED {north, south},
  degreesLatitude   INTEGER (0..8388607),          -- 23 bit field
  degreesLongitude  INTEGER (-8388608..8388607),  -- 24 bit field
  innerRadius       INTEGER (0..65535),           -- 16 bit field,
  uncertaintyRadius  INTEGER (0..127),
  offsetAngle       INTEGER (0..179),
  includedAngle     INTEGER (0..179),
  confidence         INTEGER (0..100)
}
-- ASN1STOP
```

### – *EPDU-Sequence*

The *EPDU-Sequence* contains IEs that are defined externally to LPP by other organizations.

```
-- ASN1START
EPDU-Sequence ::= SEQUENCE (SIZE (1..maxEPDU)) OF EPDU

maxEPDU INTEGER ::= 16

EPDU ::= SEQUENCE {
  ePDU-Identifier    EPDU-Identifier,
```

```

    ePDU-Body          EPDU-Body
  }
EPDU-Identifier ::= SEQUENCE {
    ePDU-ID            EPDU-ID,
    ePDU-Name          EPDU-Name    OPTIONAL,
    ...
}
EPDU-ID ::= INTEGER (1..256)
EPDU-Name ::= VisibleString (SIZE (1..32))
EPDU-Body ::= OCTET STRING
-- ASN1STOP

```

#### **EPDU-Sequence field descriptions**

##### **EPDU-ID**

This field provides a unique integer ID for the externally defined positioning method. Its value is assigned to the external entity that defines the EPDU and defined by that entity.

##### **EPDU-Name**

This field provides an optional character encoding which can be used to provide a quasi-unique name for an external PDU – e.g., by containing the name of the defining organization and/or the name of the associated public or proprietary standard for the EPDU.

##### **EPDU-Body**

The content and encoding of this field are defined externally to LPP.

### – *HorizontalVelocity*

The IE *HorizontalVelocity* is used to describe a velocity shape as defined in 3GPP TS 23.032 [15].

```

-- ASN1START
HorizontalVelocity ::= SEQUENCE {
    bearing            INTEGER(0..359),
    horizontalSpeed    INTEGER(0..2047)
}
-- ASN1STOP

```

### – *HorizontalWithVerticalVelocity*

The IE *HorizontalWithVerticalVelocity* is used to describe a velocity shape as defined in 3GPP TS 23.032 [15].

```

-- ASN1START
HorizontalWithVerticalVelocity ::= SEQUENCE {
    bearing            INTEGER(0..359),
    horizontalSpeed    INTEGER(0..2047),
    verticalDirection  ENUMERATED{upward, downward},
    verticalSpeed      INTEGER(0..255)
}
-- ASN1STOP

```

### – *HorizontalVelocityWithUncertainty*

The IE *HorizontalVelocityWithUncertainty* is used to describe a velocity shape as defined in 3GPP TS 23.032 [15].

```

-- ASN1START
HorizontalVelocityWithUncertainty ::= SEQUENCE {
    bearing            INTEGER(0..359),
    horizontalSpeed    INTEGER(0..2047),
    uncertaintySpeed    INTEGER(0..255)
}

```



```
-- ASN1STOP
```

### – *HorizontalWithVerticalVelocityAndUncertainty*

The IE *HorizontalWithVerticalVelocityAndUncertainty* is used to describe a velocity shape as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
HorizontalWithVerticalVelocityAndUncertainty ::= SEQUENCE {
    bearing                INTEGER(0..359),
    horizontalSpeed        INTEGER(0..2047),
    verticalDirection      ENUMERATED{upward, downward},
    verticalSpeed          INTEGER(0..255),
    horizontalUncertaintySpeed  INTEGER(0..255),
    verticalUncertaintySpeed  INTEGER(0..255)
}
-- ASN1STOP
```

### – *LocationCoordinateTypes*

The IE *LocationCoordinateTypes* defines a list of possible geographic shapes as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
LocationCoordinateTypes ::= SEQUENCE {
    ellipsoidPoint                BOOLEAN,
    ellipsoidPointWithUncertaintyCircle  BOOLEAN,
    ellipsoidPointWithUncertaintyEllipse  BOOLEAN,
    polygon                        BOOLEAN,
    ellipsoidPointWithAltitude        BOOLEAN,
    ellipsoidPointWithAltitudeAndUncertaintyEllipsoid  BOOLEAN,
    ellipsoidArc                    BOOLEAN,
    ...
}
-- ASN1STOP
```

### – *Polygon*

The IE *Polygon* is used to describe a geographic shape as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
Polygon ::= SEQUENCE (SIZE (3..15)) OF PolygonPoints
PolygonPoints ::= SEQUENCE {
    latitudeSign                ENUMERATED {north, south},
    degreesLatitude             INTEGER (0..8388607),          -- 23 bit field
    degreesLongitude            INTEGER (-8388608..8388607)    -- 24 bit field
}
-- ASN1STOP
```

### – *PositioningModes*

The IE *PositioningModes* is used to indicate several positioning modes using a bit map.

```
-- ASN1START
PositioningModes ::= SEQUENCE {
    posModes                    BIT STRING {
        standalone (0),
        ue-based (1),
        ue-assisted (2) } (SIZE (1..8)),
    ...
}
```

```
}
-- ASN1STOP
```

#### **PositioningModes field descriptions**

##### ***posModes***

This field specifies the positioning mode(s). This is represented by a bit string, with a one-value at the bit position means the particular positioning mode is addressed; a zero-value means not addressed.

### – *VelocityTypes*

The IE *VelocityTypes* defines a list of possible velocity shapes as defined in 3GPP TS 23.032 [15].

```
-- ASN1START
VelocityTypes ::= SEQUENCE {
    horizontalVelocity                BOOLEAN,
    horizontalWithVerticalVelocity    BOOLEAN,
    horizontalVelocityWithUncertainty  BOOLEAN,
    horizontalWithVerticalVelocityAndUncertainty  BOOLEAN,
    ...
}
-- ASN1STOP
```

## 6.4.2 Common Positioning

### – *CommonIEsRequestCapabilities*

The *CommonIEsRequestCapabilities* carries common IEs for a Request Capabilities LPP message Type.

```
-- ASN1START
CommonIEsRequestCapabilities ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### – *CommonIEsProvideCapabilities*

The *CommonIEsProvideCapabilities* carries common IEs for a Provide Capabilities LPP message Type.

```
-- ASN1START
CommonIEsProvideCapabilities ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### – *CommonIEsRequestAssistanceData*

The *CommonIEsRequestAssistanceData* carries common IEs for a Request Assistance Data LPP message Type.

```
-- ASN1START
CommonIEsRequestAssistanceData ::= SEQUENCE {
    servingCellID
    ECGI          OPTIONAL,    -- Cond EUTRA
    ...
}
ECGI ::= SEQUENCE {
```

```

mcc          SEQUENCE (SIZE (3)) OF INTEGER (0..9),
mnc          SEQUENCE (SIZE (2..3)) OF INTEGER (0..9),
cellidentity BIT STRING (SIZE (28))
}
-- ASN1STOP

```

Conditional presence	Explanation
<i>EUTRA</i>	The field is mandatory present for E-UTRA access. The field shall be omitted for non-EUTRA user plane support..

#### ***CommonIEsRequestAssistanceData* field descriptions**

***servingCellID***  
This parameter identifies the current serving cell for the target device.

### – *CommonIEsProvideAssistanceData*

The *CommonIEsProvideAssistanceData* carries common IEs for a Provide Assistance Data LPP message Type.

```

-- ASN1START
CommonIEsProvideAssistanceData ::= SEQUENCE {
    ...
}
-- ASN1STOP

```

### – *CommonIEsRequestLocationInformation*

The *CommonIEsRequestLocationInformation* carries common IEs for a Request Location Information LPP message Type.

```

-- ASN1START
CommonIEsRequestLocationInformation ::= SEQUENCE {
    locationInformationType      LocationInformationType,
    triggeredReporting           TriggeredReportingCriteria OPTIONAL, -- Cond ECID
    periodicalReporting          PeriodicalReportingCriteria OPTIONAL, -- Need ON
    additionalInformation        AdditionalInformation OPTIONAL, -- Need ON
    qos                          QoS OPTIONAL, -- Need ON
    environment                  Environment OPTIONAL, -- Need ON
    locationCoordinateTypes      LocationCoordinateTypes OPTIONAL, -- Need ON
    velocityTypes                VelocityTypes OPTIONAL, -- Need ON
    ...
}
LocationInformationType ::= ENUMERATED {
    locationEstimateRequired,
    locationMeasurementsRequired,
    locationEstimatePreferred,
    locationMeasurementsPreferred,
    ...
}
PeriodicalReportingCriteria ::= SEQUENCE {
    reportingAmount
    ENUMERATED {
        ra1, ra2, ra4, ra8, ra16, ra32,
        ra64, ra-Infinity
    } DEFAULT ra-Infinity,
    reportingInterval
    ENUMERATED {
        noPeriodicalReporting, ri0-25,
        ri0-5, ri1, ri2, ri4, ri8, ri16, ri32, ri64
    }
}
}

```

```

TriggeredReportingCriteria ::= SEQUENCE {
    cellChange                BOOLEAN,
    reportingDuration          ReportingDuration,
    ...
}

ReportingDuration ::= INTEGER (0..255)

AdditionalInformation ::= ENUMERATED {
    onlyReturnInformationRequested,
    mayReturnAdditionalInformation,
    ...
}

QoS ::= SEQUENCE {
    horizontalAccuracy          HorizontalAccuracy    OPTIONAL,    -- Need ON
    verticalCoordinateRequest   BOOLEAN,
    verticalAccuracy            VerticalAccuracy     OPTIONAL,    -- Need ON
    responseTime                ResponseTime        OPTIONAL,    -- Need ON
    velocityRequest             BOOLEAN,
    ...
}

HorizontalAccuracy ::= SEQUENCE {
    accuracy                    INTEGER(0..127),
    confidence                   INTEGER(0..100),
    ...
}

VerticalAccuracy ::= SEQUENCE {
    accuracy                    INTEGER(0..127),
    confidence                   INTEGER(0..100),
    ...
}

Confidence ::= INTEGER (1..100)

ResponseTime ::= SEQUENCE {
    time                        INTEGER (1..128),
    ...
}

Environment ::= ENUMERATED {
    badArea,
    notBadArea,
    mixedArea,
    ...
}

-- ASN1STOP
    
```

Conditional presence	Explanation
ECID	The field is optionally present, need ON, if ECID is requested. Otherwise it is not present.

CommonEsRequestLocationInformation field descriptions
<p><b>locationInformationType</b></p> <p>This IE indicates whether the server requires a location estimate or measurements. For 'locationEstimateRequired', the UE shall return a location estimate if possible, or indicate "location estimate not allowed" if not possible. For 'locationMeasurementsRequired', the UE shall return measurements if possible, or indicate "measurements not allowed" if not possible. For 'locationEstimatePreferred', the UE shall return a location estimate if possible, but may also or instead return measurements for any requested position methods for which a location estimate is not possible. For 'locationMeasurementsPreferred', the UE shall return location measurements if possible, but may also or instead return a location estimate for any requested position methods for which return of location measurements is not possible.</p>

<b>CommonEsRequestLocationInformation field descriptions</b>
<p><b>periodicalReporting</b> This IE indicates that periodic reporting is requested and comprises the following subfields:</p> <ul style="list-style-type: none"> <li>• <b>reportingAmount</b> indicates the number of periodic location information reports requested. Enumerated values correspond to 2, 4, 8, 16, 32, 64, 128, or infinite/indefinite number of reports. If the <i>reportingAmount</i> is 'infinite/indefinite', the target device should continue periodic reporting until an LPP <i>Abort</i> message is received.</li> <li>• <b>reportingInterval</b> indicates the interval between location information reports and the response time requirement for the first location information report. This is given as an integer number of seconds between 1 and 64. Measurement reports containing no measurements or no location estimate are required when a <i>reportingInterval</i> expires before a target device is able to obtain new measurements or obtain a new location estimate.</li> </ul>
<p><b>additionalInformation</b> This IE indicates whether a target device is allowed to return additional information to that requested. If a location estimate is returned, any additional information is restricted to that associated with a location estimate (e.g. might include velocity if velocity was not requested but cannot include measurements). If measurements are returned, any additional information is restricted to additional measurements (e.g. might include E-CID measurements if A-GNSS measurements were requested but not E-CID measurements).</p>
<p><b>qos</b> This IE indicates the quality of service and comprises a number of sub-fields. In the case of measurements, some of the sub-fields apply to the location estimate that could be obtained by the server from the measurements provided by the target device assuming that the measurements are the only sources of error. Fields are as follows:</p> <ul style="list-style-type: none"> <li>• <b>horizontalAccuracy</b> indicates the maximum horizontal error in the location estimate at an indicated confidence level. The 'accuracy' code and 'confidence' is as defined in 3GPP TS 23.032 [15].</li> <li>• <b>verticalCoordinateRequest</b> indicates whether a vertical coordinate is required (true) or not (false)</li> <li>• <b>verticalAccuracy</b> indicates the maximum vertical error in the location estimate at an indicated confidence level and is only applicable when a vertical coordinate is requested. The 'accuracy' code and 'confidence' is as defined in 3GPP TS 23.032 [15].</li> <li>• <b>responseTime</b> indicates the maximum response time as measured between receipt of the <i>RequestLocationInformation</i> and transmission of a <i>ProvideLocationInformation</i>. This is given as an integer number of seconds between 1 and 128. If the <i>periodicalReporting</i> IE is included in <i>CommonEsRequestLocationInformation</i>, this field should not be included by the location server and shall be ignored by the target device (if included).</li> <li>• <b>velocity</b> indicates whether velocity is requested (true) or not (false).</li> </ul> <p>All QoS requirements shall be obtained by the target device to the degree possible but it is permitted to return a response that does not fulfill all QoS requirements if some were not attainable. The single exception is response-time which shall always be fulfilled – even if that means not fulfilling other QoS requirements.</p>
<p><b>environment</b> This field provides the target device with information about expected multipath and non line of sight (NLOS) in the current area. The following values are defined:</p> <ul style="list-style-type: none"> <li>• <b>badArea</b>: possibly heavy multipath and NLOS conditions (e.g. bad urban or urban).</li> <li>• <b>notBadArea</b>: no or light multipath and usually LOS conditions (e.g. suburban or rural).</li> <li>• <b>mixedArea</b>: environment that is mixed or not defined.</li> </ul> <p>If this field is absent, a default value of 'mixedArea' applies.</p>
<p><b>locationCoordinateTypes</b> This field provides a list of the types of location estimate that the target device may return when a location estimate is obtained by the target.</p>
<p><b>velocityTypes</b> This fields provides a list of the types of velocity estimate that the target device may return when a velocity estimate is obtained by the target.</p>
<p><b>cellChange</b> If this field is present and set to TRUE, the target device provides requested location information each time the serving cell has changed.</p>
<p><b>reportingDuration</b> Maximum duration of triggered reporting in seconds. A value of zero is interpreted to mean an unlimited (i.e. "infinite") duration.</p>

### CommonEsProvideLocationInformation

The *CommonEsProvideLocationInformation* carries common IEs for a Provide Location Information LPP message Type.

```
-- ASN1START
```

```
CommonEsProvideLocationInformation ::= SEQUENCE {
```

```

    locationEstimate      LocationCoordinates  OPTIONAL,
    velocityEstimate     Velocity            OPTIONAL,
    locationError        LocationError        OPTIONAL,
    ...
}

LocationCoordinates ::= CHOICE {
    ellipsoidPoint                Ellipsoid-Point,
    ellipsoidPointWithUncertaintyCircle  Ellipsoid-PointWithUncertaintyCircle,
    ellipsoidPointWithUncertaintyEllipse EllipsoidPointWithUncertaintyEllipse,
    polygon                       Polygon,
    ellipsoidPointWithAltitude     EllipsoidPointWithAltitude,
    ellipsoidPointWithAltitudeAndUncertaintyEllipsoid EllipsoidPointWithAltitudeAndUncertaintyEllipsoid,
    ellipsoidArc                  EllipsoidArc,
    ...
}

Velocity ::= CHOICE {
    horizontalVelocity                HorizontalVelocity,
    horizontalWithVerticalVelocity    HorizontalWithVerticalVelocity,
    horizontalVelocityWithUncertainty HorizontalVelocityWithUncertainty,
    horizontalWithVerticalVelocityAndUncertainty HorizontalWithVerticalVelocityAndUncertainty,
    ...
}

LocationError ::= SEQUENCE {
    locationfailurecause      LocationFailureCause,
    ...
}

LocationFailureCause ::= ENUMERATED {
    undefined,
    requestedMethodNotSupported,
    positionMethodFailure,
    periodicLocationMeasurementsNotAvailable,
    ...
}

degreesMaximum      INTEGER ::= 8388607
degreesMaximumNegative INTEGER ::= -8388608

-- ASN1STOP

```

#### **CommonIEsProvideLocationInformation field descriptions**

##### **locationEstimate**

This field provides a location estimate using one of the geographic shapes defined in 3GPP TS 23.032 [15]. Coding of the values the various fields internal to each geographic shape follow the rules in [15]. The conditions for including this field are defined for the *locationInformationType* field in a Request Location Information message.

##### **velocityEstimate**

This field provides a velocity estimate using one of the velocity shapes defined in 3GPP TS 23.032 [15]. Coding of the values the various fields internal to each velocity shape follow the rules in [15].

##### **locationError**

This field shall be included if and only if a location estimate and measurements are not included in the LPP PDU. The field includes information concerning the reason for the lack of location information. The *LocationFailureCause* 'periodicLocationMeasurementsNotAvailable' shall be used by the target device if periodic location reporting was requested, but no measurements or location estimate are available when *the reportingInterval* expired.

#### – **CommonIEsAbort**

The *CommonIEsAbort* carries common IEs for an Abort LPP message Type.

```

-- ASN1START

CommonIEsAbort ::= SEQUENCE {
    abortCause      ENUMERATED {
        undefined,
        stopPeriodicReporting,
        targetDeviceAbort,
        networkAbort,
        ...
    }
}

```

```

}
}
-- ASN1STOP

```

#### **CommonIEsAbort field descriptions**

##### **abortCause**

This IE defines the request to abort an ongoing procedure.

### – *CommonIEsError*

The *CommonIEsError* carries common IEs for an Error LPP message Type.

```

-- ASN1START
CommonIEsError ::= SEQUENCE {
    errorCause      ENUMERATED {
        undefined,
        lppMessageHeaderError,
        lppMessageBodyError,
        epduError,
        incorrectDataValue,
        ...
    }
}
-- ASN1STOP

```

#### **CommonIEsError field descriptions**

##### **errorCause**

This IE defines the cause for an error. 'lppMessageHeaderError', 'lppMessageBodyError' and 'epduError' shall be used when a receiver detects a coding error in the LPP header, LPP message body or in an EPDU, respectively.

## 6.5 Positioning Method IEs

### 6.5.1 OTDOA Positioning

#### 6.5.1.1 OTDOA Assistance Data

##### – *OTDOA-ProvideAssistanceData*

The IE *OTDOA-ProvideAssistanceData* is used by the location server to provide assistance data to enable UE-assisted downlink OTDOA. It may also be used to provide OTDOA positioning specific error reason.

```

-- ASN1START
OTDOA-ProvideAssistanceData ::= SEQUENCE {
    otdoa-ReferenceCellInfo      OTDOA-ReferenceCellInfo      OPTIONAL,
    otdoa-NeighbourCellInfo      OTDOA-NeighbourCellInfoList  OPTIONAL,
    otdoa-Error                  OTDOA-Error                  OPTIONAL,
    ...
}
-- ASN1STOP

```

## 6.5.1.2 OTDOA Assistance Data Elements

– *OTDOA-ReferenceCellInfo*

The IE *OTDOA-ReferenceCellInfo* is used by the location server to provide reference cell information for OTDOA assistance data. The slot number offsets and expected RSTDs in *OTDOA-NeighbourCellInfoList* are provided relative to the cell defined by this IE.

```
-- ASN1START
OTDOA-ReferenceCellInfo ::= SEQUENCE {
    physCellId          INTEGER (0..503),
    cellGlobalId        ECGI                      OPTIONAL,      -- Need ON
    earfcnRef           ARFCN-ValueEUTRA          OPTIONAL,      -- Cond NotSameAsServ0
    antennaPortConfig  ENUMERATED {ports1-or-2, ports4, ... }
                                                                OPTIONAL,      -- Cond NotSameAsServ1
    cpLength            ENUMERATED { normal, extended, ... },
    prsInfo             PRS-Info                  OPTIONAL,      -- Cond PRS
    ...
}
-- ASN1STOP
```

Conditional presence	Explanation
<i>NotSameAsServ0</i>	The field is mandatory present if the ARFCN of the OTDOA reference cell for assistance data is not the same as the ARFCN of the target devices's current serving cell.
<i>NotSameAsServ1</i>	The field is mandatory present if the antenna port configuration of the OTDOA reference cell for assistance data is not the same as the antenna port configuration of the target devices's current serving cell.
<i>PRS</i>	The field is mandatory present if positioning reference signals are available in the reference cell [16]; otherwise it is not present.

**OTDOA-ReferenceCellInfo field descriptions**

<b><i>physCellId</i></b>	This field specifies the physical cell identity of the reference cell, as defined in [12].
<b><i>cellGlobalId</i></b>	This field specifies the ECGI, the globally unique identity of a cell in E-UTRA, of the reference cell, as defined in [12]. The server includes this field if it considers that it is needed to resolve ambiguity in the cell indicated by <i>physCellId</i> .
<b><i>earfcnRef</i></b>	This field specifies the ARFCN of the reference cell for the OTDOA assistance data.
<b><i>antennaPortConfig</i></b>	This field specifies whether 1 (or 2) antenna port(s) or 4 antenna ports for cell specific reference signals are used in the reference cell for OTDOA assistance data.
<b><i>cpLength</i></b>	This field specifies the cyclic prefix length of the reference cell PRS.
<b><i>prs-Info</i></b>	This field specifies the PRS configuration of the reference cell for OTDOA assistance data.

– *PRS-Info*

```
-- ASN1START
PRS-Info ::= SEQUENCE {
    prs-Bandwidth        ENUMERATED { n6, n15, n25, n50, n75, n100, ... },
    prs-ConfigurationIndex INTEGER (0..4095),
    numDL-Frames         ENUMERATED {sf-1, sf-2, sf-4, sf-6, ... },
    ...,
    prs-MutingInfo-r9    CHOICE {
        po2-r9           BIT STRING (SIZE(2)),
        po4-r9           BIT STRING (SIZE(4)),
        po8-r9           BIT STRING (SIZE(8)),
        po16-r9          BIT STRING (SIZE(16)),
        ...
    }
}
-- ASN1STOP
```



<b>PRS-Info field descriptions</b>
<p><b>prs-Bandwidth</b> This field specifies the bandwidth that is used to configure the positioning reference signals on. Enumerated values are specified in number of resource blocks (n6 corresponds to 6 resource blocks, n15 to 15 resource blocks and so on) and define 1.4, 3, 5, 10, 15 and 20 MHz bandwidth.</p>
<p><b>prs-ConfigurationIndex</b> This field specifies the positioning reference signals configuration index <math>I_{PRS}</math> as defined in [16].</p>
<p><b>numDL-Frames</b> This field specifies the number of consecutive downlink subframes <math>N_{PRS}</math> with positioning reference signals, as defined in [16]. Enumerated values define 1, 2, 4, or 6 consecutive subframes.</p>
<p><b>prs-MutingInfo</b> This field specifies the PRS muting configuration of the cell. The PRS muting configuration is defined by a periodic PRS muting sequence with periodicity <math>T_{REP}</math> where <math>T_{REP}</math>, counted in the number of positioning occasions [18], can be 2, 4, 8, or 16 which is also the length of the selected bit string that represents this PRS muting sequence. If a bit in the PRS muting sequence is set to "0", then the PRS is muted in the corresponding PRS positioning occasion. A positioning occasion comprises of <math>N_{PRS}</math> downlink positioning subframes as defined in [16]. The first bit of the PRS muting sequence corresponds to the first positioning occasion that starts after the beginning of serving cell SFN=0. The sequence is valid for all subframes after the UE has received the <i>prs-MutingInfo</i>. If this field is not present the UE may assume that the PRS muting is not in use for the cell.</p>

### – OTDOA-NeighbourCellInfoList

The IE *OTDOA-NeighbourCellInfoList* is used by the location server to provide neighbour cell information for OTDOA assistance data. The *OTDOA-NeighbourCellInfoList* is sorted according to best measurement geometry at the a-priori location estimate of the target device. I.e., the target device is expected to provide measurements in increasing neighbor cell list order (to the extent that this information is available to the target device).

```
-- ASN1START

OTDOA-NeighbourCellInfoList ::= SEQUENCE (SIZE (1..maxFreqLayers)) OF OTDOA-NeighbourFreqInfo
OTDOA-NeighbourFreqInfo ::= SEQUENCE (SIZE (1..24)) OF OTDOA-NeighbourCellInfoElement

OTDOA-NeighbourCellInfoElement ::= SEQUENCE {
    physCellId          INTEGER (0..503),
    cellGlobalId        ECGI                OPTIONAL,      -- Need ON
    earfcn              ARFCN-ValueEUTRA    OPTIONAL,      -- Cond NotSameAsRef0
    cpLength            ENUMERATED {normal, extended, ...}
                                OPTIONAL,      -- Cond NotSameAsRef1
    prsInfo             PRS-Info            OPTIONAL,      -- Cond NotSameAsRef2
    antennaPortConfig  ENUMERATED {ports-1-or-2, ports-4, ...}
                                OPTIONAL,      -- Cond NotsameAsRef3
    slotNumberOffset    INTEGER (0..31)     OPTIONAL,      -- Cond NotSameAsRef4
    prs-SubframeOffset  INTEGER (0..1279)   OPTIONAL,
    expectedRSTD        INTEGER (0..16383),
    expectedRSTD-Uncertainty
                        INTEGER (0..1023),
    ...
}

maxFreqLayers    INTEGER ::= 3

-- ASN1STOP
```

<b>Conditional presence</b>	<b>Explanation</b>
<i>NotSameAsRef0</i>	The field is mandatory present if the ARFCN is not the same as for the reference cell; otherwise it is not present.
<i>NotSameAsRef1</i>	The field is mandatory present if the cyclic prefix length is not the same as for the reference cell; otherwise it is not present.
<i>NotSameAsRef2</i>	The field is mandatory present if the PRS configuration is not the same as for the reference cell; otherwise it is not present.
<i>NotSameAsRef3</i>	The field is mandatory present if the antenna port configuration is not the same as for the reference cell; otherwise it is not present.
<i>NotSameAsRef4</i>	The field is mandatory present if the slot timing is not the same as for the reference cell; otherwise it is not present.
<i>InterFreq</i>	The field is optionally present, need OP, if the ARFCN is not the same as for the reference cell; otherwise it is not present.

<b><i>OTDOA-NeighbourCellInfoList</i> field descriptions</b>
<p><b><i>physCellId</i></b> This field specifies the physical cell identity of the neighbour cell, as defined in [12].</p>
<p><b><i>cellGlobalId</i></b> This field specifies the ECGI, the globally unique identity of a cell in E-UTRA, of the neighbour cell, as defined in [12]. The server provides this field if it considers that it is needed to resolve any ambiguity in the cell identified by <i>physCellId</i>.</p>
<p><b><i>earfcn</i></b> This field specifies the ARFCN of the neighbor cell.</p>
<p><b><i>cpLength</i></b> This field specifies the cyclic prefix length of the neighbour cell PRS.</p>
<p><b><i>prsInfo</i></b> This field specifies the PRS configuration of the neighbour cell.</p>
<p><b><i>antennaPortConfig</i></b> This field specifies whether 1 (or 2) antenna port(s) or 4 antenna ports for cell specific reference signals are used.</p>
<p><b><i>slotNumberOffset</i></b> This field specifies the slot number offset between this cell and the reference cell. The offset corresponds to the number of full slots counted from the beginning of a radio frame of the reference cell to the beginning of the closest subsequent radio frame of this cell. The offset is used to determine the neighbour cell slot number which is used for generation of reference signal sequence as defined in [16]. If this field is absent, the slot timing is the same as for the reference cell.</p>
<p><b><i>prs-SubframeOffset</i></b> This field specifies the offset between the first PRS subframe in the reference cell on the reference carrier frequency layer and the first PRS subframe in the closest subsequent PRS burst of the other cell on the other carrier frequency layer. The value is given in number of full sub-frames. If the ARFCN is not the same as for the reference cell and the field is not present, the receiver shall consider the PRS subframe offset for this cell to be 0.</p>
<p><b><i>expectedRSTD</i></b> This field indicates the RSTD value that the target device is expected to measure between this cell and the reference cell in <i>OTDOAReferenceCellInfo</i>. The RSTD value can be negative and is calculated as (<i>expectedRSTD</i>-8192). The resolution is <math>3 \times T_s</math>, with <math>T_s = 1 / (15000 \times 2048)</math> seconds.</p>
<p><b><i>expectedRSTD-Uncertainty</i></b> This field indicates the uncertainty in <i>expectedRSTD</i> value. The uncertainty is related to the location server's a-priori estimation of the target device location. The <i>expectedRSTDUncertainty</i> defines the following search window for the target device:  <math>[ \textit{expectedRSTD} - \textit{expectedRSTD-Uncertainty} ] &lt; \textit{measured RSTD} &lt; [ \textit{expectedRSTD} + \textit{expectedRSTD-Uncertainty} ]</math>  The scale factor of the <i>expectedRSTD-Uncertainty</i> field is <math>3 \times T_s</math>, with <math>T_s = 1 / (15000 \times 2048)</math> seconds.</p>

### 6.5.1.3 OTDOA Assistance Data Request

#### – *OTDOA-RequestAssistanceData*

The IE *OTDOA-RequestAssistanceData* is used by the target device to request assistance data from a location server.

```
-- ASN1START
OTDOA-RequestAssistanceData ::= SEQUENCE {
    physCellId    INTEGER (0..503),
    ...
}
-- ASN1STOP
```

<b><i>OTDOA-RequestAssistanceData</i> field descriptions</b>
<p><b><i>physCellId</i></b> This field specifies the physical cell identity of the current serving cell of the target device.</p>

#### 6.5.1.4 OTDOA Location Information

##### – *OTDOA-ProvideLocationInformation*

The IE *OTDOA-ProvideLocationInformation* is used by the target device to provide OTDOA location measurements to the location server. It may also be used to provide OTDOA positioning specific error reason.

```
-- ASN1START
OTDOA-ProvideLocationInformation ::= SEQUENCE {
    otdoaSignalMeasurementInformation  OTDOA-SignalMeasurementInformation  OPTIONAL,
    otdoa-Error                        OTDOA-Error                        OPTIONAL,
    ...
}
-- ASN1STOP
```

#### 6.5.1.5 OTDOA Location Information Elements

##### – *OTDOA-SignalMeasurementInformation*

The IE *OTDOA-SignalMeasurementInformation* is used by the target device to provide RSTD measurements to the location server.

```
-- ASN1START
OTDOA-SignalMeasurementInformation ::= SEQUENCE {
    systemFrameNumber      BIT STRING (SIZE (10)),
    physCellIdRef          INTEGER (0..503),
    cellGlobalIdRef        ECGI                    OPTIONAL,
    earfcnRef              ARFCN-ValueEUTRA        OPTIONAL,
    referenceQuality        OTDOA-MeasQuality      OPTIONAL,
    neighbourMeasurementList NeighbourMeasurementList,
    ...
}

NeighbourMeasurementList ::= SEQUENCE (SIZE(1..24)) OF NeighbourMeasurementElement

NeighbourMeasurementElement ::= SEQUENCE {
    physCellIdNeighbor      INTEGER (0..503),
    cellGlobalIdNeighbour   ECGI                    OPTIONAL,
    earfcnNeighbour         ARFCN-ValueEUTRA        OPTIONAL,
    rstd                   INTEGER (0..12711),
    rstd-Quality            OTDOA-MeasQuality,
    ...
}
-- ASN1STOP
```

#### ***OTDOA-SignalMeasurementInformation* field descriptions**

<b><i>systemFrameNumber</i></b>	This field specifies the SFN during which the last measurement was performed.
<b><i>physCellIdRef</i></b>	This field specifies the physical cell identity of the reference cell relative to which the RSTDs are provided.
<b><i>cellGlobalIdRef</i></b>	This field specifies the ECGI, the globally unique identity of a cell in E-UTRA, of the reference cell relative to which the RSTDs are provided. The target shall provide this IE if it knows the ECGI of the reference cell.
<b><i>earfcnRef</i></b>	This field specifies the E-UTRA carrier frequency of the reference cell used for the RSTD measurements. The target device shall include this field if the ARFCN used for RSTD measurements is not the same as the ARFCN of the reference cell provided in the OTDOA assistance data.
<b><i>referenceQuality</i></b>	This field specifies the target device's best estimate of the quality of the TOA measurement from the reference cell, $T_{\text{SubframeRxRef}}$ , where $T_{\text{SubframeRxRef}}$ is the time of arrival of the signal from the reference cell used to calculate the RSTD values.
<b><i>neighbourMeasurementList</i></b>	This list contains the measured RSTD values together with quality for the measurement.

<b>OTDOA-SignalMeasurementInformation field descriptions</b>
<p><b>physCellIdNeighbor</b> This field specifies the physical cell identity of the neighbour cell for which the RSTDs are provided.</p>
<p><b>cellGlobalIdNeighbour</b> This field specifies the ECGI, the globally unique identity of a cell in E-UTRA, of the neighbour cell for which the RSTDs are provided. The target device shall provide this IE if it was able to determine the ECGI of the neighbour cell at the time of measurement.</p>
<p><b>earfcnNeighbour</b> This field specifies the E-UTRA carrier frequency of the neighbour cell used for the RSTD measurements. The target device shall include this field if the ARFCN of this neighbor cell is not the same as the <i>earfcnRef</i> for the reference cell.</p>
<p><b>rstd</b> This field specifies the relative timing difference between this neighbour cell and the reference cell, as defined in [17]. Mapping of the measured quantity is defined as in [18] subclause 9.1.10.3.</p>
<p><b>rstd-Quality</b> This field specifies the target device's best estimate of the quality of the measured <i>rstd</i>.</p>

### OTDOA-MeasQuality

```

-- ASN1START
OTDOA-MeasQuality ::= SEQUENCE {
    error-Resolution      BIT STRING (SIZE (2)),
    error-Value          BIT STRING (SIZE (5)),
    error-NumSamples     BIT STRING (SIZE (3))          OPTIONAL,
    ...
}
-- ASN1STOP

```

<b>OTDOA-MeasQuality field descriptions</b>																
<p><b>error-Resolution</b> This field specifies the resolution R used in <i>error-Value</i> field. The encoding on two bits is as follows:</p> <table style="margin-left: 20px;"> <tr><td>'00'</td><td>5 meters</td></tr> <tr><td>'01'</td><td>10 meters</td></tr> <tr><td>'10'</td><td>20 meters</td></tr> <tr><td>'11'</td><td>30 meters.</td></tr> </table>	'00'	5 meters	'01'	10 meters	'10'	20 meters	'11'	30 meters.								
'00'	5 meters															
'01'	10 meters															
'10'	20 meters															
'11'	30 meters.															
<p><b>error-Value</b> This field specifies the target device's best estimate of the uncertainty of the OTDOA measurement. The encoding on five bits is as follows:</p> <table style="margin-left: 20px;"> <tr><td>'00000'</td><td>0</td><td>to (R*1-1) meters</td></tr> <tr><td>'00001'</td><td>R*1</td><td>to (R*2-1) meters</td></tr> <tr><td>'00010'</td><td>R*2</td><td>to (R*3-1) meters</td></tr> <tr><td>...</td><td></td><td></td></tr> <tr><td>'11111'</td><td>R*31</td><td>meters or more;</td></tr> </table> <p>where R is the resolution defined by <i>error-Resolution</i> field. E.g. , R=20 m corresponds to 0-19 m, 20-39 m, ..., 620+ m.</p>	'00000'	0	to (R*1-1) meters	'00001'	R*1	to (R*2-1) meters	'00010'	R*2	to (R*3-1) meters	...			'11111'	R*31	meters or more;	
'00000'	0	to (R*1-1) meters														
'00001'	R*1	to (R*2-1) meters														
'00010'	R*2	to (R*3-1) meters														
...																
'11111'	R*31	meters or more;														
<p><b>error-NumSamples</b> If the <i>error-Value</i> field provides the sample uncertainty of the OTDOA measurement, this field specifies how many measurements have been used by the target device to determine this (i.e., sample size). Following 3 bit encoding is used:</p> <table style="margin-left: 20px;"> <tr><td>'000'</td><td>Not the baseline metric</td></tr> <tr><td>'001'</td><td>5-9</td></tr> <tr><td>'010'</td><td>10-14</td></tr> <tr><td>'011'</td><td>15-24</td></tr> <tr><td>'100'</td><td>25-34</td></tr> <tr><td>'101'</td><td>35-44</td></tr> <tr><td>'110'</td><td>45-54</td></tr> <tr><td>'111'</td><td>55 or more.</td></tr> </table> <p>In case of the value '000', the <i>error-Value</i> field contains the target device's best estimate of the uncertainty of the OTDOA measurement not based on the baseline metric. E.g., other measurements such as signal-to-noise-ratio or signal strength can be utilized to estimate the <i>error-Value</i>. If this field is absent, the value of this field is '000'.</p>	'000'	Not the baseline metric	'001'	5-9	'010'	10-14	'011'	15-24	'100'	25-34	'101'	35-44	'110'	45-54	'111'	55 or more.
'000'	Not the baseline metric															
'001'	5-9															
'010'	10-14															
'011'	15-24															
'100'	25-34															
'101'	35-44															
'110'	45-54															
'111'	55 or more.															

### 6.5.1.6 OTDOA Location Information Request

#### – *OTDOA-RequestLocationInformation*

The IE *OTDOA-RequestLocationInformation* is used by the location server to request OTDOA location measurements from a target device. Details of the required measurements (e.g. details of reference cell and neighbour cells) are conveyed in the *OTDOA-ProvideAssistanceData* IE in a separate Provide Assistance Data message.

```
-- ASN1START
OTDOA-RequestLocationInformation ::= SEQUENCE {
    assistanceAvailability    BOOLEAN,
    ...
}
-- ASN1STOP
```

#### **OTDOA-RequestLocationInformation field descriptions**

##### ***assistanceAvailability***

This field indicates whether the target device may request additional OTDOA assistance data from the server. TRUE means allowed and FALSE means not allowed.

### 6.5.1.7 OTDOA Capability Information

#### – *OTDOA-ProvideCapabilities*

The IE *OTDOA-ProvideCapabilities* is used by the target device to indicate its capability to support OTDOA and to provide its OTDOA positioning capabilities to the location server.

```
-- ASN1START
OTDOA-ProvideCapabilities ::= SEQUENCE {
    otdoa-Mode    BIT STRING { ue-assisted (0) } (SIZE (1..8)),
    ...
}
-- ASN1STOP
```

#### **OTDOA-ProvideCapabilities field descriptions**

##### ***otdoa-Mode***

This field specifies the OTDOA mode(s) supported by the target device. This is represented by a bit string, with a one-value at the bit position means the particular OTDOA mode is supported; a zero-value means not supported. A zero-value in all bit positions in the bit string means OTDOA positioning method is not supported by the target device.

### 6.5.1.8 OTDOA Capability Information Request

#### – *OTDOA-RequestCapabilities*

The IE *OTDOA-RequestCapabilities* is used by the location server to request the capability of the target device to support OTDOA and to request OTDOA positioning capabilities from a target device.

```
-- ASN1START
OTDOA-RequestCapabilities ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

## 6.5.1.9 OTDOA Error Elements

### – *OTDOA-Error*

The IE *OTDOA-Error* is used by the location server or target device to provide OTDOA error reasons to the target device or location server, respectively.

```
-- ASN1START
OTDOA-Error ::= CHOICE {
    locationServerErrorCauses      OTDOA-LocationServerErrorCauses,
    targetDeviceErrorCauses       OTDOA-TargetDeviceErrorCauses,
    ...
}
-- ASN1STOP
```

### – *OTDOA-LocationServerErrorCauses*

The IE *OTDOA-LocationServerErrorCauses* is used by the location server to provide OTDOA error reasons to the target device.

```
-- ASN1START
OTDOA-LocationServerErrorCauses ::= SEQUENCE {
    cause      ENUMERATED {
        undefined,
        assistanceDataNotSupportedByServer,
        assistanceDataSupportedButCurrentlyNotAvailableByServer,
        ...
    },
    ...
}
-- ASN1STOP
```

### – *OTDOA-TargetDeviceErrorCauses*

The IE *OTDOA-TargetDeviceErrorCauses* is used by the target device to provide OTDOA error reasons to the location server.

```
-- ASN1START
OTDOA-TargetDeviceErrorCauses ::= SEQUENCE {
    cause      ENUMERATED {
        undefined,
        assistance-data-missing,
        unableToMeasureReferenceCell,
        unableToMeasureAnyNeighbourCell,
        attemptedButUnableToMeasureSomeNeighbourCells,
        ...
    },
    ...
}
-- ASN1STOP
```

## 6.5.2 A-GNSS Positioning

### 6.5.2.1 GNSS Assistance Data

#### – *A-GNSS-ProvideAssistanceData*

The IE *A-GNSS-ProvideAssistanceData* is used by the location server to provide assistance data to enable UE-based and UE-assisted A-GNSS. It may also be used to provide GNSS positioning specific error reasons.

```
-- ASN1START
```

```

A-GNSS-ProvideAssistanceData ::= SEQUENCE {
  gnss-CommonAssistData      GNSS-CommonAssistData      OPTIONAL, -- Need ON
  gnss-GenericAssistData     GNSS-GenericAssistData     OPTIONAL, -- Need ON
  gnss-Error                 A-GNSS-Error               OPTIONAL, -- Need ON
  ...
}
-- ASN1STOP

```

### – GNSS-CommonAssistData

The IE *GNSS-CommonAssistData* is used by the location server to provide assistance data which can be used for any GNSS (e.g., GPS, Galileo, GLONASS, etc.).

```

-- ASN1START
GNSS-CommonAssistData ::= SEQUENCE {
  gnss-ReferenceTime         GNSS-ReferenceTime         OPTIONAL, -- Need ON
  gnss-ReferenceLocation     GNSS-ReferenceLocation     OPTIONAL, -- Need ON
  gnss-IonosphericModel      GNSS-IonosphericModel      OPTIONAL, -- Need ON
  gnss-EarthOrientationParameters GNSS-EarthOrientationParameters OPTIONAL, -- Need ON
  ...
}
-- ASN1STOP

```

### – GNSS-GenericAssistData

The IE *GNSS-GenericAssistData* is used by the location server to provide assistance data for a specific GNSS (e.g., GPS, Galileo, GLONASS, etc.). The specific GNSS for which the provided assistance data are applicable is indicated by the IE *GNSS-ID* and (if applicable) by the IE *SBAS-ID*. Assistance for up to 16 GNSSs can be provided.

```

-- ASN1START
GNSS-GenericAssistData ::= SEQUENCE (SIZE (1..16)) OF GNSS-GenericAssistDataElement
GNSS-GenericAssistDataElement ::= SEQUENCE {
  gnss-ID                    GNSS-ID,
  sbas-ID                    SBAS-ID                    OPTIONAL, -- Cond GNSS-ID-SBAS
  gnss-TimeModels            GNSS-TimeModelList         OPTIONAL, -- Need ON
  gnss-DifferentialCorrections GNSS-DifferentialCorrections OPTIONAL, -- Need ON
  gnss-NavigationModel       GNSS-NavigationModel       OPTIONAL, -- Need ON
  gnss-RealTimeIntegrity     GNSS-RealTimeIntegrity   OPTIONAL, -- Need ON
  gnss-DataBitAssistance     GNSS-DataBitAssistance   OPTIONAL, -- Need ON
  gnss-AcquisitionAssistance GNSS-AcquisitionAssistance OPTIONAL, -- Need ON
  gnss-Almanac               GNSS-Almanac              OPTIONAL, -- Need ON
  gnss-UTC-Model             GNSS-UTC-Model            OPTIONAL, -- Need ON
  gnss-AuxiliaryInformation   GNSS-AuxiliaryInformation   OPTIONAL, -- Need ON
  ...
}
-- ASN1STOP

```

Conditional presence	Explanation
<i>GNSS-ID-SBAS</i>	The field is mandatory present if the <i>GNSS-ID</i> = <i>sbas</i> ; otherwise it is not present.

## 6.5.2.2 GNSS Assistance Data Elements

### – GNSS-ReferenceTime

The IE *GNSS-ReferenceTime* is used by the location server to provide the GNSS specific system time with uncertainty and the relationship between GNSS system time and network air-interface timing of the eNodeB/NodeB/BTS transmission in the reference cell.

If the IE *networkTime* is present, the IEs *gnss-SystemTime* and *networkTime* provide a valid relationship between GNSS system time and air-interface network time, as seen at the approximate location of the target device, i.e. the propagation delay from the the eNodeB/NodeB/BTS to the target device shall be compensated for by the location server. Depending on implementation, the relation between GNSS system time and air-interface network time may have varying accuracy. The uncertainty of this timing relation is provided in the IE *referenceTimeUnc*. If the propagation delay from the eNodeB/NodeB/BTS to the target device is not accurately known, the location server shall use the best available approximation of the propagation delay and take the corresponding delay uncertainty into account in the calculation of the IE *referenceTimeUnc*.

If the IE *networkTime* is not present, the IE *gnssSystemTime* is an estimate of current GNSS system time at time of reception of the IE *GNSS-ReferenceTime* by the target device. The location server should achieve an accuracy of +/- 3 seconds for this estimate including allowing for the transmission delay between the location server and the target device. Note that the target device should further compensate *gnss-SystemTime* for the time between the reception of *GNSS-ReferenceTime* and the time when the *gnss-SystemTime* is used.

The location server shall provide a value for the *gnss-TimeID* only for GNSSs supported by the target device.

The IE *GNSS-ReferenceTimeForOneCell* can be provided multiple times (up to 16) to provide fine time assistance for several (neighbour) cells.

```

-- ASN1START
GNSS-ReferenceTime ::= SEQUENCE {
    gnss-SystemTime      GNSS-SystemTime,
    referenceTimeUnc     INTEGER (0..127)                OPTIONAL,    -- Cond noFTA
    gnss-ReferenceTimeForCells SEQUENCE (SIZE (1..16)) OF
                        GNSS-ReferenceTimeForOneCell  OPTIONAL,    -- Need ON
    ...
}

GNSS-ReferenceTimeForOneCell ::= SEQUENCE {
    networkTime          NetworkTime,
    referenceTimeUnc     INTEGER (0..127),
    bsAlign              ENUMERATED {true}             OPTIONAL,
    ...
}
-- ASN1STOP
    
```

Conditional presence	Explanation
<i>noFTA</i>	The field may be present if <i>gnss-ReferenceTimeForCells</i> is absent; otherwise it is not present.

<b>GNSS-ReferenceTime field descriptions</b>	
<b><i>gnss-SystemTime</i></b>	This field provides the specific GNSS system time.
<b><i>networkTime</i></b>	This field specifies the cellular network time at the epoch corresponding to <i>gnss-SystemTime</i> .
<b><i>referenceTimeUnc</i></b>	<p>This field provides the accuracy of the relation between <i>gnssSystemTime</i> and <i>networkTime</i> time if IE <i>networkTime</i> is provided. When IE <i>networkTime</i> is not provided, this field can be included to provide the accuracy of the provided <i>gnssSystemTime</i>.</p> <p>If GNSS TOD is the given GNSS time, then the true GNSS time, corresponding to the provided network time as observed at the target device location, lies in the interval [GNSS TOD - <i>referenceTimeUnc</i>, GNSS TOD + <i>referenceTimeUnc</i>].</p> <p>The uncertainty <i>r</i>, expressed in microseconds, is mapped to a number <i>K</i>, with the following formula:</p> $r = C * (((1+x)^K) - 1)$ <p>with C = 0.5 and x = 0.14. To encode any higher value of uncertainty than that corresponding in the above formula to K=127, the same value, K=127, shall also be used. The uncertainty is then coded on 7 bits, as the binary encoding of K. Example values for the <i>referenceTimeUnc</i> Format: see table K to uncertainty relation below</p>



<b>GNSS-ReferenceTime field descriptions</b>
<p><b>bsAlign</b>                      This flag, if present, indicates that the transmission timings of all cells sharing, depending on the RAT, the same carrier frequency and Tracking Area/Location Area/Routing Area as the cell indicated, are frame aligned. This information allows the UE to derive the GNSS - cellular time relation for any of these cells based on the timing relation information provided in GNSS-ReferenceTime. The flag should be set consistently in all these cells. This flag does not guarantee SFN alignment.</p>

**K to uncertainty relation**

Value of K	Value of uncertainty
0	0 nanoseconds
1	70 nanoseconds
2	149.8 nanoseconds
-	-
50	349.62 microseconds
-	-
127	≥ 8.43 seconds

**GNSS-SystemTime**

```

-- ASN1START
GNSS-SystemTime ::= SEQUENCE {
    gnss-TimeID          GNSS-ID,
    gnss-DayNumber       INTEGER (0..32767),
    gnss-TimeOfDay       INTEGER (0..86399),
    gnss-TimeOfDayFrac-msec  INTEGER (0..999)    OPTIONAL, -- Need ON
    notificationOfLeapSecond  BIT STRING (SIZE(2))  OPTIONAL, -- Cond gnss-TimeID=glonass
    gps-TOW-Assist       GPS-TOW-Assist             OPTIONAL, -- Cond gnss-TimeID=gps
    ...
}
-- ASN1STOP
    
```

Conditional presence	Explanation
<i>gnss-TimeID=glonass</i>	The field may be present if <i>gnss-TimeID=glonass</i> ; otherwise it is not present.
<i>gnss-TimeID=gps</i>	The field may be present if <i>gnss-TimeID=gps</i> ; otherwise it is not present.

<b>GNSS-SystemTime field descriptions</b>
<p><b>gnss-TimeID</b>                      This field specifies the GNSS for which the <i>GNSS-SystemTime</i> is provided.</p>
<p><b>gnss-DayNumber</b>                      This field specifies the sequential number of days from the origin of the GNSS System Time as follows:                      GPS, QZSS, SBAS – Days from January 6<sup>th</sup> 1980 00:00:00 UTC(USNO);                      Galileo – TBD;                      GLONASS – Days from January 1<sup>st</sup> 1996.</p>
<p><b>gnss-TimeOfDay</b>                      This field specifies the integer number of seconds from the GNSS day change.</p>
<p><b>gnss-TimeOfDayFrac-msec</b>                      This field specifies the fractional part of the <i>gnssTimeOfDay</i> field in 1-milli-seconds resolution. The total GNSS TOD is <i>gnss-TimeOfDay + gnssTimeOfDayFrac-msec</i>.</p>
<p><b>notificationOfLeapSecond</b>                      This field specifies the notification of forthcoming leap second correction, as defined by parameter KP in [9, Table 4.7].</p>
<p><b>gps-TOW-Assist</b>                      This field contains several fields in the Telemetry (TLM) Word and Handover Word (HOW) that are currently being broadcast by the respective GPS satellites. Combining this information with GPS TOW enables the target device to know the entire 1.2-second (60-bit) pattern of TLM and HOW that is transmitted at the start of each six-second NAV subframe by the particular GPS satellite.</p>

## GPS-TOW-Assist

```
-- ASN1START
GPS-TOW-Assist ::= SEQUENCE (SIZE(1..64)) OF GPS-TOW-AssistElement
GPS-TOW-AssistElement ::= SEQUENCE {
    satelliteID      INTEGER (1..64),
    tlmWord          INTEGER (0..16383),
    antiSpooF        INTEGER (0..1),
    alert            INTEGER (0..1),
    tlmRsvdBits      INTEGER (0..3),
    ...
}
-- ASN1STOP
```

### GPS-TOW-Assist field descriptions

<b>satelliteID</b>	This field identifies the satellite for which the <i>GPS-TOW-Assist</i> is applicable. This field is identical to the GPS PRN Signal No. defined in [4].
<b>tlmWord</b>	This field contains a 14-bit value representing the Telemetry Message (TLM) being broadcast by the GPS satellite identified by the particular <i>satelliteID</i> , with the MSB occurring first in the satellite transmission, as defined in [4].
<b>antiSpooF</b>	This field contains the Anti-SpooF flag that is being broadcast by the GPS satellite identified by <i>satelliteID</i> , as defined in [1].
<b>alert</b>	This field contains the Alert flag that is being broadcast by the GPS satellite identified by <i>satelliteID</i> , as defined in [4].
<b>tlmRsvdBits</b>	This field contains the two reserved bits in the TLM Word being broadcast by the GPS satellite identified by <i>satelliteID</i> , with the MSB occurring first in the satellite transmission, as defined in [4].

## NetworkTime

```
-- ASN1START
NetworkTime ::= SEQUENCE {
    secondsFromFrameStructureStart      INTEGER(0..12533),
    fractionalSecondsFromFrameStructureStart  INTEGER(0..3999999),
    frameDrift      INTEGER (-64..63)      OPTIONAL, -- Cond GNSSsynch
    cellID          CHOICE {
        eUTRA      SEQUENCE {
            physCellId      INTEGER (0..503),
            cellGlobalIdEUTRA  CellGlobalIdEUTRA-AndUTRA  OPTIONAL, -- Need ON
            earfcn          ARFCN-ValueEUTRA,
            ...
        },
        uTRA      SEQUENCE {
            mode      CHOICE {
                fdd      SEQUENCE {
                    primary-CPICH-Info  INTEGER (0..511),
                    ...
                },
                tdd      SEQUENCE {
                    cellParameters      INTEGER (0..127),
                    ...
                }
            },
            cellGlobalIdUTRA  CellGlobalIdEUTRA-AndUTRA  OPTIONAL, -- Need ON
            uarfcn          ARFCN-ValueUTRA,
            ...
        },
        gSM      SEQUENCE {
            bcchCarrier      INTEGER (0..1023),
            bsic              INTEGER (0..63),
            cellGlobalIdGERAN  CellGlobalIdGERAN      OPTIONAL, -- Need ON
            ...
        },
        ...
    },
    ...
}
```

```

}
ARFCN-ValueUTRA ::= INTEGER (0..16383)
-- ASN1STOP

```

Conditional presence	Explanation
<i>GNSSsynch</i>	The field is present and set to 0 if <i>NetworkTime</i> is synchronized to <i>gnss-SystemTime</i> ; otherwise the field is optionally present, need OR.

<i>NetworkTime</i> field descriptions	
<b><i>secondsFromFrameStructureStart</i></b>	This field specifies the number of seconds from the beginning of the longest frame structure in the corresponding air interface. In case of E-UTRA, the SFN cycle length is 10.24 seconds. In case of UTRA, the SFN cycle length is 40.96 seconds. In case of GSM, the hyperframe length is 12533.76 seconds.
<b><i>fractionalSecondsFromFrameStructureStart</i></b>	This field specifies the fractional part of the <i>secondsFromFrameStructureStart</i> in 250 ns resolution. The total time since the particular frame structure start is <i>secondsFromFrameStructureStart</i> + <i>fractionalSecondsFromFrameStructureStart</i>
<b><i>frameDrift</i></b>	This field specifies the drift rate of the GNSS-network time relation with scale factor $2^{-30}$ seconds/second, in the range from $-5.9605e-8$ to $+5.8673e-8$ sec/sec.
<b><i>cellID</i></b>	This field specifies the cell for which the GNSS-network time relation is provided.
<b><i>physCellId</i></b>	This field specifies the physical cell identity of the reference cell (E-UTRA), as defined in [12], for which the GNSS network time relation is provided.
<b><i>cellGlobalIdEUTRA</i></b>	This field specifies the Evolved Cell Global Identifier (ECGI), the globally unique identity of a cell in E-UTRA, of the reference cell for the GNSS-network time relation, as defined in [12].
<b><i>primary-CPICH-Info</i></b>	This field specifies the physical cell identity of the reference cell (UTRA) for the GNSS-network time relation, as defined in [13].
<b><i>cellParameters</i></b>	This field specifies the physical cell identity of the reference cell (UTRA) for the GNSS-network time relation, as defined in [13].
<b><i>cellGlobalIdUTRA</i></b>	The field specifies the global UTRAN Cell Identifier, the globally unique identity of a cell in UTRA, of the reference cell for the GNSS-network time relation, as defined in [13].
<b><i>bcchCarrier</i></b>	This field specifies the absolute GSM RF channel number of the BCCH of the reference base station (GERAN) for the GNSS-network time relation, as defined in [14].
<b><i>bsic</i></b>	This field specifies the Base Station Identity Code of the reference base station (GERAN) for the GNSS-network time relation, as defined in [14].
<b><i>cellGlobalIdGERAN</i></b>	This field specifies the Cell Global Identification (CGI), the globally unique identity of a cell in GERAN, of the reference base station for the GNSS-network time relation.

## – *GNSS-ReferenceLocation*

The IE *GNSS-ReferenceLocation* is used by the location server to provide the target device with a-priori knowledge of its location in order to improve GNSS receiver performance. The IE *GNSS-ReferenceLocation* is provided in WGS-84 reference system.

```

-- ASN1START
GNSS-ReferenceLocation ::= SEQUENCE {
    threeDlocation      EllipsoidPointWithAltitudeAndUncertaintyEllipsoid,
    ...
}
-- ASN1STOP

```

## – GNSS-IonosphericModel

The IE *GNSS-IonosphericModel* is used by the location server to provide parameters to model the propagation delay of the GNSS signals through the ionosphere. Proper use of these fields allows a single-frequency GNSS receiver to remove parts of the ionospheric delay from the pseudorange measurements. Two Ionospheric Models are supported: The Klobuchar model as defined in [4], and the NeQuick model as defined in [8].

```
-- ASN1START
GNSS-IonosphericModel ::= SEQUENCE {
    klobucharModel      KlobucharModelParameter      OPTIONAL,    -- Need ON
    neQuickModel        NeQuickModelParameter        OPTIONAL,    -- Need ON
    ...
}
-- ASN1STOP
```

## – KlobucharModelParameter

```
-- ASN1START
KlobucharModelParameter ::= SEQUENCE {
    dataID              BIT STRING (SIZE (2)),
    alfa0               INTEGER (-128..127),
    alfa1               INTEGER (-128..127),
    alfa2               INTEGER (-128..127),
    alfa3               INTEGER (-128..127),
    beta0               INTEGER (-128..127),
    beta1               INTEGER (-128..127),
    beta2               INTEGER (-128..127),
    beta3               INTEGER (-128..127),
    ...
}
-- ASN1STOP
```

### ***KlobucharModelParameter* field descriptions**

<b><i>dataID</i></b>	When <i>dataID</i> has the value '11' it indicates that the parameters have been generated by QZSS, and the parameters have been specialized and are applicable within the area defined in [7]. When <i>dataID</i> has the value '00' it indicates the parameters are applicable worldwide [4,7]. All other values for <i>dataID</i> are reserved.
<b><i>alpha0</i></b>	This field specifies the $\alpha_0$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{30}$ seconds.
<b><i>alpha1</i></b>	This field specifies the $\alpha_1$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{27}$ seconds/semi-circle.
<b><i>alpha2</i></b>	This field specifies the $\alpha_2$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{24}$ seconds/semi-circle <sup>2</sup> .
<b><i>alpha3</i></b>	This field specifies the $\alpha_3$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{24}$ seconds/semi-circle <sup>3</sup> .
<b><i>beta0</i></b>	This field specifies the $\beta_0$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{11}$ seconds.
<b><i>beta1</i></b>	This field specifies the $\beta_1$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{14}$ seconds/semi-circle.
<b><i>beta2</i></b>	This field specifies the $\beta_2$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{16}$ seconds/semi-circle <sup>2</sup> .
<b><i>beta3</i></b>	This field specifies the $\beta_3$ parameter of the Klobuchar model, as specified in [4]. Scale factor $2^{16}$ seconds/semi-circle <sup>3</sup> .

– *NeQuickModelParameter*

```
-- ASN1START
NeQuickModelParameter ::= SEQUENCE {
    ai0          INTEGER (0..4095),
    ai1          INTEGER (0..4095),
    ai2          INTEGER (0..4095),
    ionoStormFlag1  INTEGER (0..1)    OPTIONAL,  -- Need OP
    ionoStormFlag2  INTEGER (0..1)    OPTIONAL,  -- Need OP
    ionoStormFlag3  INTEGER (0..1)    OPTIONAL,  -- Need OP
    ionoStormFlag4  INTEGER (0..1)    OPTIONAL,  -- Need OP
    ionoStormFlag5  INTEGER (0..1)    OPTIONAL,  -- Need OP
    ...
}
-- ASN1STOP
```

<i>NeQuickModelParameter</i> field descriptions
<b>ai0, ai1, ai2</b> These fields are used to estimate the ionospheric distortions on pseudoranges as described in [8] on page 71.
<b>ionoStormFlag1, ionoStormFlag2, ionoStormFlag3, ionoStormFlag4, ionoStormFlag5</b> These fields specify the ionosphere storm flags (1,...,5) for five different regions as described in [8] on page 71. If the ionosphere storm flag for a region is not present the target device shall treat the ionosphere storm condition as unknown.

– *GNSS-EarthOrientationParameters*

The IE *GNSS-EarthOrientationParameters* is used by the location server to provide parameters to construct the ECEF and ECI coordinate transformation as defined in [4]. The IE *GNSS-EarthOrientationParameters* indicates the relationship between the Earth's rotational axis and WGS-84 reference system.

```
-- ASN1START
GNSS-EarthOrientationParameters ::= SEQUENCE {
    teop          INTEGER (0..65535),
    pmX           INTEGER (-1048576..1048575),
    pmXdot        INTEGER (-16384..16383),
    pmY           INTEGER (-1048576..1048575),
    pmYdot        INTEGER (-16384..16383),
    deltaUT1      INTEGER (-1073741824..1073741823),
    deltaUT1dot   INTEGER (-262144..262143),
    ...
}
-- ASN1STOP
```

<i>GNSS-EarthOrientationParameters</i> field descriptions
<b>teop</b> This field specifies the EOP data reference time in seconds, as specified in [4]. Scale factor $2^4$ seconds.
<b>pmX</b> This field specifies the X-axis polar motion value at reference time in arc-seconds, as specified in [4]. Scale factor $2^{20}$ arc-seconds.
<b>pmXdot</b> This field specifies the X-axis polar motion drift at reference time in arc-seconds/day, as specified in [4]. Scale factor $2^{21}$ arc-seconds/day.
<b>pmY</b> This field specifies the Y-axis polar motion value at reference time in arc-seconds, as specified in [4]. Scale factor $2^{20}$ arc-seconds.
<b>pmYdot</b> This field specifies the Y-axis polar motion drift at reference time in arc-seconds/day, as specified in [4]. Scale factor $2^{21}$ arc-seconds/day.

<b>GNSS-EarthOrientationParameters field descriptions</b>
<p><b>deltaUT1</b> This field specifies the UT1-UTC difference at reference time in seconds, as specified in [4]. Scale factor <math>2^{-24}</math> seconds.</p>
<p><b>deltaUT1dot</b> This field specifies the Rate of UT1-UTC difference at reference time in seconds/day, as specified in [4]. Scale factor <math>2^{-25}</math> seconds/day.</p>

### – GNSS-TimeModelList

The IE *GNSS-TimeModelList* is used by the location server to provide the GNSS-GNSS system time offset between the GNSS system time indicated by IE *GNSS-ID* in IE *GNSS-GenericAssistDataElement* to the GNSS system time indicated by IE *gnss-TO-ID*. Several *GNSS-TimeModelElement* IEs can be included with different *gnss-TO-ID* fields.

```
-- ASN1START
GNSS-TimeModelList ::= SEQUENCE (SIZE (1..15)) OF GNSS-TimeModelElement

GNSS-TimeModelElement ::= SEQUENCE {
    gnss-TimeModelRefTime    INTEGER (0..65535),
    tA0                      INTEGER (-67108864..67108863),
    tA1                      INTEGER (-4096..4095)                OPTIONAL,    -- Need ON
    tA2                      INTEGER (-64..63)                   OPTIONAL,    -- Need ON
    gnss-TO-ID               INTEGER (1..15),
    weekNumber               INTEGER (0..8191)                   OPTIONAL,    -- Need ON
    deltaT                   INTEGER (-128..127)                OPTIONAL,    -- Need ON
    ...
}
-- ASN1STOP
```

<b>GNSS-TimeModelElement field descriptions</b>
<p><b>gnss-TimeModelRefTime</b> This field specifies the the reference time of week for <i>GNSSTimeModelElement</i> and it is given in GNSS specific system time. Scale factor <math>2^4</math> seconds.</p>
<p><b>tA0</b> This field specifies the bias coefficient of the <i>GNSSTimeModelElement</i>. Scale factor <math>2^{-35}</math> seconds.</p>
<p><b>tA1</b> This field specifies the drift coefficient of the <i>GNSSTimeModelElement</i>. Scale factor of <math>2^{-51}</math> seconds/second.</p>
<p><b>tA2</b> This field specifies the drift rate correction coefficient of the <i>GNSSTimeModelElement</i>. Scale factor of <math>2^{-68}</math> seconds/second<sup>2</sup>.</p>
<p><b>gnss-TO-ID</b> This field specifies the GNSS system time of the GNSS for which the <i>GNSS-TimeModelElement</i> is applicable. <i>GNSS-TimeModelElement</i> contains parameters to convert GNSS system time from the system indicated by <i>GNSS-ID</i> to GNSS system time indicated by <i>gnss-TO-ID</i>. The conversion is defined in [4,5,6]. See table of <i>gnss-TO-ID</i> to Indication relation below.</p>
<p><b>weekNumber</b> This field specifies the reference week of the <i>GNSS-TimeModelElement</i> given in GNSS specific system time. Scale factor 1 week.</p>
<p><b>deltaT</b> This field specifies the integer number of seconds of the GNSS-GNSS time offset provided in the <i>GNSS-TimeModelElement</i>. Scale factor 1 second.</p>

#### gnss-TO-ID to Indication relation

Value of <i>gnss-TOID</i>	Indication
1	GPS
2	Galileo

3	QZSS
4	GLONASS
5-15	reserved

**GNSS-DifferentialCorrections**

The IE *GNSS-DifferentialCorrections* is used by the location server to provide differential GNSS corrections to the target device for a specific GNSS. Differential corrections can be provided for up to 3 signals per GNSS.

```

-- ASN1START
GNSS-DifferentialCorrections ::= SEQUENCE {
    dgnss-RefTime      INTEGER (0..3599),
    dgnss-SgnTypeList  DGNSS-SgnTypeList,
    ...
}

DGNSS-SgnTypeList ::= SEQUENCE (SIZE (1..3)) OF DGNSS-SgnTypeElement

DGNSS-SgnTypeElement ::= SEQUENCE {
    gnss-SignalID      GNSS-SignalID,
    gnss-StatusHealth  INTEGER (0..7),
    dgnss-SatList      DGNSS-SatList,
    ...
}

DGNSS-SatList ::= SEQUENCE (SIZE (1..64)) OF DGNSS-CorrectionsElement

DGNSS-CorrectionsElement ::= SEQUENCE {
    svID              SV-ID,
    iod               BIT STRING (SIZE(11)),
    udre              INTEGER (0..3),
    pseudoRangeCor    INTEGER (-2047..2047),
    rangeRateCor      INTEGER (-127..127),
    udreGrowthRate    INTEGER (0..7)          OPTIONAL,  -- Need ON
    udreValidityTime  INTEGER (0..7)          OPTIONAL,  -- Need ON
    ...
}
-- ASN1STOP

```

**GNSS-DifferentialCorrections field descriptions**

***dgnss-RefTime***

This field specifies the time for which the DGNSS corrections are valid, modulo 1 hour. *dgnss-RefTime* is given in GNSS specific system time.  
Scale factor 1-second.

***dgnss-SgnTypeList***

This list includes differential correction data for different GNSS signal types, identified by *GNSS-SignalID*.

***gnss-StatusHealth***

This field specifies the status of the differential corrections. The values of this field and their respective meanings are defined as in table *gnss-StatusHealth Value to Indication relation below*.

The first six values in this field indicate valid differential corrections. When using the values described below, the "UDRE Scale Factor" value is applied to the UDRE values contained in the element. The purpose is to indicate an estimate in the amount of error in the corrections.

The value "110" indicates that the source of the differential corrections (e.g., reference station or external DGNSS network) is currently not being monitored. The value "111" indicates that the corrections provided by the source are invalid, as judged by the source.

***dgnss-SatList***

This list includes differential correction data for different GNSS satellites, identified by *SV-ID*.

***iod***

This field specifies the Issue of Data field which contains the identity for the *GNSS-NavigationModel*.

***udre***

This field provides an estimate of the uncertainty (1-σ) in the corrections for the particular satellite. The value in this field shall be multiplied by the UDRE Scale Factor in the *gnss-StatusHealth* field to determine the final UDRE estimate for the particular satellite. The meanings of the values for this field are shown in the table *udre Value to Indication relation below*.

<b>GNSS-DifferentialCorrections field descriptions</b>	
<p><b>pseudoRangeCor</b>                      This field specifies the correction to the pseudorange for the particular satellite at <i>dgnss-RefTime</i>, <math>t_0</math>. The value of this field is given in meters and the scale factor is 0.32 meters in the range of <math>\pm 655.04</math> meters. The method of calculating this field is described in [11].                      If the location server has received a request for GNSS assistance data from a target device which included a request for the GNSS Navigation Model and DGNSS, the location server shall determine, for each satellite, if the navigation model stored by the target device is still suitable for use with DGNSS corrections and if so and if DGNSS corrections are supported the location server should send DGNSS corrections without including the GNSS Navigation Model. The <i>iod</i> value sent for a satellite shall always be the IOD value that corresponds to the navigation model for which the pseudo-range corrections are applicable.                      The target device shall only use the <i>pseudoRangeCor</i> value when the IOD value received matches its available navigation model.                      Pseudo-range corrections are provided with respect to GNSS specific geodetic datum (e.g., PZ-90.02 if <i>GNSS-ID</i> indicates GLONASS).                      Scale factor 0.32 meters.</p>	
<p><b>rangeRateCor</b>                      This field specifies the rate-of-change of the pseudorange correction for the particular satellite, using the satellite ephemeris and clock corrections identified by the <i>iod</i> field. The value of this field is given in meters per second and the resolution is 0.032 meters/sec in the range of <math>\pm 4.064</math> meters/sec. For some time <math>t_1 &gt; t_0</math>, the corrections for <i>iod</i> are estimated by  <math display="block">PRC(t_1, IOD) = PRC(t_0, IOD) + RRC(t_0, IOD) \cdot (t_1 - t_0)</math>                     , and the target device uses this to correct the pseudorange it measures at <math>t_1</math>, <math>PR_m(t_1, IOD)</math>, by  <math display="block">PR(t_1, IOD) = PR_m(t_1, IOD) + PRC(t_1, IOD)</math>                     .                      The location server shall always send the RRC value that corresponds to the PRC value that it sends. The target device shall only use the RRC value when the <i>iod</i> value received matches its available navigation model.                      Scale factor 0.032 meters/second.</p>	
<p><b>udreGrowthRate</b>                      This field provides an estimate of the growth rate of uncertainty (<math>1-\sigma</math>) in the corrections for the particular satellite identified by <i>SV-ID</i>. The estimated UDRE at time value specified in the <i>udreValidityTime</i> <math>t_1</math> is calculated as follows:  <math display="block">UDRE(t_0+t_1) = UDRE(t_0) \times udreGrowthRate</math>                     , where <math>t_0</math> is the DGNSS Reference Time <i>dgnss-RefTime</i> for which the corrections are valid, <math>t_1</math> is the <i>udreValidityTime</i> field, <math>UDRE(t_0)</math> is the value of the <i>udre</i> field, and <i>udreGrowthRate</i> field is the factor as shown in the table Value of <i>udreGrowthRate</i> to Indication relation below.</p>	
<p><b>udreValidityTime</b>                      This field specifies the time when the <i>udreGrowthRate</i> field applies and is included if <i>udreGrowthRate</i> is included. The meaning of the values for this field is as shown in the table Value of <i>udreValidityTime</i> to Indication relation below.</p>	

**gnss-StatusHealth Value to Indication relation**

<b>gnss-StatusHealth Value</b>	<b>Indication</b>
000	UDRE Scale Factor = 1.0
001	UDRE Scale Factor = 0.75
010	UDRE Scale Factor = 0.5
011	UDRE Scale Factor = 0.3
100	UDRE Scale Factor = 0.2
101	UDRE Scale Factor = 0.1
110	Reference Station Transmission Not Monitored
111	Data is invalid - disregard

**udre Value to Indication relation**

<b>udre Value</b>	<b>Indication</b>
00	UDRE $\leq$ 1.0 m
01	1.0 m < UDRE $\leq$ 4.0 m
10	4.0 m < UDRE $\leq$ 8.0 m
11	8.0 m < UDRE

**Value of udreGrowthRate to Indication relation**

<b>Value of udreGrowthRate</b>	<b>Indication</b>
000	1.5



001	2
010	4
011	6
100	8
101	10
110	12
111	16

### Value of *udreValidityTime* to Indication relation

Value of <i>udreValidityTime</i>	Indication [seconds]
000	20
001	40
010	80
011	160
100	320
101	640
110	1280
111	2560

## – GNSS-*NavigationModel*

The IE *GNSS-NavigationModel* is used by the location server to provide precise navigation data to the GNSS capable target device. In response to a request from a target device for GNSS Assistance Data, the location server shall determine whether to send the navigation model for a particular satellite to a target device based upon factors like the T-Toe limit specified by the target device and any request from the target device for DGNSS (see also *GNSS-DifferentialCorrections*). GNSS Orbit Model can be given in Keplerian parameters or as state vector in Earth-Centered Earth-Fixed coordinates, dependent on the *GNSS-ID* and the target device capabilities. The meaning of these parameters is defined in relevant ICDs of the particular GNSS and GNSS specific interpretations apply. For example, GPS and QZSS use the same model parameters but some parameters have a different interpretation [7].

```
-- ASN1START

GNSS-NavigationModel ::= SEQUENCE {
    nonBroadcastIndFlag    INTEGER (0..1),
    gnss-SatelliteList     GNSS-NavModelSatelliteList,
    ...
}

GNSS-NavModelSatelliteList ::= SEQUENCE (SIZE(1..64)) OF GNSS-NavModelSatelliteElement

GNSS-NavModelSatelliteElement ::= SEQUENCE {
    svID                   SV-ID,
    svHealth               BIT STRING (SIZE(8)),
    iod                    BIT STRING (SIZE(11)),
    gnss-ClockModel        GNSS-ClockModel,
    gnss-OrbitModel        GNSS-OrbitModel,
    ...
}

GNSS-ClockModel ::= CHOICE {
    standardClockModelList StandardClockModelList,      -- Model-1
    nav-ClockModel         NAV-ClockModel,              -- Model-2
    cnav-ClockModel        CNAV-ClockModel,             -- Model-3
    glonass-ClockModel     GLONASS-ClockModel,         -- Model-4
    sbas-ClockModel        SBAS-ClockModel,             -- Model-5
    ...
}

GNSS-OrbitModel ::= CHOICE {
    keplerianSet           NavModelKeplerianSet,        -- Model-1
    nav-KeplerianSet       NavModelNAV-KeplerianSet,   -- Model-2
    cnav-KeplerianSet      NavModelCNAV-KeplerianSet,  -- Model-3
    glonass-ECEF           NavModel-GLONASS-ECEF,     -- Model-4
    sbas-ECEF              NavModel-SBAS-ECEF,         -- Model-5
    ...
}
-- ASN1END
```

-- ASN1STOP

<b>GNSS-<i>NavigationModel</i> field descriptions</b>	
<b><i>nonBroadcastIndFlag</i></b>	This field indicates if the <i>GNSS-NavigationModel</i> elements are not derived from satellite broadcast data or are given in a format not native to the GNSS. A value of 0 means the <i>GNSS-NavigationModel</i> data elements correspond to GNSS satellite broadcasted data; a value of 1 means the <i>GNSS-NavigationModel</i> data elements are not derived from satellite broadcast.
<b><i>gnss-SatelliteList</i></b>	This list provides ephemeris and clock corrections for GNSS satellites indicated by <i>SV-ID</i> .
<b><i>svHealth</i></b>	This field specifies the satellite's current health. The health values are GNSS system specific. The interpretation of <i>svHealth</i> depends on the <i>GNSS-ID</i> and is as shown in table GNSS to <i>svHealth</i> Bit String(8) relation below.
<b><i>iod</i></b>	This field specifies the Issue of Data and contains the identity for GNSS Navigation Model. In case of broadcasted GPS NAV ephemeris, the <i>iod</i> contains the IODC as described in [4]. In case of broadcasted Modernized GPS ephemeris, the <i>iod</i> contains the 11-bit parameter $t_{oe}$ as defined in [4, Table 30-I] [6, Table 3.5-1]. In case of broadcasted SBAS ephemeris, the <i>iod</i> contains the 8 bits Issue of Data as defined in [10] Message Type 9. In case of broadcasted QZSS QZS-L1 ephemeris, the <i>iod</i> contains the IODC as described in [7]. In case of broadcasted QZSS QZS-L1C/L2C/L5 ephemeris, the <i>iod</i> contains the 11-bit parameter $t_{oe}$ as defined in [7]. In case of broadcasted GLONASS ephemeris, the <i>iod</i> contains the parameter $t_b$ as defined in [9]. In the case of broadcasted Galileo ephemeris, the <i>iod</i> contains the IOD index as described in [8]. The interpretation of <i>iod</i> depends on the <i>GNSS-ID</i> and is as shown in table GNSS to <i>iod</i> Bit String(11) relation below.

**GNSS to *svHealth* Bit String(8) relation**

GNSS	<i>svHealth</i> Bit String(8)							
	Bit 1 (MSB)	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8 (LSB)
GPS L1/CA <sup>(1)</sup>	SV Health [4]						'0' (reserved)	'0' (reserved)
Modernized GPS <sup>(2)</sup>	L1C Health [6]	L1 Health [4,5]	L2 Health [4,5]	L5 Health [4,5]	'0' (reserved)	'0' (reserved)	'0' (reserved)	'0' (reserved)
SBAS <sup>(3)</sup>	Ranging On (0), Off(1) [10]	Corrections On(0), Off(1) [10]	Integrity On(0), Off(1) [10]	'0' (reserved)	'0' (reserved)	'0' (reserved)	'0' (reserved)	'0' (reserved)
QZSS <sup>(4)</sup> QZS-L1	SV Health [7]						'0' (reserved)	'0' (reserved)
QZSS <sup>(5)</sup> QZS-L1C/L2C/L5	L1C Health [7]	L1 Health [7]	L2 Health [7]	L5 Health [7]	'0' (reserved)	'0' (reserved)	'0' (reserved)	'0' (reserved)
GLONASS	$B_n$ (MSB) [9, page 30]	$F_T$ [9, Table 4.4]				'0' (reserved)	'0' (reserved)	'0' (reserved)
Galileo [5, pages 75-76]	E5a Data Validity Status	E5b Data Validity Status	E1-B Data Validity Status	E5a Signal Health Status See [8], Table 67		'0' (reserved)	'0' (reserved)	'0' (reserved)
Note 1: If <i>GNSS-ID</i> indicates 'gps', and GNSS Orbit Model-2 is included, this interpretation of <i>svHealth</i> applies. Note 2: If <i>GNSS-ID</i> indicates 'gps', and GNSS Orbit Model-3 is included, this interpretation of <i>svHealth</i> applies. If a certain signal is not supported on the satellite indicated by <i>SV-ID</i> , the corresponding health bit shall be set to '1' (i.e., signal can not be used). Note 3: <i>svHealth</i> in case of <i>GNSS-ID</i> indicates 'sbas' includes the 5 LSBs of the Health included in GEO Almanac Message Parameters (Type 17) [10]. Note 4: If <i>GNSS-ID</i> indicates 'qzss', and GNSS Orbit Model-2 is included, this interpretation of <i>svHealth</i> applies. Note 5: If <i>GNSS-ID</i> indicates 'qzss', and GNSS Orbit Model-3 is included, this interpretation of <i>svHealth</i> applies.								

**GNSS to *iod* Bit String(11) relation**

GNSS	<i>iod</i> Bit String(11)										
	Bit 1 (MSB)	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8	Bit 9	Bit 10	Bit 11 (LSB)
GPS L1/CA	'0'	Issue of Data, Clock [4]									
Modernized GPS	$t_{oe}$ (seconds, scale factor 300, range 0 – 604500) [4,5,6]										
SBAS	'0'	'0'	'0'	Issue of Data ([10], Message Type 9)							
QZSS QZS-L1	'0'	Issue of Data, Clock [7]									
QZSS	$t_{oe}$ (seconds, scale factor 300, range 0 – 604500) [4]										

QZS-L1C/L2C/L5					
GLONASS	'0'	'0'	'0'	'0'	$t_b$ (minutes, scale factor 15, range 0 – 1425) [9]
Galileo	'0'				IOD [8]

**StandardClockModelList**

```

-- ASN1START
StandardClockModelList ::= SEQUENCE (SIZE(1..2)) OF StandardClockModelElement
StandardClockModelElement ::= SEQUENCE {
    stanClockToc      INTEGER (0..16383),
    stanClockAF2     INTEGER (-2048..2047),
    stanClockAF1     INTEGER (-131072..131071),
    stanClockAF0     INTEGER (-134217728..134217727),
    stanClockTgd     INTEGER (-512..511)           OPTIONAL, -- Need ON
    stanModelID      INTEGER (0..1)               OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP
    
```

**StandardClockModelList field descriptions**

<p><b>standardClockModelList</b>  <i>gnss-ClockModel</i> Model-1 contains one or two clock model elements depending on the GNSS. If included, clock Model-1 shall be included once or twice depending on the target device capability.                  If the target device is supporting multiple Galileo signals, the location server shall include both F/Nav and I/Nav clock models in <i>gnss-ClockModel</i> if the location server assumes the target device to perform location information calculation using multiple signals.</p>
<p><b>stanClockToc</b>                  Parameter <math>t_{oc}</math> defined in [8].                  Scale factor 60 seconds.</p>
<p><b>stanClockAF2</b>                  Parameter <math>a_2</math> defined in [8].                  Scale factor <math>2^{-65}</math> seconds/second<sup>2</sup>.</p>
<p><b>stanClockAF1</b>                  Parameter <math>a_1</math> defined in [8].                  Scale factor <math>2^{-45}</math> seconds/second.</p>
<p><b>stanClockAF0</b>                  Parameter <math>a_0</math> defined in [8].                  Scale factor <math>2^{-33}</math> seconds.</p>
<p><b>stanClockTgd</b>                  Parameter <math>T_{GD}</math> defined in [8].                  Scale factor <math>2^{-32}</math> seconds.                  This field is required if the target device supports only single frequency Galileo signal.</p>
<p><b>stanModelID</b>                  This field specifies the identity of the clock model according to the table Value of stanModelID to Identity relation below. This field is required if the location server includes both F/Nav and I/Nav Galileo clock models in <i>gnss-ClockModel</i>.</p>

**Value of stanModelID to Identity relation**

Value of stanModelID	Identity
0	I/Nav
1	F/Nav

**NAV-ClockModel**

```

-- ASN1START
NAV-ClockModel ::= SEQUENCE {
    navToc      INTEGER (0..37799),
    navaf2     INTEGER (-128..127),
}
    
```

```

    navaf1      INTEGER (-32768..32767),
    navaf0      INTEGER (-2097152..2097151),
    navTgd      INTEGER (-128..127),
    ...
}
-- ASN1STOP

```

#### NAV-ClockModel field descriptions

<p><b>navToc</b> Parameter <math>t_{oc}</math>, time of clock (seconds) [4,7]. Scale factor <math>2^4</math> seconds.</p>
<p><b>navaf2</b> Parameter <math>a_{i2}</math>, clock correction polynomial coefficient (sec/sec<sup>2</sup>) [4,7]. Scale factor <math>2^{-55}</math> seconds/second<sup>2</sup>.</p>
<p><b>navaf1</b> Parameter <math>a_{i1}</math>, clock correction polynomial coefficient (sec/sec) [4,7]. Scale factor <math>2^{43}</math> seconds/second.</p>
<p><b>navaf0</b> Parameter <math>a_{i0}</math>, clock correction polynomial coefficient (seconds) [4,7]. Scale factor <math>2^{-31}</math> seconds.</p>
<p><b>navTgd</b> Parameter <math>T_{GD}</math>, group delay (seconds) [4,7]. Scale factor <math>2^{-31}</math> seconds.</p>

#### CNAV-ClockModel

```

-- ASN1START
CNAV-ClockModel ::= SEQUENCE {
    cnavToc      INTEGER (0..2015),
    cnavTop      INTEGER (0..2015),
    cnavURA0    INTEGER (-16..15),
    cnavURA1    INTEGER (0..7),
    cnavURA2    INTEGER (0..7),
    cnavAf2      INTEGER (-512..511),
    cnavAf1      INTEGER (-524288..524287),
    cnavAf0      INTEGER (-33554432..33554431),
    cnavTgd      INTEGER (-4096..4095),
    cnavISCl1cp  INTEGER (-4096..4095)          OPTIONAL, -- Need ON
    cnavISCl1cd  INTEGER (-4096..4095)          OPTIONAL, -- Need ON
    cnavISCl1ca  INTEGER (-4096..4095)          OPTIONAL, -- Need ON
    cnavISCl2c   INTEGER (-4096..4095)          OPTIONAL, -- Need ON
    cnavISCl5i5  INTEGER (-4096..4095)          OPTIONAL, -- Need ON
    cnavISCl5q5  INTEGER (-4096..4095)          OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP

```

#### CNAV-ClockModel field descriptions

<p><b>cnavToc</b> Parameter <math>t_{oc}</math>, clock data reference time of week (seconds) [4,5,6,7][1, 2, 3, 4]. Scale factor 300 seconds.</p>
<p><b>cnavTop</b> Parameter <math>t_{op}</math>, clock data predict time of week (seconds) [4,5,6,7]. Scale factor 300 seconds</p>
<p><b>cnavURA0</b> Parameter <math>URA_{oc}</math> Index, SV clock accuracy index (dimensionless) [4,5,6,7].</p>
<p><b>cnavURA1</b> Parameter <math>URA_{oc1}</math> Index, SV clock accuracy change index (dimensionless) [4,5,6,7].</p>
<p><b>cnavURA2</b> Parameter <math>URA_{oc2}</math> Index, SV clock accuracy change rate index (dimensionless) [4,5,6,7].</p>
<p><b>cnavAf2</b> Parameter <math>a_{i2-n}</math>, SV clock drift rate correction coefficient (sec/sec<sup>2</sup>) [4,5,6,7]. Scale factor <math>2^{-60}</math> seconds/second<sup>2</sup>.</p>

<b>CNAV-ClockModel field descriptions</b>
<p><b><i>cnavAf1</i></b> Parameter <math>a_{r1-n1}</math>, SV clock drift correction coefficient (sec/sec) [4,5,6,7]. Scale factor <math>2^{-48}</math> seconds/second.</p>
<p><b><i>cnavAf0</i></b> Parameter <math>a_{r0-n1}</math>, SV clock bias correction coefficient (seconds) [4,5,6,7]. Scale factor <math>2^{-35}</math> seconds.</p>
<p><b><i>cnavTgd</i></b> Parameter <math>T_{GD}</math>, Group delay correction (seconds) [4,5,6,7]. Scale factor <math>2^{-35}</math> seconds.</p>
<p><b><i>cnavISCI1cp</i></b> Parameter <math>ISC_{L1CP}</math>, inter signal group delay correction (seconds) [6,7]. Scale factor <math>2^{-35}</math> seconds. The location server includes this field if the target device is GPS capable and supports the L1<sub>CP</sub> signal.</p>
<p><b><i>cnavISCI1cd</i></b> Parameter <math>ISC_{L1CD}</math>, inter signal group delay correction (seconds) [6,7]. Scale factor <math>2^{-35}</math> seconds. The location server includes this field if the target device is GPS capable and supports the L1<sub>CD</sub> signal.</p>
<p><b><i>cnavISCI1ca</i></b> Parameter <math>ISC_{L1CA}</math>, inter signal group delay correction (seconds) [4,5,7]. Scale factor <math>2^{-35}</math> seconds. The location server includes this field if the target device is GPS capable and supports the L1<sub>CA</sub> signal.</p>
<p><b><i>cnavISCI2c</i></b> Parameter <math>ISC_{L2C}</math>, inter signal group delay correction (seconds) [4,5,7]. Scale factor <math>2^{-35}</math> seconds. The location server includes this field if the target device is GPS capable and supports the L2<sub>C</sub> signal.</p>
<p><b><i>cnavISCI5i5</i></b> Parameter <math>ISC_{L5i5}</math>, inter signal group delay correction (seconds) [5,7]. Scale factor <math>2^{-35}</math> seconds. The location server includes this field if the target device is GPS capable and supports the L5 signal.</p>
<p><b><i>cnavISCI5q5</i></b> Parameter <math>ISC_{L5Q5}</math>, inter signal group delay correction (seconds) [5,7]. Scale factor <math>2^{-35}</math> seconds. The location server includes this field if the target device is GPS capable and supports the L5 signal.</p>

### — *GLONASS-ClockModel*

```
-- ASN1START
GLONASS-ClockModel ::= SEQUENCE {
    gloTau          INTEGER (-2097152..2097151),
    gloGamma        INTEGER (-1024..1023),
    gloDeltaTau     INTEGER (-16..15)           OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP
```

<b>GLONASS-ClockModel field descriptions</b>
<p><b><i>gloTau</i></b> Parameter <math>\tau_n(t_b)</math>, satellite clock offset (seconds) [9]. Scale factor <math>2^{-30}</math> seconds.</p>
<p><b><i>gloGamma</i></b> Parameter <math>\gamma_n(t_b)</math>, relative frequency offset from nominal value (dimensionless) [9]. Scale factor <math>2^{-40}</math>.</p>
<p><b><i>gloDeltaTau</i></b> Parameter <math>\Delta\tau_n</math>, time difference between transmission in G2 and G1 (seconds) [9]. Scale factor <math>2^{-30}</math> seconds. The location server includes this parameter if the target device is dual frequency GLONASS receiver capable; otherwise it is not present.</p>

### — *SBAS-ClockModel*

```
-- ASN1START
```

```

SBAS-ClockModel ::= SEQUENCE {
    sbasTo          INTEGER (0..5399),
    sbasAgfo        INTEGER (-2048..2047),
    sbasAgf1        INTEGER (-128..127),
    ...
}
-- ASN1STOP

```

#### **SBAS-ClockModel field descriptions**

<p><b>sbasTo</b> Parameter <math>t_0</math> [10]. Scale factor 16 seconds.</p>
<p><b>sbasAgfo</b> Parameter <math>a_{Gf_0}</math> [10]. Scale factor <math>2^{31}</math> seconds.</p>
<p><b>sbasAgf1</b> Parameter <math>a_{Gf1}</math> [10]. Scale factor <math>2^{40}</math> seconds/second.</p>

### – *NavModelKeplerianSet*

```

-- ASN1START
NavModelKeplerianSet ::= SEQUENCE {
    keplerToe        INTEGER (0 .. 16383),
    keplerW          INTEGER (-2147483648..2147483647),
    keplerDeltaN     INTEGER (-32768..32767),
    keplerM0         INTEGER (-2147483648..2147483647),
    keplerOmegaDot   INTEGER (degreesMaximumNegative..degreesMaximum),
    keplerE          INTEGER (0..4294967295),
    keplerIDot       INTEGER (-8192..8191),
    keplerAPowerHalf INTEGER (0..4294967295),
    keplerI0         INTEGER (-2147483648..2147483647),
    keplerOmega0     INTEGER (-2147483648..2147483647),
    keplerCrS        INTEGER (-32768..32767),
    keplerCis        INTEGER (-32768..32767),
    keplerCus        INTEGER (-32768..32767),
    keplerCrc        INTEGER (-32768..32767),
    keplerCic        INTEGER (-32768..32767),
    keplerCuc        INTEGER (-32768..32767),
    ...
}
-- ASN1STOP

```

#### **NavModelKeplerianSet field descriptions**

<p><b>keplerToe</b> Parameter <math>t_{oe}</math>, time-of-ephemeris in seconds [8]. Scale factor 60 seconds.</p>
<p><b>keplerW</b> Parameter <math>\omega</math>, argument of perigee (semi-circles) [8]. Scale factor <math>2^{31}</math> semi-circles.</p>
<p><b>keplerDeltaN</b> Parameter <math>\Delta n</math>, mean motion difference from computed value (semi-circles/sec) [8]. Scale factor <math>2^{43}</math> semi-circles/second.</p>
<p><b>keplerM0</b> Parameter <math>M_0</math>, mean anomaly at reference time (semi-circles) [8]. Scale factor <math>2^{31}</math> semi-circles.</p>
<p><b>keplerOmegaDot</b> Parameter <math>OMEGA_{dot}</math>, longitude of ascending node of orbit plane at weekly epoch (semi-circles/sec) [8]. Scale factor <math>2^{43}</math> semi-circles/second.</p>
<p><b>keplerE</b> Parameter <math>e</math>, eccentricity [8]. Scale factor <math>2^{33}</math>.</p>
<p><b>KeplerIDot</b> Parameter <math>Idot</math>, rate of inclination angle (semi-circles/sec) [8]. Scale factor <math>2^{43}</math> semi-circles/second.</p>

<i>NavModelKeplerianSet</i> field descriptions
<p><b>keplerAPowerHalf</b> Parameter sqrtA, semi-major Axis in (meters)<sup>½</sup> [8]. Scale factor 2<sup>-19</sup> meters<sup>½</sup>.</p>
<p><b>keplerI0</b> Parameter i<sub>0</sub>, inclination angle at reference time (semi-circles) [8]. Scale factor 2<sup>-31</sup> semi-circles.</p>
<p><b>keplerOmega0</b> Parameter OMEGA<sub>0</sub>, longitude of ascending node of orbit plane at weekly epoch (semi-circles) [8]. Scale factor 2<sup>-31</sup> semi-circles.</p>
<p><b>keplerCrs</b> Parameter C<sub>rs</sub>, amplitude of the sine harmonic correction term to the orbit radius (meters) [8]. Scale factor 2<sup>-5</sup> meters.</p>
<p><b>keplerCis</b> Parameter C<sub>is</sub>, amplitude of the sine harmonic correction term to the angle of inclination (radians) [8]. Scale factor 2<sup>-29</sup> radians.</p>
<p><b>keplerCus</b> Parameter C<sub>us</sub>, amplitude of the sine harmonic correction term to the argument of latitude (radians) [8]. Scale factor 2<sup>-29</sup> radians.</p>
<p><b>keplerCrc</b> Parameter C<sub>rc</sub>, amplitude of the cosine harmonic correction term to the orbit radius (meters) [8]. Scale factor 2<sup>-5</sup> meters.</p>
<p><b>keplerCic</b> Parameter C<sub>ic</sub>, amplitude of the cosine harmonic correction term to the angle of inclination (radians) [8]. Scale factor 2<sup>-29</sup> radians.</p>
<p><b>keplerCuc</b> Parameter C<sub>uc</sub>, amplitude of the cosine harmonic correction term to the argument of latitude (radians) [8]. Scale factor 2<sup>-29</sup> radians.</p>

### – *NavModelNAV-KeplerianSet*

```

-- ASN1START
NavModelNAV-KeplerianSet ::= SEQUENCE {
    navURA          INTEGER (0..15),
    navFitFlag      INTEGER (0..1),
    navToe          INTEGER (0..37799),
    navOmega        INTEGER (-2147483648..2147483647),
    navDeltaN       INTEGER (-32768..32767),
    navM0           INTEGER (-2147483648..2147483647),
    navOmegaADot    INTEGER (degreesMaximumNegative..degreesMaximum),
    navE            INTEGER (0..4294967295),
    navIDot         INTEGER (-8192..8191),
    navAPowerHalf   INTEGER (0..4294967295),
    navI0           INTEGER (-2147483648..2147483647),
    navOmegaA0      INTEGER (-2147483648..2147483647),
    navCrs          INTEGER (-32768..32767),
    navCis          INTEGER (-32768..32767),
    navCus          INTEGER (-32768..32767),
    navCrc          INTEGER (-32768..32767),
    navCic          INTEGER (-32768..32767),
    navCuc          INTEGER (-32768..32767),
    addNAVparam     SEQUENCE {
        ephemerCodeOnL2  INTEGER (0..3),
        ephemerL2Pflag  INTEGER (0..1),
        ephemerSF1Rsvd  SEQUENCE {
            reserved1    INTEGER (0..degreesMaximum),    -- 23-bit field
            reserved2    INTEGER (0..16777215),          -- 24-bit field
            reserved3    INTEGER (0..16777215),          -- 24-bit field
            reserved4    INTEGER (0..65535)              -- 16-bit field
        },
        ephemerAODA      INTEGER (0..31)
    } OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP

```

### *NavModelNAV-KeplerianSet* field descriptions

<b>NavModelNAV-KeplerianSet field descriptions</b>
<b>navURA</b> Parameter URA Index, SV accuracy (dimensionless) [4,7].
<b>navFitFlag</b> Parameter Fit Interval Flag, fit interval indication (dimensionless) [4,7]
<b>navToe</b> Parameter $t_{oe}$ , time of ephemeris (seconds) [4,7]. Scale factor $2^4$ seconds.
<b>navOmega</b> Parameter $\omega$ , argument of perigee (semi-circles) [4,7]. Scale factor $2^{31}$ semi-circles.
<b>navDeltaN</b> Parameter $\Delta n$ , mean motion difference from computed value (semi-circles/sec) [4,7]. Scale factor $2^{43}$ semi-circles/second.
<b>navM0</b> Parameter $M_0$ , mean anomaly at reference time (semi-circles) [4,7]. Scale factor $2^{31}$ semi-circles.
<b>navOmegaADot</b> Parameter $\dot{\Omega}$ , rate of right ascension (semi-circles/sec) [4,7]. Scale factor $2^{43}$ semi-circles/second.
<b>navE</b> Parameter e, eccentricity (dimensionless) [4,7]. Scale factor $2^{33}$ .
<b>navIDot</b> Parameter IDOT, rate of inclination angle (semi-circles/sec) [4,7]. Scale factor $2^{43}$ semi-circles/second.
<b>navAPowerHalf</b> Parameter $\sqrt{A}$ , square root of semi-major axis (meters <sup>1/2</sup> ) [4,7]. Scale factor $2^{19}$ meters <sup>1/2</sup> .
<b>navI0</b> Parameter $i_0$ , inclination angle at reference time (semi-circles) [4,7]. Scale factor $2^{31}$ semi-circles.
<b>navOmegaA0</b> Parameter $\Omega_0$ , longitude of ascending node of orbit plane at weekly epoch (semi-circles) [4,7]. Scale factor $2^{31}$ semi-circles.
<b>navCrs</b> Parameter $C_{rs}$ , amplitude of sine harmonic correction term to the orbit radius (meters) [4,7]. Scale factor $2^5$ meters.
<b>navCis</b> Parameter $C_{is}$ , amplitude of sine harmonic correction term to the angle of inclination (radians) [4,7]. Scale factor $2^{29}$ radians.
<b>navCus</b> Parameter $C_{us}$ , amplitude of sine harmonic correction term to the argument of latitude (radians) [4,7]. Scale factor $2^{29}$ radians.
<b>navCrc</b> Parameter $C_{rc}$ , amplitude of cosine harmonic correction term to the orbit radius (meters) [4,7]. Scale factor $2^5$ meters.
<b>navCic</b> Parameter $C_{ic}$ , amplitude of cosine harmonic correction term to the angle of inclination (radians) [4,7]. Scale factor $2^{29}$ radians.
<b>navCuc</b> Parameter $C_{uc}$ , amplitude of cosine harmonic correction term to the argument of latitude (radians) [4,7]. Scale factor $2^{29}$ radians.
<b>addNAVparam</b> These fields include data and reserved bits in the GPS NAV message [4,14]. These additional navigation parameters, if provided by the location server, allow the target device to perform data wipe-off similar to what is done by the target device with the <i>GNSS-DataBitAssistance</i> .

### NavModelCNAV-KeplerianSet

```
-- ASN1START
NavModelCNAV-KeplerianSet ::= SEQUENCE {
    cnavTop          INTEGER (0..2015),
    cnavURAindex    INTEGER (-16..15),
```



```

cnavDeltaA      INTEGER (-33554432..33554431) ,
cnavAdot        INTEGER (-16777216..16777215) ,
cnavDeltaNo     INTEGER (-65536..65535) ,
cnavDeltaNoDot  INTEGER (-4194304..4194303) ,
cnavMo          INTEGER (-4294967296..4294967295) ,
cnavE           INTEGER (0..8589934591) ,
cnavOmega       INTEGER (-4294967296..4294967295) ,
cnavOMEGA0      INTEGER (-4294967296..4294967295) ,
cnavDeltaOmegaDot  INTEGER (-65536..65535) ,
cnavIo          INTEGER (-4294967296..4294967295) ,
cnavIoDot       INTEGER (-16384..16383) ,
cnavCis         INTEGER (-32768..32767) ,
cnavCic         INTEGER (-32768..32767) ,
cnavCrS         INTEGER (degreesMaximumNegative..degreesMaximum) ,
cnavCrC         INTEGER (degreesMaximumNegative..degreesMaximum) ,
cnavCus         INTEGER (-1048576..1048575) ,
cnavCuc         INTEGER (-1048576..1048575) ,
...
}
-- ASN1STOP

```

### NavModelCNAV-KeplerianSet field descriptions

<p><b>cnavTop</b> Parameter <math>t_{op}</math>, data predict time of week (seconds) [4,5,6,7]. Scale factor 300 seconds.</p>
<p><b>cnavURAindex</b> Parameter <math>URA_{oe}</math> Index, SV accuracy (dimensionless) [4,5,6,7].</p>
<p><b>cnavDeltaA</b> Parameter <math>\Delta A</math>, semi-major axis difference at reference time (meters) [4,5,6,7]. Scale factor <math>2^{-9}</math> meters.</p>
<p><b>cnavAdot</b> Parameter <math>\dot{A}</math>, change rate in semi-major axis (meters/sec) [4,5,6,7]. Scale factor <math>2^{-21}</math> meters/sec.</p>
<p><b>cnavDeltaNo</b> Parameter <math>\Delta n_0</math>, mean motion difference from computed value at reference time (semi-circles/sec) [4,5,6,7]. Scale factor <math>2^{-44}</math> semi-circles/second.</p>
<p><b>cnavDeltaNoDot</b> Parameter <math>\dot{\Delta n}_0</math>, rate of mean motion difference from computed value (semi-circles/sec<sup>2</sup>) [4,5,6,7]. Scale factor <math>2^{-57}</math> semi-circles/second<sup>2</sup>.</p>
<p><b>cnavMo</b> Parameter <math>M_{0-n}</math>, mean anomaly at reference time (semi-circles) [4,5,6,7]. Scale factor <math>2^{-32}</math> semi-circles.</p>
<p><b>cnavE</b> Parameter <math>e_n</math>, eccentricity (dimensionless) [4,5,6,7]. Scale factor <math>2^{-34}</math>.</p>
<p><b>cnavOmega</b> Parameter <math>\omega_n</math>, argument of perigee (semi-circles) [4,5,6,7]. Scale factor <math>2^{-32}</math> semi-circles.</p>
<p><b>cnavOMEGA0</b> Parameter <math>\Omega_{0-n}</math>, reference right ascension angle (semi-circles) [4,5,6,7]. Scale factor <math>2^{-32}</math> semi-circles.</p>
<p><b>cnavDeltaOmegaDot</b> Parameter <math>\dot{\Delta \Omega}</math>, rate of right ascension difference (semi-circles/sec) [4,5,6,7]. Scale factor <math>2^{-44}</math> semi-circles/second.</p>
<p><b>cnavIo</b> Parameter <math>i_{0-n}</math>, inclination angle at reference time (semi-circles) [4,5,6,7]. Scale factor <math>2^{-32}</math> semi-circles.</p>
<p><b>cnavIoDot</b> Parameter <math>\dot{i}_{0-n}</math>-DOT, rate of inclination angle (semi-circles/sec) [4,5,6,7]. Scale factor <math>2^{-44}</math> semi-circles/second..</p>
<p><b>cnavCis</b> Parameter <math>C_{is-n}</math>, amplitude of sine harmonic correction term to the angle of inclination (radians) [4,5,6,7]. Scale factor <math>2^{-30}</math> radians.</p>
<p><b>cnavCic</b> Parameter <math>C_{ic-n}</math>, amplitude of cosine harmonic correction term to the angle of inclination (radians) [4,5,6,7]. Scale factor <math>2^{-30}</math> radians.</p>

<b>NavModelCNAV-KeplerianSet field descriptions</b>
<p><b>cnavCrS</b> Parameter <math>C_{rs-n}</math>, amplitude of sine harmonic correction term to the orbit radius (meters) [4,5,6,7]. Scale factor <math>2^8</math> meters.</p>
<p><b>cnavCrc</b> Parameter <math>C_{rc-n}</math>, amplitude of cosine harmonic correction term to the orbit radius (meters) [4,5,6,7]. Scale factor <math>2^8</math> meters.</p>
<p><b>cnavCus</b> Parameter <math>C_{us-n}</math>, amplitude of the sine harmonic correction term to the argument of latitude (radians) [4,5,6,7]. Scale factor <math>2^{30}</math> radians.</p>
<p><b>cnavCuc</b> Parameter <math>C_{uc-n}</math>, amplitude of cosine harmonic correction term to the argument of latitude (radians) [4,5,6,7]. Scale factor <math>2^{30}</math> radians.</p>

### NavModel-GLONASS-ECEF

```
-- ASN1START
NavModel-GLONASS-ECEF ::= SEQUENCE {
    gloEn          INTEGER (0..31),
    gloP1         BIT STRING (SIZE(2)),
    gloP2         BOOLEAN,
    gloM          INTEGER (0..3),
    gloX          INTEGER (-67108864..67108863),
    gloXdot       INTEGER (degreesMaximumNegative..degreesMaximum),
    gloXdotdot    INTEGER (-16..15),
    gloY          INTEGER (-67108864..67108863),
    gloYdot       INTEGER (degreesMaximumNegative..degreesMaximum),
    gloYdotdot    INTEGER (-16..15),
    gloZ          INTEGER (-67108864..67108863),
    gloZdot       INTEGER (degreesMaximumNegative..degreesMaximum),
    gloZdotdot    INTEGER (-16..15),
    ...
}
-- ASN1STOP
```

<b>NavModel-GLONASS-ECEF field descriptions</b>
<p><b>gloEn</b> Parameter <math>E_n</math>, age of data (days) [9]. Scale factor 1 days.</p>
<p><b>gloP1</b> Parameter P1, time interval between two adjacent values of <math>t_b</math> (minutes) [9].</p>
<p><b>gloP2</b> Parameter P2, change of <math>t_b</math> flag (dimensionless) [9].</p>
<p><b>gloM</b> Parameter M, type of satellite (dimensionless) [9].</p>
<p><b>gloX</b> Parameter <math>x_n(t_b)</math>, x-coordinate of satellite at time <math>t_b</math> (kilometers) [9]. Scale factor <math>2^{11}</math> kilometers.</p>
<p><b>gloXdot</b> Parameter <math>\dot{x}_n(t_b)</math>, x-coordinate of satellite velocity at time <math>t_b</math> (kilometers/sec) [9]. Scale factor <math>2^{20}</math> kilometers/second.</p>
<p><b>gloXdotdot</b> Parameter <math>\ddot{x}_n(t_b)</math>, x-coordinate of satellite acceleration at time <math>t_b</math> (kilometers/sec<sup>2</sup>) [9]. Scale factor <math>2^{30}</math> kilometers/second<sup>2</sup>.</p>
<p><b>gloY</b> Parameter <math>y_n(t_b)</math>, y-coordinate of satellite at time <math>t_b</math> (kilometers) [9]. Scale factor <math>2^{11}</math> kilometers.</p>
<p><b>gloYdot</b> Parameter <math>\dot{y}_n(t_b)</math>, y-coordinate of satellite velocity at time <math>t_b</math> (kilometers/sec) [9]. Scale factor <math>2^{20}</math> kilometers/second.</p>

<i>NavModel-GLONASS-ECEF</i> field descriptions
<p><b>gloYdotdot</b>                      Parameter <math>\ddot{y}_n(t_b)</math>, y-coordinate of satellite acceleration at time <math>t_b</math> (kilometers/sec<sup>2</sup>) [9].                      Scale factor 2<sup>-30</sup> kilometers/second<sup>2</sup>.</p>
<p><b>gloZ</b>                      Parameter <math>z_n(t_b)</math>, z-coordinate of satellite at time <math>t_b</math> (kilometers) [9].                      Scale factor 2<sup>-11</sup> kilometers.</p>
<p><b>gloZdot</b>                      Parameter <math>\dot{z}_n(t_b)</math>, z-coordinate of satellite velocity at time <math>t_b</math> (kilometers/sec) [9].                      Scale factor 2<sup>-20</sup> kilometers/second.</p>
<p><b>gloZdotdot</b>                      Parameter <math>\ddot{z}_n(t_b)</math>, z-coordinate of satellite acceleration at time <math>t_b</math> (kilometers/sec<sup>2</sup>) [9].                      Scale factor 2<sup>-30</sup> kilometers/second<sup>2</sup>.</p>

*NavModel-SBAS-ECEF*

```

-- ASN1START
NavModel-SBAS-ECEF ::= SEQUENCE {
    sbasTo          INTEGER (0..5399)                OPTIONAL,  -- Cond ClockModel
    sbasAccuracy    BIT STRING (SIZE(4)),
    sbasXg          INTEGER (-536870912..536870911),
    sbasYg          INTEGER (-536870912..536870911),
    sbasZg          INTEGER (-16777216..16777215),
    sbasXgDot       INTEGER (-65536..65535),
    sbasYgDot       INTEGER (-65536..65535),
    sbasZgDot       INTEGER (-131072..131071),
    sbasXgDotDot    INTEGER (-512..511),
    sbasYgDotDot    INTEGER (-512..511),
    sbasZgDotDot    INTEGER (-512..511),
    ...
}
-- ASN1STOP
    
```

Conditional presence	Explanation
<i>ClockModel</i>	This field is mandatory present if <i>gnss-ClockModel</i> Model-5 is not included; otherwise it is not present.

<i>NavModel-SBAS-ECEF</i> field descriptions
<p><b>sbasTo</b>                      Parameter <math>t_0</math>, time of applicability (seconds) [10].                      Scale factor 16 seconds.</p>
<p><b>sbasAccuracy</b>                      Parameter Accuracy, (dimensionless) [10].</p>
<p><b>sbasXg</b>                      Parameter <math>X_G</math>, (meters) [10].                      Scale factor 0.08 meters.</p>
<p><b>sbasYg</b>                      Parameter <math>Y_G</math>, (meters) [10].                      Scale factor 0.08 meters.</p>
<p><b>sbasZg</b>                      Parameter <math>Z_G</math>, (meters) [10].                      Scale factor 0.4 meters.</p>
<p><b>sbasXgDot</b>                      Parameter <math>X_G</math>, Rate-of-Change, (meters/sec) [10].                      Scale factor 0.000625 meters/second.</p>
<p><b>sbasYgDot</b>                      Parameter <math>Y_G</math>, Rate-of-Change, (meters/sec) [10].                      Scale factor 0.000625 meters/second.</p>
<p><b>sbasZgDot</b>                      Parameter <math>Z_G</math>, Rate-of-Change, (meters/sec) [10].                      Scale factor 0.004 meters/second.</p>

<i>NavModel-SBAS-ECEF</i> field descriptions
<p><b><i>sbasXgDotDot</i></b>            Parameter <math>X_G</math>, Acceleration, (meters/sec<sup>2</sup>) [10].            Scale factor 0.0000125 meters/second<sup>2</sup>.</p>
<p><b><i>sbagYgDotDot</i></b>            Parameter <math>Y_G</math>, Acceleration, (meters/sec<sup>2</sup>) [10].            Scale factor 0.0000125 meters/second<sup>2</sup>.</p>
<p><b><i>sbasZgDotDot</i></b>            Parameter <math>Z_G</math> Acceleration, (meters/sec<sup>2</sup>) [10].            Scale factor 0.0000625 meters/second<sup>2</sup>.</p>

## – *GNSS-RealTimeIntegrity*

The IE *GNSS-RealTimeIntegrity* is used by the location server to provide parameters that describe the real-time status of the GNSS constellations. *GNSS-RealTimeIntegrity* data communicates the health of the GNSS signals to the mobile in real-time.

The location server shall always transmit the *GNSS-RealTimeIntegrity* with the current list of unhealthy signals (i.e., not only for signals/SVs currently visible at the reference location), for any GNSS positioning attempt and whenever GNSS assistance data are sent. If the number of bad signals is zero, then the *GNSS-RealTimeIntegrity* IE shall be omitted.

```
-- ASN1START
GNSS-RealTimeIntegrity ::= SEQUENCE {
    gnss-BadSignalList  GNSS-BadSignalList,
    ...
}
GNSS-BadSignalList ::= SEQUENCE (SIZE(1..64)) OF BadSignalElement
BadSignalElement ::= SEQUENCE {
    badSVID             SV-ID,
    badSignalID         GNSS-SignalIDs  OPTIONAL,  -- Need OP
    ...
}
-- ASN1STOP
```

<i>GNSS-RealTimeIntegrity</i> field descriptions
<p><b><i>gnss-BadSignalList</i></b>            This field specifies a list of satellites with bad signal or signals.</p>
<p><b><i>badSVID</i></b>            This field specifies the GNSS SV-ID of the satellite with bad signal or signals.</p>
<p><b><i>badSignalID</i></b>            This field identifies the bad signal or signals of a satellite. This is represented by a bit string in <i>GNSS-SignalIDs</i>, with a one-value at a bit position means the particular GNSS signal type of the SV is unhealthy; a zero-value means healthy. Absence of this field means that all signals on the specific SV are bad.</p>

## – *GNSS-DataBitAssistance*

The IE *GNSS-DataBitAssistance* is used by the location server to provide data bit assistance data for specific satellite signals for data wipe-off. The data bits included in the assistance data depends on the GNSS and its signal.

```
-- ASN1START
GNSS-DataBitAssistance ::= SEQUENCE {
    gnss-TOD             INTEGER (0..3599),
    gnss-TODfrac         INTEGER (0..999)  OPTIONAL,  -- Need ON
    gnss-DataBitsSatList GNSS-DataBitsSatList,
    ...
}
GNSS-DataBitsSatList ::= SEQUENCE (SIZE(1..64)) OF GNSS-DataBitsSatElement
GNSS-DataBitsSatElement ::= SEQUENCE {
    svID                SV-ID,
    gnss-DataBitsSgnList GNSS-DataBitsSgnList,
```

```

}
...
}
GNSS-DataBitsSgnList ::= SEQUENCE (SIZE(1..8)) OF GNSS-DataBitsSgnElement
GNSS-DataBitsSgnElement ::= SEQUENCE {
    gnss-SignalType      GNSS-SignalID,
    gnss-DataBits        BIT STRING (SIZE (1..1024)),
    ...
}
-- ASN1STOP

```

#### **GNSS-DataBitAssistance field descriptions**

##### **gnss-TOD**

This field specifies the reference time of the first bit of the data in *GNSS-DataBitAssistance* in integer seconds in GNSS specific system time, modulo 1 hour.

Scale factor 1 second.

##### **gnss-TODfrac**

This field specifies the fractional part of the *gnss-TOD* in 1-milli-second resolution.

Scale factor 1 millisecond. The total GNSS TOD is *gnss-TOD* + *gnss-TODfrac*.

##### **gnss-DataBitsSatList**

This list specifies the data bits for a particular GNSS satellite *SV-ID* and signal *GNSS-SignalID*.

##### **svID**

This field specifies the GNSS *SV-ID* of the satellite for which the *GNSS-DataBitAssistance* is given.

##### **gnss-SignalType**

This field identifies the GNSS signal type of the *GNSS-DataBitAssistance*.

##### **gnss-DataBits**

Data bits are contained in GNSS system and data type specific format.

In case of GPS L1 C/A, it contains the NAV data modulation bits as defined in [4].

In case of Modernized GPS L1C, it contains the encoded and interleaved modulation symbols as defined in [6] section 3.2.3.1. In case of Modernized GPS L2C, it contains either the NAV data modulation bits, the FEC encoded NAV data modulation symbols, or the FEC encoded CNAV data modulation symbols, dependent on the current signal configuration of this satellite as defined in [4, Table 3-III]. In case of Modernized GPS L5, it contains the FEC encoded CNAV data modulation symbols as defined in [5].

In case of SBAS, it contains the FEC encoded data modulation symbols as defined in [10].

In case of QZSS QZS-L1, it contains the NAV data modulation bits as defined in [7] section 5.2. In case of QZSS QZS-L1C, it contains the encoded and interleaved modulation symbols as defined in [7] section 5.3. In case of QZSS QZS-L2C, it contains the encoded modulation symbols as defined in [7] section 5.5. In case of QZSS QZS-L5, it contains the encoded modulation symbols as defined in [7] section 5.6.

In case of GLONASS, it contains the 100 sps differentially Manchester encoded modulation symbols as defined in [9] section 3.3.2.2.

In case of Galileo, it contains the FEC encoded and interleaved modulation symbols. The logical levels 1 and 0 correspond to signal levels -1 and +1, respectively.

## — *GNSS-AcquisitionAssistance*

The IE *GNSS-AcquisitionAssistance* is used by the location server to provide parameters that enable fast acquisition of the GNSS signals. Essentially, these parameters describe the range and derivatives from respective satellites to the reference location at the reference time *GNSS-SystemTime* provided in IE *GNSS-ReferenceTime*.

Whenever *GNSS-AcquisitionAssistance* is provided by the location server, the IE *GNSS-ReferenceTime* shall be provided as well. E.g., even if the target device request for assistance data includes only a request for *GNSS-AcquisitionAssistance*, the location server shall also provide the corresponding IE *GNSS-ReferenceTime*.

Figure 6.5.2.2-1 illustrates the relation between some of the fields, using GPS TOW as exemplary reference.

```

-- ASN1START
GNSS-AcquisitionAssistance ::= SEQUENCE {
    gnss-SignalID      GNSS-SignalID,
    gnss-AcquisitionAssistList GNSS-AcquisitionAssistList,

```

```

...
}
GNSS-AcquisitionAssistList ::= SEQUENCE (SIZE(1..64)) OF GNSS-AcquisitionAssistElement
GNSS-AcquisitionAssistElement ::= SEQUENCE {
  svID                SV-ID,
  doppler0            INTEGER (-2048..2047),
  doppler1            INTEGER (0..63),
  dopplerUncertainty INTEGER (0..4),
  codePhase           INTEGER (0..1022),
  intCodePhase        INTEGER (0..127),
  codePhaseSearchWindow INTEGER (0..31),
  azimuth             INTEGER (0..511),
  elevation           INTEGER (0..127),
  ...
}
-- ASN1STOP

```

### **GNSS-AcquisitionAssistance field descriptions**

<b>gnss-SignalID</b>	This field specifies the GNSS signal for which the acquisition assistance are provided.
<b>gnss-AcquisitionAssistList</b>	These fields provide a list of acquisition assistance data for each GNSS satellite.
<b>svID</b>	This field specifies the GNSS SV-ID of the satellite for which the <i>GNSS-AcquisitionAssistance</i> is given.
<b>doppler0</b>	This field specifies the Doppler (0 <sup>th</sup> order term) value. A positive value in Doppler defines the increase in satellite signal frequency due to velocity towards the target device. A negative value in Doppler defines the decrease in satellite signal frequency due to velocity away from the target device. Doppler is given in unit of m/s by multiplying the Doppler value in Hz by the nominal wavelength of the assisted signal. Scale factor 0.5 m/s in the range from -1024 m/s to +1023.5 m/s.
<b>doppler1</b>	This field specifies the Doppler (1 <sup>st</sup> order term) value. A positive value defines the rate of increase in satellite signal frequency due to acceleration towards the target device. A negative value defines the rate of decrease in satellite signal frequency due to acceleration away from the target device. Scale factor 1/210 m/s <sup>2</sup> in the range from -0.2 m/s <sup>2</sup> to +0.1 m/s <sup>2</sup> .
<b>dopplerUncertainty</b>	This field specifies the Doppler uncertainty value. It is defined such that the Doppler experienced by a stationary target device is in the range [Doppler–Doppler Uncertainty] to [Doppler+Doppler Uncertainty]. Doppler Uncertainty is given in unit of m/s by multiplying the Doppler Uncertainty value in Hz by the nominal wavelength of the assisted signal. Defined values: 2.5 m/s, 5 m/s, 10 m/s, 20 m/s, 40 m/s as encoded by an integer <i>n</i> in the range 0-4 according to: $2^{-n}(40)$ m/s; $n = 0 - 4$ .
<b>codePhase</b>	This field specifies the code phase, in units of milli-seconds, in the range from 0 to 1 millisecond scaled by the nominal chipping rate of the GNSS signal, where increasing values of the field signify increasing predicted signal code phases, as seen by a receiver at the reference location at the reference time. The reference location would typically be an apriori estimate of the target device location. Scale factor $2^{-10}$ ms in the range from 0 to $(1-2^{-10})$ ms.
<b>intCodePhase</b>	This field contains integer code phase (expressed modulo 128 ms) currently being transmitted at the reference time, as seen by a receiver at the reference location. Scale factor 1 ms in the range from 0 to 127 ms.
<b>codePhaseSearchWindow</b>	This field contains the code phase search window. The code phase search window accounts for the uncertainty in the estimated target device location but not any uncertainty in reference time. It is defined such that the expected code phase is in the range [Code Phase–Code Phase Search Window] to [Code Phase+Code Phase Search Window] given in units of milli-seconds. Range 0-31, mapping according to the table codePhaseSearchWindow Value to Interpretation Code Phase Search Window [ms] relation shown below.
<b>azimuth</b>	This field specifies the azimuth angle. An angle of <i>x</i> degrees means the satellite azimuth <i>a</i> is in the range $(x \leq a < x+0.703125)$ degrees. Scale factor 0.703125 degrees.
<b>elevation</b>	This field specifies the elevation angle. An angle of <i>y</i> degrees means the satellite elevation <i>e</i> is in the range $(y \leq e < y+0.703125)$ degrees. Scale factor 0.703125 degrees.

**codePhaseSearchWindow Value to Interpretation Code Phase Search Window [ms] relation**

<b>codePhaseSearchWindow Value</b>	<b>Interpretation Code Phase Search Window [ms]</b>
'00000'	No information
'00001'	0,002
'00010'	0,004
'00011'	0,008
'00100'	0,012
'00101'	0,016
'00110'	0,024
'00111'	0,032
'01000'	0,048
'01001'	0,064
'01010'	0,096
'01011'	0,128
'01100'	0,164
'01101'	0,200
'01110'	0,250
'01111'	0,300
'10000'	0,360
'10001'	0,420
'10010'	0,480
'10011'	0,540
'10100'	0,600
'10101'	0,660
'10110'	0,720
'10111'	0,780
'11000'	0,850
'11001'	1,000
'11010'	1,150
'11011'	1,300
'11100'	1,450
'11101'	1,600
'11110'	1,800
'11111'	2,000

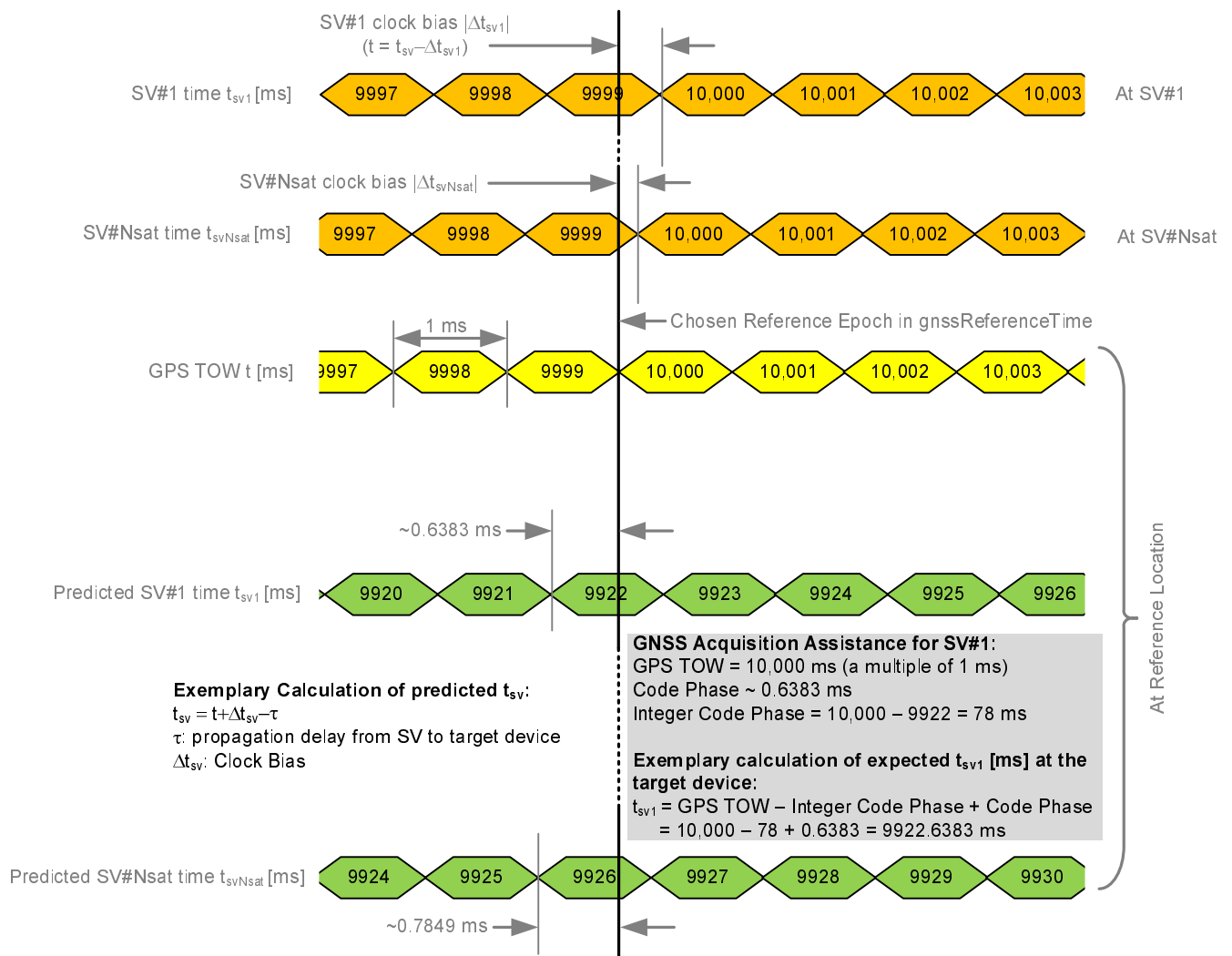


Figure 6.5.2.2-1: Exemplary calculation of some GNSS Acquisition Assistance fields.

### GNSS-Almanac

The IE *GNSS-Almanac* is used by the location server to provide the coarse, long-term model of the satellite positions and clocks. The meaning of these parameters is defined in relevant ICDs of the particular GNSS and GNSS specific interpretations apply. For example, GPS and QZSS use the same model parameters but some parameters have a different interpretation [7]. *GNSS-Almanac* is useful for receiver tasks that require coarse accuracy, such as determining satellite visibility. The model is valid for up to a few weeks, typically. Since it is a long-term model, the field should be provided for all satellites available in the GNSS constellation (i.e., not only for SVs visible at the reference location and including SVs flagged as unhealthy in almanac). The *completeAlmanacProvided* field indicates whether or not the location server provided almanacs for the complete GNSS constellation.

```
-- ASN1START
GNSS-Almanac ::= SEQUENCE {
    weekNumber          INTEGER (0..255)    OPTIONAL,  -- Need ON
    toa                 INTEGER (0..255)    OPTIONAL,  -- Need ON
    ioda                INTEGER (0..3)      OPTIONAL,  -- Need ON
    completeAlmanacProvided  BOOLEAN,
    gnss-AlmanacList     GNSS-AlmanacList,
    ...
}

GNSS-AlmanacList ::= SEQUENCE (SIZE(1..64)) OF GNSS-AlmanacElement

GNSS-AlmanacElement ::= CHOICE {
    keplerianAlmanacSet    AlmanacKeplerianSet,    -- Model-1
    keplerianNAV-Almanac  AlmanacNAV-KeplerianSet, -- Model-2
}
```



```

keplerianReducedAlmanac AlmanacReducedKeplerianSet, -- Model-3
keplerianMidiAlmanac    AlmanacMidiAlmanacSet,    -- Model-4
keplerianGLONASS        AlmanacGLONASS-AlmanacSet, -- Model-5
ecef-SBAS-Almanac       AlmanacECEF-SBAS-AlmanacSet, -- Model-6
...
}
-- ASN1STOP
    
```

<b>GNSS-Almanac field descriptions</b>
<p><b>weekNumber</b> This field specifies the almanac reference week number in GNSS specific system time to which the almanac reference time <i>toa</i> is referenced, modulo 256 weeks. This field is required for non-GLONASS GNSS.</p>
<p><b>toa</b> This field specifies the almanac reference time given in GNSS specific system time, in units of seconds with a scale factor of 212. This field is required for non-GLONASS GNSS.</p>
<p><b>ioda</b> This field specifies the issue of data. This field is required for non-GLONASS GNSS.</p>
<p><b>completeAlmanacProvided</b> If set to TRUE, the <i>gnss-AlmanacList</i> contains almanacs for the complete GNSS constellation indicated by <i>GNSS-ID</i>.</p>
<p><b>gnss-AlmanacList</b> This list contains the almanac model for each GNSS satellite in the GNSS constellation.</p>

*AlmanacKeplerianSet*

```

-- ASN1START
AlmanacKeplerianSet ::= SEQUENCE {
    svID                SV-ID,
    kepAlmanacE         INTEGER (0..2047),
    kepAlmanacDeltaI    INTEGER (-1024..1023),
    kepAlmanacOmegaDot  INTEGER (-1024..1023),
    kepSVHealth         INTEGER (0..15),
    kepAlmanacAPowerHalf INTEGER (-65536..65535),
    kepAlmanacOmega0    INTEGER (-32768..32767),
    kepAlmanacW         INTEGER (-32768..32767),
    kepAlmanacM0        INTEGER (-32768..32767),
    kepAlmanacAF0       INTEGER (-8192..8191),
    kepAlmanacAF1       INTEGER (-1024..1023),
    ...
}
-- ASN1STOP
    
```

<b>AlmanacKeplerianSet field descriptions</b>
<p><b>svID</b> This field identifies the satellite for which the GNSS Almanac Model is given.</p>
<p><b>kepAlmanacE</b> Parameter e, eccentricity, dimensionless [8]. Scale factor 2<sup>-16</sup>.</p>
<p><b>kepAlmanacDeltaI</b> Parameter δ<sub>i</sub>, semi-circles [8]. Scale factor 2<sup>-14</sup> semi-circles.</p>
<p><b>kepAlmanacOmegaDot</b> Parameter OMEGADOT, longitude of ascending node of orbit plane at weekly epoch (semi-circles/sec) [8]. Scale factor 2<sup>-33</sup> semi-circles/seconds.</p>
<p><b>kepSVHealth</b> Parameter SV Health KP, dimensionless. This field specifies the SV Health status in GNSS almanac model using Keplerian parameters. In Galileo case this field shall contain the I/NAV health status bits [8].</p>
<p><b>kepAlmanacAPowerHalf</b> Parameter delta A<sup>1/2</sup>, Semi-Major Axis delta (meters)<sup>1/2</sup> [8]. Scale factor 2<sup>-9</sup> meters<sup>1/2</sup>.</p>
<p><b>kepAlmanacOmega0</b> Parameter OMEGA<sub>0</sub>, longitude of ascending node of orbit plane at weekly epoch (semi-circles) [8]. Scale factor 2<sup>-15</sup> semi-circles.</p>

<i>AlmanacKeplerianSet</i> field descriptions
<p><b>kepAlmanacW</b> Parameter <math>\omega</math>, argument of perigee (semi-circles) [8]. Scale factor <math>2^{-15}</math> semi-circles.</p>
<p><b>kepAlmanacM0</b> Parameter <math>M_0</math>, mean anomaly at reference time (semi-circles) [8]. Scale factor <math>2^{-15}</math> semi-circles.</p>
<p><b>kepAlmanacAF0</b> Parameter <math>af_0</math>, seconds [8]. Scale factor <math>2^{-19}</math> seconds.</p>
<p><b>kepAlmanacAF1</b> Parameter <math>af_1</math>, sec/sec [8]. Scale factor <math>2^{-38}</math> seconds/second.</p>

– *AlmanacNAV-KeplerianSet*

```

-- ASN1START
AlmanacNAV-KeplerianSet ::= SEQUENCE {
    svID                SV-ID,
    navAlmE              INTEGER (0..65535),
    navAlmDeltaI         INTEGER (-32768..32767),
    navAlmOMEGADOT      INTEGER (-32768..32767),
    navAlmSVHealth      INTEGER (0..255),
    navAlmSqrtA         INTEGER (0..16777215),
    navAlmOMEGAo        INTEGER (degreesMaximumNegative..degreesMaximum),
    navAlmOmega          INTEGER (degreesMaximumNegative..degreesMaximum),
    navAlmMo             INTEGER (degreesMaximumNegative..degreesMaximum),
    navAlmaf0            INTEGER (-1024..1023),
    navAlmaf1            INTEGER (-1024..1023),
    ...
}
-- ASN1STOP

```

<i>AlmanacNAV-KeplerianSet</i> field descriptions
<b>svID</b> This field identifies the satellite for which the GNSS Almanac Model is given.
<b>navAlmE</b> Parameter e, eccentricity, dimensionless [4,7]. Scale factor $2^{21}$ .
<b>navAlmDeltaI</b> Parameter $\delta i$ , correction to inclination, semi-circles [4,7]. Scale factor $2^{19}$ semi-circles.
<b>navAlmOMEGADOT</b> Parameter $\dot{\Omega}$ , rate of right ascension, semi-circles/sec [4,7]. Scale factor $2^{38}$ semi-circles/second.
<b>navAlmSVHealth</b> Parameter SV Health, satellite health [4,7].
<b>navAlmSqrtA</b> Parameter $\sqrt{A}$ , square root of the semi-major axis, meters <sup>1/2</sup> [4,7] Scale factor $2^{11}$ meters <sup>1/2</sup> .
<b>navAlmOMEGAo</b> Parameter $\Omega_0$ , longitude of ascending node of orbit plane at weekly epoch, semi-circles [4,7]. Scale factor $2^{23}$ semi-circles.
<b>navAlmOmega</b> Parameter $\omega$ , argument of perigee semi-circles [4,7]. Scale factor $2^{23}$ semi-circles.
<b>navAlmMo</b> Parameter $M_0$ , mean anomaly at reference time semi-circles [4,7]. Scale factor $2^{23}$ semi-circles.
<b>navAlmaf0</b> Parameter $a_0$ , apparent satellite clock correction seconds [4,7]. Scale factor $2^{20}$ seconds.
<b>navAlmaf1</b> Parameter $a_1$ , apparent satellite clock correction sec/sec [4,7]. Scale factor $2^{38}$ semi-circles seconds/second.

### *AlmanacReducedKeplerianSet*

```

-- ASN1START
AlmanacReducedKeplerianSet ::= SEQUENCE {
    svID                SV-ID,
    redAlmDeltaA        INTEGER (-128..127),
    redAlmOmega0        INTEGER (-64..63),
    redAlmPhi0          INTEGER (-64..63),
    redAlmL1Health      BOOLEAN,
    redAlmL2Health      BOOLEAN,
    redAlmL5Health      BOOLEAN,
    ...
}
-- ASN1STOP

```

<i>AlmanacReducedKeplerianSet</i> field descriptions
<b>svID</b> This field identifies the satellite for which the GNSS Almanac Model is given.
<b>redAlmDeltaA</b> Parameter $\delta_A$ , meters [4,5,6,7]. Scale factor $2^{+9}$ meters.
<b>redAlmOmega0</b> Parameter $\Omega_0$ , semi-circles [4,5,6,7]. Scale factor $2^{-6}$ semi-circles.
<b>redAlmPhi0</b> Parameter $\Phi_0$ , semi-circles [4,5,6,7]. Scale factor $2^{-6}$ semi-circles.
<b>redAlmL1Health</b> Parameter L1 Health, dimensionless [4,5,6,7].
<b>redAlmL2Health</b> Parameter L2 Health, dimensionless [4,5,6,7].
<b>redAlmL5Health</b> Parameter L5 Health, dimensionless [4,5,6,7].

– *AlmanacMidiAlmanacSet*

```
-- ASN1START
AlmanacMidiAlmanacSet ::= SEQUENCE {
    svID                SV-ID,
    midiAlmE            INTEGER (0..2047),
    midiAlmDeltaI       INTEGER (-1024..1023),
    midiAlmOmegaDot     INTEGER (-1024..1023),
    midiAlmSqrtA        INTEGER (0..131071),
    midiAlmOmega0       INTEGER (-32768..32767),
    midiAlmOmega        INTEGER (-32768..32767),
    midiAlmMo           INTEGER (-32768..32767),
    midiAlmaf0          INTEGER (-1024..1023),
    midiAlmaf1          INTEGER (-512..511),
    midiAlmL1Health     BOOLEAN,
    midiAlmL2Health     BOOLEAN,
    midiAlmL5Health     BOOLEAN,
    ...
}
-- ASN1STOP
```

<b>AlmanacMidiAlmanacSet field descriptions</b>
<b>svID</b> This field identifies the satellite for which the GNSS Almanac Model is given.
<b>midiAlmE</b> Parameter $e$ , dimensionless [4,5,6,7]. Scale factor $2^{-16}$ .
<b>midiAlmDeltaI</b> Parameter $\delta_i$ , semi-circles [4,5,6,7]. Scale factor $2^{-14}$ semi-circles.
<b>midiAlmOmegaDot</b> Parameter $\dot{\Omega}$ , semi-circles/sec [4,5,6,7]. Scale factor $2^{-33}$ semi-circles/second.
<b>midiAlmSqrtA</b> Parameter $\sqrt{A}$ , meters <sup>1/2</sup> [4,5,6,7]. Scale factor $2^{-4}$ meters <sup>1/2</sup> .
<b>midiAlmOmega0</b> Parameter $\Omega_0$ , semi-circles [4,5,6,7]. Scale factor $2^{-15}$ semi-circles.
<b>midiAlmOmega</b> Parameter $\omega$ , semi-circles [4,5,6,7]. Scale factor $2^{-15}$ semi-circles.
<b>midiAlmMo</b> Parameter $M_0$ , semi-circles [4,5,6,7]. Scale factor $2^{-15}$ semi-circles.
<b>midiAlmaf0</b> Parameter $a_{f0}$ , seconds [4,5,6,7]. Scale factor $2^{20}$ seconds.
<b>midiAlmaf1</b> Parameter $a_{f1}$ , sec/sec [4,5,6,7]. Scale factor $2^{37}$ seconds/second.
<b>midiAlmL1Health</b> Parameter L1 Health, dimensionless [4,5,6,7].
<b>midiAlmL2Health</b> Parameter L2 Health, dimensionless [4,5,6,7].
<b>midiAlmL5Health</b> Parameter L5 Health, dimensionless [4,5,6,7].

### AlmanacGLONASS-AlmanacSet

```
-- ASN1START
AlmanacGLONASS-AlmanacSet ::= SEQUENCE {
    gloAlm-NA          INTEGER (1..1461),
    gloAlmNA          INTEGER (1..24),
    gloAlmHA          INTEGER (0..31),
    gloAlmLambdaA     INTEGER (-1048576..1048575),
    gloAlmLambdaA     INTEGER (0..2097151),
    gloAlmDeltaIa     INTEGER (-131072..131071),
    gloAlmDeltaTA     INTEGER (-2097152..2097151),
    gloAlmDeltaTdotA  INTEGER (-64..63),
    gloAlmEpsilonA    INTEGER (0..32767),
    gloAlmOmegaA      INTEGER (-32768..32767),
    gloAlmTauA        INTEGER (-512..511),
    gloAlmCA          INTEGER (0..1),
    gloAlmMA          BIT STRING (SIZE(2))          OPTIONAL, -- Need ON
    ...
}
-- ASN1STOP
```

<b>AlmanacGLONASS-AlmanacSet field descriptions</b>
<b>gloAlmNA</b> Parameter $N^A$ , days [9]. Scale factor 1 days.
<b>gloAlmna</b> Parameter $n^A$ , dimensionless [9].
<b>gloAlmHA</b> Parameter $H_n^A$ , dimensionless [9].
<b>gloAlmLambdaA</b> Parameter $\lambda_n^A$ , semi-circles [9]. Scale factor $2^{20}$ semi-circles.
<b>gloAlmLambdaA</b> Parameter $t_{\lambda_n}^A$ , seconds [9]. Scale factor $2^5$ seconds.
<b>gloAlmDeltaA</b> Parameter $\Delta_n^A$ , semi-circles [9]. Scale factor $2^{20}$ semi-circles.
<b>gloAlmDeltaTA</b> Parameter $\Delta T_n^A$ , sec/orbit period [9]. Scale factor $2^9$ seconds/orbit period.
<b>gloAlmDeltaTdotA</b> Parameter $\Delta T\_DOT_n^A$ , sec/orbit period <sup>2</sup> [9]. Scale factor $2^{14}$ seconds/orbit period <sup>2</sup> .
<b>gloAlmEpsilonA</b> Parameter $\epsilon_n^A$ , dimensionless [9]. Scale factor $2^{20}$ .
<b>gloAlmOmegaA</b> Parameter $\omega_n^A$ , semi-circles [9]. Scale factor $2^{15}$ semi-circles.
<b>gloAlmTauA</b> Parameter $\tau_n^A$ , seconds [9]. Scale factor $2^{18}$ seconds.
<b>gloAlmCA</b> Parameter $C_n^A$ , dimensionless [9].
<b>gloAlmMA</b> Parameter $M_n^A$ , dimensionless [9]. This parameter is present if its value is nonzero; otherwise it is not present.

### AlmanacECEF-SBAS-AlmanacSet

```

-- ASN1START
AlmanacECEF-SBAS-AlmanacSet ::= SEQUENCE {
    sbasAlmDataID      INTEGER (0..3),
    svID               SV-ID,
    sbasAlmHealth      BIT STRING (SIZE(8)),
    sbasAlmXg          INTEGER (-16384..16383),
    sbasAlmYg          INTEGER (-16384..16383),
    sbasAlmZg          INTEGER (-256..255),
    sbasAlmXgdot       INTEGER (-4..3),
    sbasAlmYgdot       INTEGER (-4..3),
    sbasAlmZgdot       INTEGER (-8..7),
    sbasAlmTo          INTEGER (0..2047),
    ...
}
-- ASN1STOP

```

<b>AlmanacECEF-SBAS-AlmanacSet field descriptions</b>
<b>sbasAlmDataID</b> Parameter Data ID, dimensionless [10].
<b>svID</b> This field identifies the satellite for which the GNSS Almanac Model is given.
<b>sbasAlmHealth</b> Parameter Health, dimensionless [10].
<b>sbasAlmXg</b> Parameter $X_G$ , meters [10]. Scale factor 2600 meters.
<b>sbasAlmYg</b> Parameter $Y_G$ , meters [10]. Scale factor 2600 meters.
<b>sbasAlmZg</b> Parameter $Z_G$ , meters [10]. Scale factor 26000 meters.
<b>sbasAlmXgdot</b> Parameter $X_G$ Rat-of-Change, meters/sec [10]. Scale factor 10 meters/second.
<b>sbasAlmYgDot</b> Parameter $Y_G$ Rate-of-Change, meters/sec [10]. Scale factor 10 meters/second.
<b>sbasAlmZgDot</b> Parameter $Z_G$ Rate-of-Change, meters/sec [10]. Scale factor 40.96 meters/second.
<b>sbasAlmTo</b> Parameter $t_0$ , seconds [10]. Scale factor 64 meters/seconds.

## – GNSS-UTC-Model

The IE *GNSS-UTC-Model* is used by the location server to provide several sets of parameters needed to relate GNSS system time to Universal Time Coordinate (UTC), as defined in [4,5,6,7,8,9,10].

The UTC time standard, UTC(k), is GNSS specific. E.g., if *GNSS-ID* indicates GPS, *GNSS-UTC-Model* contains a set of parameters needed to relate GPS system time to UTC(USNO); if *GNSS-ID* indicates QZSS, *GNSS-UTC-Model* contains a set of parameters needed to relate QZST to UTC(NICT); if *GNSS-ID* indicates GLONASS, *GNSS-UTC-Model* contains a set of parameters needed to relate GLONASS system time to UTC(RU); if *GNSS-ID* indicates SBAS, *GNSS-UTC-Model* contains a set of parameters needed to relate SBAS network time for the SBAS indicated by *SBAS-ID* to the UTC standard defined by the UTC Standard ID.

```
-- ASN1START
GNSS-UTC-Model ::= CHOICE {
    utcModel1      UTC-ModelSet1,  -- Model-1
    utcModel2      UTC-ModelSet2,  -- Model-2
    utcModel3      UTC-ModelSet3,  -- Model-3
    utcModel4      UTC-ModelSet4,  -- Model-4
    ...
}
-- ASN1STOP
```

## – UTC-ModelSet1

```
-- ASN1START
UTC-ModelSet1 ::= SEQUENCE {
    gnss-Utc-A1      INTEGER (degreesMaximumNegative..degreesMaximum),
    gnss-Utc-A0      INTEGER (-2147483648..2147483647),
    gnss-Utc-Tot     INTEGER (0..255),
    gnss-Utc-WNt     INTEGER (0..255),
    gnss-Utc-DeltaTls INTEGER (-128..127),
    gnss-Utc-WNlsf   INTEGER (0..255),
    gnss-Utc-DN      INTEGER (-128..127),
    gnss-Utc-DeltaTlsf INTEGER (-128..127),
    ...
}
```

```
}
-- ASN1STOP
```

#### UTC-ModelSet1 field descriptions

<b>gnss-Utc-A1</b> Parameter $A_1$ , scale factor $2^{-50}$ seconds/second [4,7,8].
<b>gnss-Utc-A0</b> Parameter $A_0$ , scale factor $2^{-30}$ seconds [4,7,8].
<b>gnss-Utc-Tot</b> Parameter $t_{ot}$ , scale factor $2^{12}$ seconds [4,7,8].
<b>gnss-Utc-WNt</b> Parameter $WN_t$ , scale factor 1 week [4,7,8].
<b>gnss-Utc-DeltaTls</b> Parameter $\Delta t_{LS}$ , scale factor 1 second [4,7,8].
<b>gnss-Utc-WNlsf</b> Parameter $WN_{LSF}$ , scale factor 1 week [4,7,8].
<b>gnss-Utc-DN</b> Parameter DN, scale factor 1 day [4,7,8].
<b>gnss-Utc-DeltaTlsf</b> Parameter $\Delta t_{LSF}$ , scale factor 1 second [4,7,8].

#### UTC-ModelSet2

```
-- ASN1START
UTC-ModelSet2 ::= SEQUENCE {
    utcA0          INTEGER (-32768..32767),
    utcA1          INTEGER (-4096..4095),
    utcA2          INTEGER (-64..63),
    utcDeltaTls   INTEGER (-128..127),
    utcTot         INTEGER (0..65535),
    utcWNot        INTEGER (0..8191),
    utcWNlsf       INTEGER (0..255),
    utcDN          BIT STRING (SIZE(4)),
    utcDeltaTlsf  INTEGER (-128..127),
    ...
}
-- ASN1STOP
```

#### UTC-ModelSet2 field descriptions

<b>utcA0</b> Parameter $A_{0-n}$ , bias coefficient of GNSS time scale relative to UTC time scale (seconds) [4,5,6,7]. Scale factor $2^{-35}$ seconds.
<b>utcA1</b> Parameter $A_{1-n}$ , drift coefficient of GNSS time scale relative to UTC time scale (sec/sec) [4,5,6,7]. Scale factor $2^{-51}$ seconds/second.
<b>utcA2</b> Parameter $A_{2-n}$ , drift rate correction coefficient of GNSS time scale relative to UTC time scale (sec/sec <sup>2</sup> ) [4,5,6,7]. Scale factor $2^{-68}$ seconds/second <sup>2</sup> .
<b>utcDeltaTls</b> Parameter $\Delta t_{LS}$ , current or past leap second count (seconds) [4,5,6,7]. Scale factor 1 second.
<b>utcTot</b> Parameter $t_{ot}$ , time data reference time of week (seconds) [4,5,6,7]. Scale factor $2^4$ seconds.
<b>utcWNot</b> Parameter $WN_{ot}$ , time data reference week number (weeks) [4,5,6,7]. Scale factor 1 week.
<b>utcWNlsf</b> Parameter $WN_{LSF}$ , leap second reference week number (weeks) [4,5,6,7]. Scale factor 1 week.
<b>utcDN</b> Parameter DN, leap second reference day number (days) [4,5,6,7]. Scale factor 1 day.



<i>UTC-ModelSet2</i> field descriptions
<p><b>utcDeltaTlsf</b>                      Parameter <math>\Delta t_{LSF}</math>, current or future leap second count (seconds) [4,5,6,7].                      Scale factor 1 second.</p>

– *UTC-ModelSet3*

```

-- ASN1START
UTC-ModelSet3 ::= SEQUENCE {
    nA          INTEGER (1..1461),
    tauC        INTEGER (-2147483648..2147483647),
    b1          INTEGER (-1024..1023)          OPTIONAL, -- Cond GLONASS-M
    b2          INTEGER (-512..511)           OPTIONAL, -- Cond GLONASS-M
    kp          BIT STRING (SIZE(2))          OPTIONAL, -- Cond GLONASS-M
    ...
}
-- ASN1STOP
    
```

Conditional presence	Explanation
GLONASS-M	The field is mandatory present if GLONASS-M satellites are present in the current GLONASS constellation; otherwise it is not present.

<i>UTC-ModelSet3</i> field descriptions
<p><b>nA</b>                      Parameter <math>N^A</math>, calendar day number within four-year period beginning since the leap year (days) [9].                      Scale factor 1 day.</p>
<p><b>tauC</b>                      Parameter <math>\tau_c</math>, GLONASS time scale correction to UTC(SU) (seconds) [9].                      Scale factor <math>2^{-31}</math> seconds.</p>
<p><b>b1</b>                      Parameter B1, coefficient to determine <math>\Delta UT1</math> (seconds) [9].                      Scale factor <math>2^{10}</math> seconds.</p>
<p><b>b2</b>                      Parameter B2, coefficient to determine <math>\Delta UT1</math> (seconds/msd) [9].                      Scale factor <math>2^{16}</math> seconds/msd.</p>
<p><b>kp</b>                      Parameter KP, notification of expected leap second correction (dimensionless) [9].</p>

– *UTC-ModelSet4*

```

-- ASN1START
UTC-ModelSet4 ::= SEQUENCE {
    utcA1wnt    INTEGER (degreesMaximumNegative..degreesMaximum),
    utcA0wnt    INTEGER (-2147483648..2147483647),
    utcTot      INTEGER (0..255),
    utcWNt      INTEGER (0..255),
    utcDeltaTls INTEGER (-128..127),
    utcWNlsf    INTEGER (0..255),
    utcDN       INTEGER (-128..127),
    utcDeltaTlsf INTEGER (-128..127),
    utcStandardID INTEGER (0..7),
    ...
}
-- ASN1STOP
    
```

<i>UTC-ModelSet4</i> field descriptions
<p><b>utcA1wnt</b>                      Parameter <math>A_{1WNT}</math>, sec/sec ([10], Message Type 12).                      Scale factor <math>2^{50}</math> seconds/second.</p>

<i>UTC-ModelSet4</i> field descriptions
<p><b><i>utcA0wnt</i></b>                      Parameter <math>A_{0WNT}</math>, seconds ([10], Message Type 12).                      Scale factor <math>2^{-30}</math> seconds.</p>
<p><b><i>utcTot</i></b>                      Parameter <math>t_{ot}</math>, seconds ([10], Message Type 12).                      Scale factor <math>2^{12}</math> seconds.</p>
<p><b><i>utcWNt</i></b>                      Parameter <math>W_{Nt}</math>, weeks ([10], Message Type 12).                      Scale factor 1 week.</p>
<p><b><i>utcDeltaTIs</i></b>                      Parameter <math>\Delta t_{LS}</math>, seconds ([10], Message Type 12).                      Scale factor 1 second.</p>
<p><b><i>utcWNIsf</i></b>                      Parameter <math>W_{NLSF}</math>, weeks ([10], Message Type 12).                      Scale factor 1 week.</p>
<p><b><i>utcDN</i></b>                      Parameter DN, days ([10], Message Type 12).                      Scale factor 1 day.</p>
<p><b><i>utcDeltaTIsf</i></b>                      Parameter <math>\Delta t_{LSF}</math>, seconds ([10], Message Type 12).                      Scale factor 1 second.</p>
<p><b><i>utcStandardID</i></b>                      If <i>GNSS-ID</i> indicates 'sbas', this field indicates the UTC standard used for the SBAS network time indicated by <i>SBAS-ID</i> to UTC relation as defined as ([7], Message Type 12) in the table Value of UTC Standard ID to UTC Standard relation shown below.</p>

**Value of UTC Standard ID to UTC Standard relation**

Value of UTC Standard ID	UTC Standard
0	UTC as operated by the Communications Research Laboratory (CRL), Tokyo, Japan
1	UTC as operated by the National Institute of Standards and Technology (NIST)
2	UTC as operated by the U. S. Naval Observatory (USNO)
3	UTC as operated by the International Bureau of Weights and Measures (BIPM)
4-7	Reserved for future definition

***GNSS-AuxiliaryInformation***

The IE *GNSS-AuxiliaryInformation* is used by the location server to provide additional information dependent on the *GNSS-ID*. If *GNSS-AuxiliaryInformation* is provided together with other satellite dependent GNSS assistance data (i.e., any of *GNSS-DifferentialCorrections*, *GNSS-NavigationModel*, *GNSS-DataBitAssistance*, or *GNSS-AcquisitionAssistance* IEs) and LPP pseudo-segmentation is used, the *GNSS-AuxiliaryInformation* should be provided for the same satellites and in the same LPP segment as the other satellite dependent GNSS assistance data.

```

-- ASN1START
GNSS-AuxiliaryInformation ::= CHOICE {
    gnss-ID-GPS          GNSS-ID-GPS,
    gnss-ID-GLONASS     GNSS-ID-GLONASS,
    ...
}

GNSS-ID-GPS ::= SEQUENCE (SIZE(1..64)) OF GNSS-ID-GPS-SatElement

GNSS-ID-GPS-SatElement ::= SEQUENCE {
    svID                SV-ID,
    signalsAvailable    GNSS-SignalIDs,
    ...
}

GNSS-ID-GLONASS ::= SEQUENCE (SIZE(1..64)) OF GNSS-ID-GLONASS-SatElement

GNSS-ID-GLONASS-SatElement ::= SEQUENCE {
    svID                SV-ID,
    signalsAvailable    GNSS-SignalIDs,
    channelNumber       INTEGER (-7..13) OPTIONAL, -- Cond FDMA

```

```

...
}
-- ASN1STOP

```

Conditional presence	Explanation
FDMA	The field is mandatory present if the GLONASS SV indicated by <i>svID</i> broadcasts FDMA signals; otherwise it is not present.

<b>GNSS-AuxiliaryInformation field descriptions</b>	
<b>gnss-ID-GPS</b>	This choice may only be present if <i>GNSS-ID</i> indicates GPS.
<b>gnss-ID-GLONASS</b>	This choice may only be present if <i>GNSS-ID</i> indicates GLONASS.
<b>svID</b>	This field specifies the GNSS SV for which the <i>GNSS-AuxiliaryInformation</i> is given.
<b>signalsAvailable</b>	This field indicates the ranging signals supported by the satellite indicated by <i>svID</i> . This field is given as a bit string as defined in <i>GNSS-SignalIDs</i> for a particular GNSS. If a bit is set to '1' it indicates that the satellite identified by <i>svID</i> transmits ranging signals according to the signal correspondence in <i>GNSS-SignalIDs</i> . If a bit is set to '0' it indicates that the corresponding signal is not supported on the satellite identified by <i>svID</i> .
<b>channelNumber</b>	This field indicates the GLONASS carrier frequency number of the satellite identified by <i>svID</i> , as defined in [9].

### 6.5.2.3 GNSS Assistance Data Request

#### – *A-GNSS-RequestAssistanceData*

The IE *A-GNSS-RequestAssistanceData* is used by the target device to request GNSS assistance data from a location server.

```

-- ASN1START
A-GNSS-RequestAssistanceData ::= SEQUENCE {
    gnss-CommonAssistDataReq    GNSS-CommonAssistDataReq    OPTIONAL, -- Cond CommonADReq
    gnss-GenericAssistDataReq   GNSS-GenericAssistDataReq   OPTIONAL, -- Cond GenADReq
    ...
}
-- ASN1STOP

```

Conditional presence	Explanation
<i>CommonADReq</i>	The field is mandatory present if the target device requests <i>GNSS-CommonAssistData</i> ; otherwise it is not present.
<i>GenADReq</i>	This field is mandatory present if the target device requests <i>GNSS-GenericAssistData</i> for one or more specific GNSS; otherwise it is not present.

#### – *GNSS-CommonAssistDataReq*

The IE *GNSS-CommonAssistDataReq* is used by the target device to request assistance data that are applicable to any GNSS from a location server.

```

-- ASN1START
GNSS-CommonAssistDataReq ::= SEQUENCE {
    gnss-ReferenceTimeReq      GNSS-ReferenceTimeReq      OPTIONAL, -- Cond RefTimeReq
    gnss-ReferenceLocationReq  GNSS-ReferenceLocationReq  OPTIONAL, -- Cond RefLocReq
    gnss-IonosphericModelReq   GNSS-IonosphericModelReq   OPTIONAL, -- Cond IonoModReq
    gnss-EarthOrientationParametersReq GNSS-EarthOrientationParametersReq OPTIONAL, -- Cond EOPReq
    ...
}
-- ASN1STOP

```

```
}
-- ASN1STOP
```

Conditional presence	Explanation
<i>RefTimeReq</i>	The field is mandatory present if the target device requests <i>GNSS-ReferenceTime</i> ; otherwise it is not present.
<i>RefLocReq</i>	This field is mandatory present if the target device requests <i>GNSS-ReferenceLocation</i> ; otherwise it is not present.
<i>IonoModReq</i>	This field is mandatory present if the target device requests <i>GNSS-IonosphericModel</i> ; otherwise it is not present.
<i>EOPReq</i>	This field is mandatory present if the target device requests <i>GNSS-EarthOrientationParameters</i> ; otherwise it is not present.

## – GNSS-GenericAssistDataReq

The IE *GNSS-GenericAssistDataReq* is used by the target device to request assistance data from a location server for one or more specific GNSS (e.g., GPS, Galileo, GLONASS, etc.). The specific GNSS for which the assistance data are requested is indicated by the IE *GNSS-ID* and (if applicable) by the IE *SBAS-ID*. Assistance for up to 16 GNSSs can be requested.

```
-- ASN1START
GNSS-GenericAssistDataReq ::= SEQUENCE (SIZE (1..16)) OF GNSS-GenericAssistDataReqElement
GNSS-GenericAssistDataReqElement ::= SEQUENCE {
  gnss-ID                GNSS-ID,
  sbas-ID                SBAS-ID                                OPTIONAL, -- Cond GNSS-ID-SBAS
  gnss-TimeModelsReq    GNSS-TimeModelListReq                OPTIONAL, -- Cond TimeModReq
  gnss-DifferentialCorrectionsReq GNSS-DifferentialCorrectionsReq    OPTIONAL, -- Cond DGNSS-Req
  gnss-NavigationModelReq GNSS-NavigationModelReq                OPTIONAL, -- Cond NavModReq
  gnss-RealTimeIntegrityReq GNSS-RealTimeIntegrityReq            OPTIONAL, -- Cond RTIReq
  gnss-DataBitAssistanceReq GNSS-DataBitAssistanceReq            OPTIONAL, -- Cond DataBitsReq
  gnss-AcquisitionAssistanceReq GNSS-AcquisitionAssistanceReq        OPTIONAL, -- Cond AcquAssistReq
  gnss-AlmanacReq       GNSS-AlmanacReq                        OPTIONAL, -- Cond AlmanacReq
  gnss-UTCModelReq      GNSS-UTC-ModelReq                      OPTIONAL, -- Cond UTCModReq
  gnss-AuxiliaryInformationReq GNSS-AuxiliaryInformationReq        OPTIONAL, -- Cond AuxInfoReq
  ...
}
-- ASN1STOP
```

Conditional presence	Explanation
<i>GNSS-ID-SBAS</i>	The field is mandatory present if the <i>GNSS-ID = sbas</i> ; otherwise it is not present.
<i>TimeModReq</i>	The field is mandatory present if the target device requests <i>GNSS-TimeModelList</i> ; otherwise it is not present.
<i>DGNSS-Req</i>	The field is mandatory present if the target device requests <i>GNSS-DifferentialCorrections</i> ; otherwise it is not present.
<i>NavModReq</i>	The field is mandatory present if the target device requests <i>GNSS-NavigationModel</i> ; otherwise it is not present.
<i>RTIReq</i>	The field is mandatory present if the target device requests <i>GNSS-RealTimeIntegrity</i> ; otherwise it is not present.
<i>DataBitsReq</i>	The field is mandatory present if the target device requests <i>GNSS-DataBitAssistance</i> ; otherwise it is not present.
<i>AcquAssistReq</i>	The field is mandatory present if the target device requests <i>GNSS-AcquisitionAssistance</i> ; otherwise it is not present.
<i>AlmanacReq</i>	The field is mandatory present if the target device requests <i>GNSS-Almanac</i> ; otherwise it is not present.
<i>UTCModReq</i>	The field is mandatory present if the target device requests <i>GNSS-UTCModel</i> ; otherwise it is not present.
<i>AuxInfoReq</i>	The field is mandatory present if the target device requests <i>GNSS-AuxiliaryInformation</i> ; otherwise it is not present.

## 6.5.2.4 GNSS Assistance Data Request Elements

### – GNSS-ReferenceTimeReq

The IE *GNSSReferenceTimeReq* is used by the target device to request the *GNSSReferenceTime* assistance from the location server.

```
-- ASN1START
GNSS-ReferenceTimeReq ::= SEQUENCE {
    gnss-TimeReqPrefList    SEQUENCE (SIZE (1..8)) OF GNSS-ID,
    gps-TOW-assistReq       BOOLEAN                OPTIONAL, -- Cond gps
    notOfLeapSecReq         BOOLEAN                OPTIONAL, -- Cond glonass
    ...
}
-- ASN1STOP
```

Conditional presence	Explanation
<i>gps</i>	The field is mandatory present if <i>gnss-TimeReqPrefList</i> includes a <i>GNSS-ID</i> = 'gps'; otherwise it is not present.
<i>glonass</i>	The field is mandatory present if <i>gnss-TimeReqPrefList</i> includes a <i>GNSS-ID</i> = 'glonass'; otherwise it is not present.

#### GNSS-ReferenceTimeReq field descriptions

<b><i>gnss-TimeReqPrefList</i></b> This field is used by the target device to request the system time for one or more specific GNSSs, specified by GNSS-ID in the order of preference. The first <i>GNSS-ID</i> in the list is the most preferred GNSS for reference time, the second <i>GNSS-ID</i> is the second most preferred, etc.
<b><i>gps-TOW-assistReq</i></b> This field is used by the target device to request the <i>gps-TOW-Assist</i> field in <i>GNSS-SystemTime</i> . TRUE means requested.
<b><i>notOfLeapSecReq</i></b> This field is used by the target device to request the <i>notificationOfLeapSecond</i> field in <i>GNSS-SystemTime</i> . TRUE means requested.

### – GNSS-ReferenceLocationReq

The IE *GNSS-ReferenceLocationReq* is used by the target device to request the *GNSS-ReferenceLocation* assistance from the location server.

```
-- ASN1START
GNSS-ReferenceLocationReq ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### – GNSS-IonosphericModelReq

The IE *GNSS-IonosphericModelReq* is used by the target device to request the *GNSS-IonosphericModel* assistance from the location server.

```
-- ASN1START
GNSS-IonosphericModelReq ::= SEQUENCE {
    klobucharModelReq       BIT STRING (SIZE(2))    OPTIONAL, -- Cond klobuchar
    neQuickModelReq         NULL                    OPTIONAL, -- Cond nequick
    ...
}
-- ASN1STOP
```

Conditional presence	Explanation
<i>klobuchar</i>	The field is mandatory present if the target device requests <i>klobucharModel</i> ; otherwise it is not present. The BIT STRING defines the dataID requested, defined in IE <i>KlobucharModelParameter</i> .
<i>nequick</i>	The field is mandatory present if the target device requests <i>neQuickModel</i> ; otherwise it is not present.

### – *GNSS-EarthOrientationParametersReq*

The IE *GNSS-EarthOrientationParametersReq* is used by the target device to request the *GNSS-EarthOrientationParameters* assistance from the location server.

```
-- ASN1START
GNSS-EarthOrientationParametersReq ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### – *GNSS-TimeModelListReq*

The IE *GNSSTimeModelListReq* is used by the target device to request the *GNSS-TimeModelElement* assistance from the location server.

```
-- ASN1START
GNSS-TimeModelListReq ::= SEQUENCE (SIZE(1..15)) OF GNSS-TimeModelElementReq
GNSS-TimeModelElementReq ::= SEQUENCE {
    gnss-TO-IDsReq  INTEGER (1..15),
    deltaTreq       BOOLEAN,
    ...
}
-- ASN1STOP
```

#### *GNSS-TimeModelElementReq* field descriptions

##### ***gnss-TO-IDsReq***

This field specifies the requested *gnss-TO-ID*. The meaning and encoding is the same as the *gnss-TO-ID* field in the *GNSSTimeModelElement* IE.

##### ***deltaTreq***

This field specifies whether or not the location server is requested to include the *deltaT* field in the *GNSS-TimeModelElement* IE. TRUE means requested.

### – *GNSS-DifferentialCorrectionsReq*

The IE *GNSSDifferentialCorrectionsReq* is used by the target device to request the *GNSS-DifferentialCorrections* assistance from the location server.

```
-- ASN1START
GNSS-DifferentialCorrectionsReq ::= SEQUENCE {
    dgnss-SignalsReq  GNSS-SignalIDs,
    dgnss-ValidityTimeReq  BOOLEAN,
    ...
}
-- ASN1STOP
```

#### *GNSS-DifferentialCorrectionsReq* field descriptions

**GNSS-DifferentialCorrectionsReq field descriptions****dgNSS-SignalsReq**

This field specifies the GNSS Signal(s) for which the *GNSS-DifferentialCorrections* are requested. A one-value at a bit position means DGNSS corrections for the specific signal are requested; a zero-value means not requested. The target device shall set a maximum of three bits to value 'one'.

**dgNSS-ValidityTimeReq**

This field specifies whether the *udreGrowthRate* and *udreValidityTime* in *GNSS-DifferentialCorrections* are requested or not. TRUE means requested.

**GNSS-NavigationModelReq**

The IE *GNSS-NavigationModelReq* is used by the target device to request the *GNSS-NavigationModel* assistance from the location server.

```
-- ASN1START

GNSS-NavigationModelReq ::= CHOICE {
    storedNavList      StoredNavListInfo,
    reqNavList         ReqNavListInfo,
    ...
}

StoredNavListInfo ::= SEQUENCE {
    gnss-WeekOrDay      INTEGER (0..4095),
    gnss-Toe            INTEGER (0..255),
    t-toeLimit          INTEGER (0..15),
    satListRelatedDataList  SatListRelatedDataList OPTIONAL,
    ...
}

SatListRelatedDataList ::= SEQUENCE (SIZE (1..64)) OF SatListRelatedDataElement

SatListRelatedDataElement ::= SEQUENCE {
    svID                SV-ID,
    iod                 BIT STRING (SIZE(11)),
    clockModelID        INTEGER (1..8) OPTIONAL,
    orbitModelID        INTEGER (1..8) OPTIONAL,
    ...
}

ReqNavListInfo ::= SEQUENCE {
    svReqList           BIT STRING (SIZE (64)),
    clockModelID-PrefList SEQUENCE (SIZE (1..8)) OF INTEGER (1..8) OPTIONAL,
    orbitModelID-PrefList SEQUENCE (SIZE (1..8)) OF INTEGER (1..8) OPTIONAL,
    addNavparamReq      BOOLEAN OPTIONAL, -- Cond orbitModelID-2
    ...
}

-- ASN1STOP
```

Conditional presence	Explanation
<i>orbitModelID-2</i>	The field is mandatory present if <i>orbitModelID-PrefList</i> is absent or includes a Model-ID = '2'; otherwise it is not present.

**GNSS-NavigationModelReq field descriptions****storedNavList**

This list provides information to the location server about which *GNSS-NavigationModel* data the target device has currently stored for the particular GNSS indicated by *GNSS-ID*.

**reqNavList**

This list provides information to the location server which *GNSS-NavigationModel* data are requested by the target device.

**gnss-WeekOrDay**

If *GNSS-ID* does not indicate 'glonass', this field defines the GNSS Week number of the assistance currently held by the target device.

If *GNSS-ID* is set to 'glonass', this field defines the calendar number of day within the four-year interval starting from 1<sup>st</sup> of January in a leap year, as defined by the parameter  $N_T$  in [9] of the assistance currently held by the target device.

<b>GNSS-NavigationModelReq field descriptions</b>	
<b>gnss-Toe</b>	If <i>GNSS-ID</i> does not indicate 'glonass', this field defines the GNSS time of ephemeris in hours of the latest ephemeris set contained by the target device. If <i>GNSS-ID</i> is set to 'glonass', this field defines the time of ephemeris in units of 15 minutes of the latest ephemeris set contained by the target device (range 0 to 95 representing time values between 0 and 1425 minutes). In this case, values 96 to 255 shall not be used by the sender.
<b>t-toeLimit</b>	If <i>GNSS-ID</i> does not indicate 'glonass', this IE defines the ephemeris age tolerance of the target device in units of hours. If <i>GNSS-ID</i> is set to 'glonass', this IE defines the ephemeris age tolerance of the target device in units of 30 minutes.
<b>satListRelatedDataList</b>	This list defines the clock and orbit models currently held by the target device for each SV. This field is not included if the target device does not have any stored clock and orbit models for any SV.
<b>svID</b>	This field identifies the particular GNSS satellite.
<b>iod</b>	This field identifies the issue of data currently held by the target device.
<b>clockModelID, orbitModelID</b>	These fields define the clock and orbit model number currently held by the target device. If these fields are absent, the default interpretation of the table GNSS-ID to clockModelID & orbitModelID relation below applies.
<b>svReqList</b>	This field defines the SV for which the navigation model assistance is requested. Each bit position in this BIT STRING represents a <i>SV-ID</i> . Bit 1 represents <i>SV-ID</i> =1 and bit 64 represents <i>SV-ID</i> =64. A one-value at a bit position means the navigation model data for the corresponding <i>SV-ID</i> is requested, a zero-value means not requested.
<b>clockModelIDPrefList, orbitModelID-PrefList</b>	These fields define the Model-IDs of the clock and orbit models that the target device wishes to obtain in the order of preference. The first Model-ID in the list is the most preferred model, the second Model-ID the second most preferred, etc. If these fields are absent, the default interpretation of the table GNSS-ID to clockModelID-PrefList & orbitModelIDPrefList relation below applies.
<b>addNavparamReq</b>	This field specifies whether the location server is requested to include the <i>addNAVparam</i> fields in <i>GNSS-NavigationModel</i> IE ( <i>NavModel-NAVKeplerianSet</i> field) or not. TRUE means requested.

#### GNSS-ID to clockModelID & orbitModelID relation

<b>GNSS-ID</b>	<b>clockModelID</b>	<b>orbitModelID</b>
gps	2	2
sbas	5	5
qzss	2	2
galileo	1	1
glonass	4	4

#### GNSS-ID to clockModelID-PrefList & orbitModelID-PrefList relation

<b>GNSS-ID</b>	<b>clockModelID-PrefList</b>	<b>orbitModelID-PrefList</b>
gps	Model-2	Model-2
sbas	Model-5	Model-5
qzss	Model-2	Model-2
galileo	Model-1	Model-1
glonass	Model-4	Model-4

#### – GNSS-RealTimeIntegrityReq

The IE *GNSS-RealTimeIntegrityReq* is used by the target device to request the *GNSS-RealTimeIntegrity* assistance from the location server.

```
-- ASN1START
GNSS-RealTimeIntegrityReq ::= SEQUENCE {
    ...
}
```



```
-- ASN1STOP
```

### – GNSS-DataBitAssistanceReq

The IE *GNSS-DataBitAssistanceReq* is used by the target device to request the *GNSS-DataBitAssistance* assistance from the location server.

```
-- ASN1START
GNSS-DataBitAssistanceReq ::= SEQUENCE {
  gnss-TOD-Req      INTEGER (0..3599),
  gnss-TOD-FracReq  INTEGER (0..999)      OPTIONAL,
  dataBitInterval   INTEGER (0..15),
  gnss-SignalType   GNSS-SignalIDs,
  gnss-DataBitsReq  GNSS-DataBitsReqSatList OPTIONAL,
  ...
}
GNSS-DataBitsReqSatList ::= SEQUENCE (SIZE(1..64)) OF GNSS-DataBitsReqSatElement
GNSS-DataBitsReqSatElement ::= SEQUENCE {
  svID              SV-ID,
  ...
}
-- ASN1STOP
```

#### GNSS-DataBitAssistanceReq field descriptions

##### **gnss-TOD-Req**

This field specifies the reference time for the first data bit requested in GNSS specific system time, modulo 1 hour. Scale factor 1 second.

##### **gnss-TOD-FracReq**

This field specifies the fractional part of *gnss-TOD-Req* in 1-milli-second resolution. Scale factor 1 millisecond.

##### **dataBitInterval**

This field specifies the time length for which the Data Bit Assistance is requested. The *GNSS-DataBitAssistance* shall be relative to the time interval (*gnss-TOD-Req*, *gnss-TOD-Req* + *dataBitInterval*).

The *dataBitInterval* *r*, expressed in seconds, is mapped to a binary number *K* with the following formula:

$$r = 0.1 \times 2^K$$

Value *K*=15 means that the time interval is not specified.

##### **gnss-SignalType**

This field specifies the GNSS Signal(s) for which the *GNSS-DataBitAssistance* are requested. A one-value at a bit position means *GNSS-DataBitAssistance* for the specific signal is requested; a zero-value means not requested.

##### **gnss-DataBitsReq**

This list contains the SV-IDs for which the *GNSS-DataBitAssistance* is requested.

### – GNSS-AcquisitionAssistanceReq

The IE *GNSS-AcquisitionAssistanceReq* is used by the target device to request the *GNSS-AcquisitionAssistance* assistance from the location server.

```
-- ASN1START
GNSS-AcquisitionAssistanceReq ::= SEQUENCE {
  gnss-SignalID-Req  GNSS-SignalID,
  ...
}
-- ASN1STOP
```

#### GNSS-AcquisitionAssistanceReq field descriptions

##### **gnss-SignalID-Req**

This field specifies the GNSS signal type for which *GNSSAcquisitionAssistance* is requested.

## – GNSS-AlmanacReq

The IE *GNSS-AlmanacReq* is used by the target device to request the *GNSS-Almanac* assistance from the location server.

```
-- ASN1START
GNSS-AlmanacReq ::= SEQUENCE {
    modelID          INTEGER (1..8)    OPTIONAL,
    ...
}
-- ASN1STOP
```

### GNSS-AlmanacReq field descriptions

#### **modelID**

This field specifies the Almanac Model ID requested. If this field is absent, the default interpretation as in the table GNSS-ID to modelID relation below applies.

#### GNSS-ID to modelID relation

<b>GNSS-ID</b>	<b>modelID</b>
gps	2
sbas	6
qzss	2
galileo	1
glonass	5

## – GNSS-UTC-ModelReq

The IE *GNSS-UTC-ModelReq* is used by the target device to request the *GNSS-UTC-Model* assistance from the location server.

```
-- ASN1START
GNSS-UTC-ModelReq ::= SEQUENCE {
    modelID          INTEGER (1..8)    OPTIONAL,
    ...
}
-- ASN1STOP
```

### GNSS-UTC-ModelReq field descriptions

#### **modelID**

This field specifies the *GNSS-UTCModel* set requested. If this field is absent, the default interpretation as in the table GNSS-ID to modelID relation below applies.

#### GNSS-ID to modelID relation

<b>GNSS-ID</b>	<b>modelID</b>
gps	1
sbas	4
qzss	1
galileo	1
glonass	3

## – GNSS-AuxiliaryInformationReq

The IE *GNSS-AuxiliaryInformationReq* is used by the target device to request the *GNSS-AuxiliaryInformation* assistance from the location server.

```
-- ASN1START
GNSS-AuxiliaryInformationReq ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### 6.5.2.5 GNSS Location Information

#### – *A-GNSS-ProvideLocationInformation*

The IE *A-GNSS-ProvideLocationInformation* is used by the target device to provide location measurements (e.g., pseudo-ranges, location estimate, velocity) to the location server, together with time information. It may also be used to provide GNSS positioning specific error reason.

```
-- ASN1START
A-GNSS-ProvideLocationInformation ::= SEQUENCE {
    gnss-SignalMeasurementInformation    GNSS-SignalMeasurementInformation    OPTIONAL,
    gnss-LocationInformation              GNSS-LocationInformation              OPTIONAL,
    gnss-Error                            A-GNSS-Error                            OPTIONAL,
    ...
}
-- ASN1STOP
```

### 6.5.2.6 GNSS Location Information Elements

#### – *GNSS-SignalMeasurementInformation*

The IE *GNSS-SignalMeasurementInformation* is used by the target device to provide GNSS signal measurement information to the location server and GNSS-network time association if requested by the location server. This information includes the measurements of code phase, Doppler,  $C/N_0$  and optionally accumulated carrier phase, also called accumulated deltarange (ADR), which enable the UE-assisted GNSS method where position is computed in the location server. Figure 6.5.2.6-1 illustrates the relation between some of the fields.

```
-- ASN1START
GNSS-SignalMeasurementInformation ::= SEQUENCE {
    measurementReferenceTime    MeasurementReferenceTime,
    gnss-MeasurementList        GNSS-MeasurementList,
    ...
}
-- ASN1STOP
```

#### **GNSS-SignalMeasurementInformation field descriptions**

##### ***measurementReferenceTime***

This field specifies the GNSS system time for which the information provided in *gnss-MeasurementList* is valid. It may also include network time, if requested by the location server and supported by the target device.

##### ***gnss-MeasurementList***

This field provides GNSS signal measurement information for up to 16 GNSSs.

#### – *MeasurementReferenceTime*

The IE *MeasurementReferenceTime* is used to specify the time when the measurements provided in *A-GNSS-Provide-Location-Information* are valid. It may also include GNSS-network time association, in which case reported measurements shall be valid for the cellular frame boundary defined in the network time association.

```
-- ASN1START
MeasurementReferenceTime ::= SEQUENCE {
```

```

gnss-TOD-msec      INTEGER (0..3599999),
gnss-TOD-frac      INTEGER (0..3999)          OPTIONAL,
gnss-TOD-unc       INTEGER (0..127)          OPTIONAL,
gnss-TimeID        GNSS-ID,
networkTime        CHOICE {
  eUTRA            SEQUENCE {
    physCellId      INTEGER (0..503),
    cellGlobalId    CellGlobalIdEUTRA-AndUTRA  OPTIONAL,
    systemFrameNumber BIT STRING (SIZE (10)),
    ...
  },
  uTRA            SEQUENCE {
    mode            CHOICE {
      fdd          SEQUENCE {
        primary-CPICH-Info INTEGER (0..511),
        ...
      },
      tdd          SEQUENCE {
        cellParameters  INTEGER (0..127),
        ...
      }
    },
    cellGlobalId    CellGlobalIdEUTRA-AndUTRA  OPTIONAL,
    referenceSystemFrameNumber
      INTEGER (0..4095),
    ...
  },
  gSM            SEQUENCE {
    bcchCarrier     INTEGER (0..1023),
    bsic            INTEGER (0..63),
    cellGlobalId    CellGlobalIdGERAN          OPTIONAL,
    referenceFrame   SEQUENCE {
      referenceFN     INTEGER (0..65535),
      referenceFNMSB  INTEGER (0..63)         OPTIONAL,
      ...
    },
    deltaGNSS-TOD   INTEGER (0..127)          OPTIONAL,
    ...
  },
  ...
}
OPTIONAL,
...
}
-- ASN1STOP

```

#### MeasurementReferenceTime field descriptions

##### **gnss-TOD-msec**

This field specifies the GNSS TOD for which the measurements and/or location estimate are valid. The 22 bits of GNSS TOD are the least significant bits. The most significant bits shall be derived by the location server to unambiguously derive the GNSS TOD.

The value for GNSS TOD is derived from the GNSS specific system time indicated in *gnss-TimeID* rounded down to the nearest millisecond unit.

Scale factor 1 millisecond.

##### **gnss-TOD-frac**

This field specifies the fractional part of the GNSS TOD in 250 ns resolution. The total GNSS TOD is given by *gnss-TOD-msec* + *gnss-TOD-frac*.

Scale factor 250 nanoseconds.

##### **gnss-TOD-unc**

This field provides the accuracy of the relation GNSS-network time when GNSS-network time association is provided. When GNSS-network time association is not provided, this element can be included to provide the accuracy of the reported *gnss-TOD-msec*.

If GNSS TOD is the given GNSS time, then the true GNSS time, corresponding to the provided network time if applicable, as observed at the target device location, lies in the interval [GNSS TOD – *gnss-TOD-unc*, GNSS TOD + *gnss-TOD-unc*].

The uncertainty *r*, expressed in microseconds, is mapped to a number *K*, with the following formula:

$$r = C * (((1+x)^K) - 1)$$

with *C* = 0.5 and *x* = 0.14. To encode any higher value of uncertainty than that corresponding in the above formula to *K*=127, the same value, *K*=127, shall also be used. The uncertainty is then coded on 7 bits, as the binary encoding of *K*. Examples of *gnss-TOD-unc* value are as in the table Value of *K* to Value of uncertainty relation below.

This field shall be included if the target device provides GNSS-network time relationship.

<b>MeasurementReferenceTime field descriptions</b>
<p><b>gnss-TimeID</b> This field specifies the GNSS system time for which the <i>gnss-TOD-msec</i> (and <i>gnss-TOD-frac</i> if applicable) is provided.</p>
<p><b>networkTime</b> These fields specify the network time event which the GNSS TOD time stamps. This field shall be included if the target device provides GNSS-network time relationship.</p>
<p><b>physCellId</b> This field identifies the reference cell, as defined in [12], that is used for the GNSS-network time relation.</p>
<p><b>cellGlobalId</b> This field specifies the globally unique cell identifier (Evolved Cell Global Identifier (ECGI) in E-UTRA, global UTRAN Cell Identifier in UTRA, or Cell Global Identification (CGI) in GERAN) of the reference cell, as defined in [12] for E-UTRA and [13] for UTRA, for which the GNSS network time relation is provided.</p>
<p><b>systemFrameNumber</b> This field specifies the system frame number in E-UTRA which the GNSS time time stamps, as defined in [12].</p>
<p><b>mode</b> This field identifies the reference cell for the GNSS-network time relation, as defined in [13].</p>
<p><b>referenceSystemFrameNumber</b> This field specifies the system frame number in UTRA, as defined in [13], which is used for time stamping.</p>
<p><b>bcchCarrier, bsic</b> This field identifies the reference cell for the GNSS-network time relation in UTRA, as defined in [14].</p>
<p><b>referenceFN, referenceFNMSB</b> These fields specify the frame number in GERAN which the GNSS time time stamps, as defined in [14]. The time of the reference frame boundary is as observed by the target device, i.e. without Timing Advance compensation. The <i>referenceFNMSB</i> field indicates the most significant bits of the frame number of the reference BTS corresponding to the <i>GNSS-MeasurementList</i>. Starting from the complete GSM frame number denoted FN, the target device calculates Reference FN MSB as <math display="block">\text{Reference FN MSB} = \text{floor}(\text{FN}/42432)</math> The complete GSM frame number FN can then be reconstructed in the location server by combining the fields <i>referenceFN</i> with <i>referenceFNMSB</i> in the following way <math display="block">\text{FN} = \text{referenceFNMSB} * 42432 + \text{referenceFN}</math></p>
<p><b>deltaGNSS-TOD</b> This field specifies the difference in milliseconds between <i>gnss-TOD-msec</i> reported and the milli-second part of the SV time <i>tsv_1</i> of the first SV in the list reported from the target device, as defined in [14]. The <i>deltaGNSS-TOD</i> is defined as <math display="block">\text{deltaGNSS-TOD} = \text{gnss-TOD-msec} - \text{fix}(\text{tsv}_1)</math> where <i>fix()</i> denotes rounding to the nearest integer towards zero.</p>

**Value of K to Value of uncertainty relation**

Value of K	Value of uncertainty
0	0 microseconds
1	0.07 microseconds
2	0.1498 microseconds
-	-
50	349.62 microseconds
-	-
127	≥ 8430000 microseconds

**GNSS-MeasurementList**

The IE *GNSS-MeasurementList* is used by the target device to provide measurements of code phase, Doppler, C/N<sub>0</sub> and optionally accumulated carrier phase, also called accumulated deltarange (ADR).

```

-- ASN1START
GNSS-MeasurementList ::= SEQUENCE (SIZE(1..16)) OF GNSS-MeasurementForOneGNSS
GNSS-MeasurementForOneGNSS ::= SEQUENCE {
    gnss-ID                GNSS-ID,
    gnss-SgnMeasList       GNSS-SgnMeasList,
    ...
}
GNSS-SgnMeasList ::= SEQUENCE (SIZE(1..8)) OF GNSS-SgnMeasElement
    
```

```

GNSS-SgnMeasElement ::= SEQUENCE {
    gnss-SignalID          GNSS-SignalID,
    gnss-CodePhaseAmbiguity INTEGER (0..127)          OPTIONAL,
    gnss-SatMeasList      GNSS-SatMeasList,
    ...
}

GNSS-SatMeasList ::= SEQUENCE (SIZE(1..64)) OF GNSS-SatMeasElement

GNSS-SatMeasElement ::= SEQUENCE {
    svID                  SV-ID,
    cNo                   INTEGER (0..63),
    mpathDet              ENUMERATED {notMeasured (0), low (1), medium (2), high (3), ...},
    carrierQualityInd     INTEGER (0..3)              OPTIONAL,
    codePhase              INTEGER (0..2097151),
    integerCodePhase      INTEGER (0..127)            OPTIONAL,
    codePhaseRMSError     INTEGER (0..63),
    doppler                INTEGER (-32768..32767)    OPTIONAL,
    adr                   INTEGER (0..33554431)        OPTIONAL,
    ...
}

-- ASN1STOP

```

### **GNSS-MeasurementList field descriptions**

<b>gnss-ID</b>	This field identifies the GNSS constellation on which the GNSS signal measurements were measured. Measurement information for up to 16 GNSSs can be included.
<b>gnss-SgnMeasList</b>	This list provides GNSS signal measurement information for up to 8 GNSS signal types per GNSS.
<b>gnss-SignalID</b>	This field identifies the signal on which GNSS signal measurement parameters were measured.
<b>gnss-CodePhaseAmbiguity</b>	This field provides the ambiguity of the code phase measurement. It is given in units of milli-seconds in the range between 0 and 127 milli-seconds. The total code phase for a satellite <i>k</i> (Satk) is given modulo this <i>gnss-CodePhaseAmbiguity</i> and is reconstructed with: $Code\_Phase\_Tot(Satk) = codePhase(Satk) + integerCodePhase(Satk) + n * gnss-CodePhaseAmbiguity$ , $n = 0, 1, 2, \dots$ If there is no code phase ambiguity, the <i>gnss-CodePhaseAmbiguity</i> shall be set to 0. The field is optional. If <i>gnss-CodePhaseAmbiguity</i> is absent, the default value is 1 milli-second.
<b>gnss-SatMeasList</b>	This list provides GNSS signal measurement information for up to 64 GNSS satellites.
<b>svID</b>	This field identifies the satellite on which the GNSS signal measurements were measured.
<b>cNo</b>	This field provides an estimate of the carrier-to-noise ratio of the received signal from the particular satellite. The target device shall set this field to the value of the satellite $C/N_0$ , as referenced to the antenna connector, in units of 1 dB-Hz, in the range from 0 to 63 dB-Hz. Scale factor 1 dB-Hz.
<b>mpathDet</b>	This field contains the multipath indicator value, defined in the table Value of mpathDet to Multipath Indication relation below.
<b>carrierQualityInd</b>	This field indicates the quality of a carrier phase measurement. The LSB indicates the data polarity, that is, if the data from a specific satellite is received inverted, this is indicated by setting the LSB value to '1'. In the case the data is not inverted, the LSB is set to '0'. The MSB indicates if accumulation of the carrier phase has been continuous, that is, without cycle slips since the previous measurement report. If the carrier phase accumulation has been continuous, the MSB value is set to '1X'. Otherwise, the MSB is set to '0X'. This field is optional and shall be included only when carrier phase measurements are provided. See table Bit toPolarity Indication relation below.
<b>codePhase</b>	This field contains the whole and fractional value of the code-phase measurement made by the target device for the particular satellite signal at the time of measurement in the units of ms. GNSS specific code phase measurements (e.g. chips) are converted into unit of ms by dividing the measurements by the nominal values of the measured signal chipping rate. Scale factor $2^{-21}$ milli-seconds, in the range from 0 to $(1-2^{-21})$ milli-seconds.
<b>integerCodePhase</b>	This field indicates the integer milli-second part of the code phase that is expressed modulo the <i>gnss-CodePhaseAmbiguity</i> . The value of the ambiguity is given in the <i>gnss-CodePhaseAmbiguity</i> field. The <i>integerCodePhase</i> is optional. If <i>integerCodePhase</i> is absent, the default value is 0 milli-second. Scale factor 1 milli-second, in the range from 0 to 127 milli-seconds.

<b>GNSS-MeasurementList field descriptions</b>	
<b>codePhaseRMSError</b>	This field contains the pseudorange RMS error value. This parameter is specified according to a floating-point representation shown in the table below.
<b>doppler</b>	This field contains the Doppler measured by the target device for the particular satellite signal. This information can be used to compute the 3-D velocity of the target device. Doppler measurements are converted into unit of m/s by multiplying the Doppler measurement in Hz by the nominal wavelength of the measured signal. Scale factor 0.04 meter/seconds.
<b>adr</b>	This field contains the ADR measurement measured by the target device for the particular satellite signal. This information can be used to compute the 3-D velocity or high-accuracy position of the target device. ADR measurements are converted into units of meter by multiplying the ADR measurement by the nominal wavelength of the measured signal. Scale factor $2^{-10}$ meters, in the range from 0 to 32767.5 meters.

#### Value of mpathDet to Multipath Indication relation

Value of <i>mpathDet</i>	Multipath Indication
00	Not measured
01	Low, MP error < 5m
10	Medium, 5m < MP error < 43m
11	High, MP error > 43m

#### Bit toPolarity Indication relation

Value	Polarity Indication
0	Data Direct, carrier phase not continuous
1	Data Inverted, carrier phase not continuous
2	Data Direct, carrier phase continuous
3	Data Inverted, carrier phase continuous

#### floating-point representation

Index	Mantissa	Exponent	Floating-Point value, $x_i$	Pseudorange value, P
0	000	000	0.5	$P < 0.5$
1	001	000	0.5625	$0.5 \leq P < 0.5625$
l	x	y	$0.5 * (1 + x/8) * 2^y$	$x_{i-1} \leq P < x_i$
62	110	111	112	$104 \leq P < 112$
63	111	111	--	$112 \leq P$

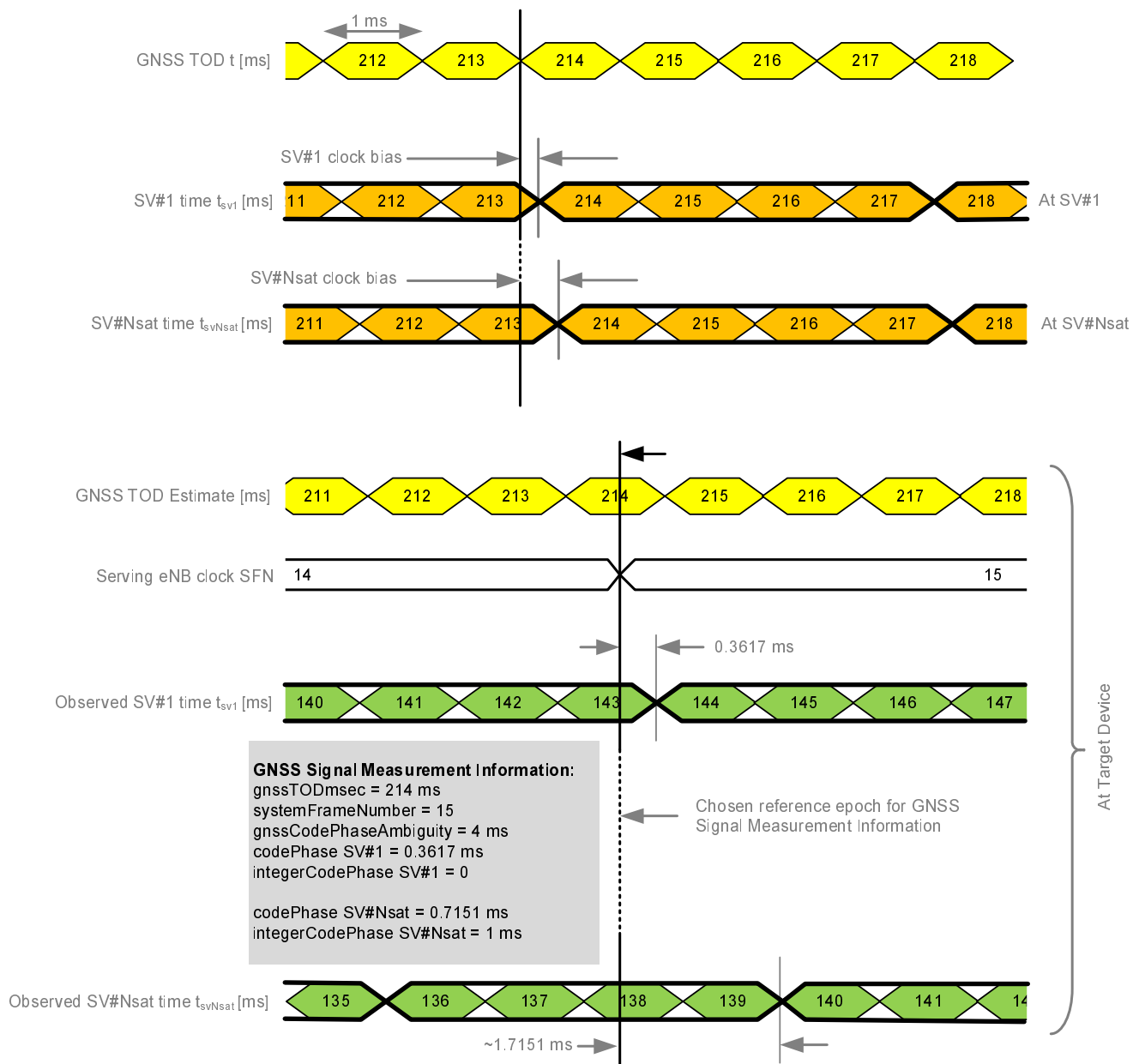


Figure 6.5.2.6-1: Exemplary calculation of some GNSS Signal Measurement Information fields.

*GNSS-LocationInformation*

The IE *GNSS-LocationInformation* is included by the target device when location and optionally velocity information derived using GNSS or hybrid GNSS and other measurements is provided to the location server.

```
-- ASN1START
GNSS-LocationInformation ::= SEQUENCE {
  measurementReferenceTime      MeasurementReferenceTime,
  agnss-List                    GNSS-ID-Bitmap,
  ...
}
-- ASN1STOP
```

**GNSS-LocationInformation field descriptions**



<b>GNSS-LocationInformation field descriptions</b>
<p><b>measurementReferenceTime</b> This field specifies the GNSS system time for which the location estimate and optionally velocity are valid. It may also include GNSS-network time relationship, if requested by the location server and supported by the target device.</p>
<p><b>gnss-List</b> This field provides a list of satellite systems used by the target device to calculate the location estimate and velocity estimate, if included. This is represented by a bit string in <i>GNSS-ID-Bitmap</i>, with a one-value at the bit position means the particular method has been used; a zero-value means not used.</p>

## 6.5.2.7 GNSS Location Information Request

### – *A-GNSS-RequestLocationInformation*

The IE *A-GNSS-RequestLocationInformation* is used by the location server to request location information from the target device using GNSS.

```
-- ASN1START
A-GNSS-RequestLocationInformation ::= SEQUENCE {
    gnss-PositioningInstructions    GNSS-PositioningInstructions,
    ...
}
-- ASN1STOP
```

## 6.5.2.8 GNSS Location Information Request Elements

### – *GNSS-PositioningInstructions*

The IE *GNSS-PositioningInstructions* is used to provide GNSS measurement instructions.

```
-- ASN1START
GNSS-PositioningInstructions ::= SEQUENCE {
    gnss-Methods                GNSS-ID-Bitmap, -- Need ON
    fineTimeAssistanceMeasReq   BOOLEAN,
    adrMeasReq                  BOOLEAN,
    multiFreqMeasReq           BOOLEAN,
    assistanceAvailability      BOOLEAN,
    ...
}
-- ASN1STOP
```

<b>GNSS-PositioningInstructions field descriptions</b>
<p><b>gnssMethods</b> This field indicates the satellite systems allowed by the location server. This is represented by a bit string in <i>GNSS-IDs</i>, with a one-value at the bit position means the particular GNSS is allowed; a zero-value means not allowed. The target device shall not request assistance data or report or obtain measurements for systems that are not indicated in this bit map.</p>
<p><b>fineTimeAssistanceMeasReq</b> This field indicates whether the target device is requested to report GNSS-network time association. TRUE means requested.</p>
<p><b>adrMeasReq</b> This field indicates whether the target device is requested to include ADR measurements in <i>GNSSMeasurementList</i> IE or not. TRUE means requested.</p>
<p><b>multiFreqMeasReq</b> This field indicates whether the target device is requested to report measurements on multiple supported GNSS signal types in <i>GNSSMeasurementList</i> IE or not. TRUE means requested.</p>
<p><b>assistanceAvailability</b> This field indicates whether the target device may request additional GNSS assistance data from the server. TRUE means allowed and FALSE means not allowed.</p>

### 6.5.2.9 GNSS Capability Information

#### – A-GNSS-ProvideCapabilities

The IE *A-GNSS-Provide-Capabilities* is used by the target device to indicate its capability to support A-GNSS and to provide it's A-GNSS location capabilities (e.g., GNSSs and assistance data supported) to the location server.

```

-- ASN1START
A-GNSS-ProvideCapabilities ::= SEQUENCE {
    gnss-SupportList          GNSS-SupportList          OPTIONAL,
    assistanceDataSupportList AssistanceDataSupportList OPTIONAL,
    locationCoordinateTypes   LocationCoordinateTypes  OPTIONAL,
    velocityTypes             VelocityTypes             OPTIONAL,
    ...
}

GNSS-SupportList ::= SEQUENCE (SIZE(1..16)) OF GNSS-SupportElement

GNSS-SupportElement ::= SEQUENCE {
    gnss-ID                  GNSS-ID,
    sbas-IDs                 SBAS-IDs                OPTIONAL,    -- Cond GNSS-ID-SBAS
    agnss-Modes              PositioningModes,
    gnss-Signals             GNSS-SignalIDs,
    fta-MeasSupport          SEQUENCE {
        cellTime             AccessTypes,
        mode                 PositioningModes,
        ...
    } OPTIONAL,    -- Cond fta
    adr-Support              BOOLEAN,
    velocityMeasurementSupport BOOLEAN,
    ...
}

AssistanceDataSupportList ::= SEQUENCE {
    gnss-CommonAssistanceDataSupport GNSS-CommonAssistanceDataSupport,
    gnss-GenericAssistanceDataSupport GNSS-GenericAssistanceDataSupport,
    ...
}

-- ASN1STOP

```

Conditional presence	Explanation
<i>GNSS-ID-SBAS</i>	The field is mandatory present if the <i>GNSS-ID = sbas</i> ; otherwise it is not present.
<i>fta</i>	The field is mandatory present if the target device supports the reporting of fine time assistance measurements; otherwise it is not present.

<b>A-GNSS-ProvideCapabilities field descriptions</b>	
<b><i>gnss-SupportList</i></b>	This field specifies the list of GNSS supported by the target device and the target device capabilities associated with each of the supported GNSS. This field shall be present if the <i>gnss-SupportListReq</i> in the <i>agnss-RequestCapabilities</i> IE is set to TRUE and if the target device supports the A-GNSS positioning method.
<b><i>gnss-ID</i></b>	This field specifies the GNSS supported by the target device for which the capabilities in <i>GNSS-SupportElement</i> are provided. This field shall be included if the target device supports at least one GNSS.
<b><i>sbas-IDs</i></b>	This field specifies the SBAS(s) supported by the target device. This is represented by a bit string, with a one-value at the bit position means the particular SBAS is supported; a zero-value means not supported.
<b><i>agnss-Modes</i></b>	This field specifies the GNSS mode(s) supported by the target device for the GNSS indicated by <i>gnss-ID</i> . This is represented by a bit string, with a one-value at the bit position means the particular GNSS mode is supported; a zero-value means not supported.
<b><i>gnss-Signals</i></b>	This field specifies the GNSS signal(s) supported by the target device for the GNSS indicated by <i>gnss-ID</i> . This is represented by a bit string, with a one-value at the bit position means the particular GNSS signal type is supported; a zero-value means not supported.

<b>A-GNSS-ProvideCapabilities field descriptions</b>
<p><b>fta-MeasSupport</b>                      This field specifies that the target device is capable of performing fine time assistance measurements (i.e., GNSS-cellular time association reporting). The <i>cellTime</i> field specifies for which cellular network(s) this capability is supported. This is represented by a bit string, with a one-value at the bit position means FTA measurements for the specific cellular network time is supported; a zero-value means not supported. The <i>mode</i> field specifies for which GNSS mode(s) FTA measurements are supported by the target device. This is represented by a bit string, with a one-value at the bit position means FTA measurements for the GNSS mode is supported; a zero-value means not supported.</p>
<p><b>adr-Support</b>                      This field specifies whether the target device supports ADR measurement reporting. TRUE means supported.</p>
<p><b>velocityMeasurementSupport</b>                      This field specifies whether the target device supports measurement reporting related to velocity. TRUE means supported.</p>
<p><b>assistanceDataSupportList</b>                      This list defines the assistance data and assistance data choices supported by the target device. This field shall be present if assisted GNSS is supported. This field shall be present if the <i>assistanceDataSupportListReq</i> in the <i>agnss-RequestCapabilities</i> IE is set to TRUE and if the target device supports the assisted GNSS positioning method.</p>
<p><b>locationCoordinateTypes</b>                      This parameter identifies the geographical location coordinate types that a target device supports for GNSS. TRUE indicates that a location coordinate type is supported and FALSE that it is not. This field shall be included if the target device supports UE-based or standalone A-GNSS.</p>
<p><b>velocityTypes</b>                      This parameter identifies the velocity types that a target device supports for GNSS. TRUE indicates that a velocity type is supported and FALSE that it is not. FALSE for all velocity types indicates that velocity is not supported.</p>

### 6.5.2.10 GNSS Capability Information Elements

#### – GNSS-CommonAssistanceDataSupport

The IE *GNSS-CommonAssistanceDataSupport* is used by the target device to provide information on supported GNSS common assistance data types to the location server.

```

-- ASN1START
GNSS-CommonAssistanceDataSupport ::= SEQUENCE {
    gnss-ReferenceTimeSupport          GNSS-ReferenceTimeSupport
                                     OPTIONAL, -- Cond RefTimeSup
    gnss-ReferenceLocationSupport     GNSS-ReferenceLocationSupport
                                     OPTIONAL, -- Cond RefLocSup
    gnss-IonosphericModelSupport      GNSS-IonosphericModelSupport
                                     OPTIONAL, -- Cond IonoModSup
    gnss-EarthOrientationParametersSupport GNSS-EarthOrientationParametersSupport
                                     OPTIONAL, -- Cond EOPSup
    ...
}
-- ASN1STOP
    
```

<b>Conditional presence</b>	<b>Explanation</b>
<i>RefTimeSup</i>	The field is mandatory present if the target device supports <i>GNSS-ReferenceTime</i> ; otherwise it is not present.
<i>RefLocSup</i>	This field is mandatory present if the target device supports <i>GNSS-ReferenceLocation</i> ; otherwise it is not present.
<i>IonoModSup</i>	This field is mandatory present if the target device supports <i>GNSS-IonosphericModel</i> ; otherwise it is not present.
<i>EOPSup</i>	This field is mandatory present if the target device supports <i>GNSS-EarthOrientationParameters</i> ; otherwise it is not present.

#### – GNSS-ReferenceTimeSupport

```

-- ASN1START
GNSS-ReferenceTimeSupport ::= SEQUENCE {
    gnss-SystemTime          GNSS-ID-Bitmap,
    ...
}
    
```

```

    fta-Support      AccessTypes      OPTIONAL, -- Cond fta
    ...
}
-- ASN1STOP

```

Conditional presence	Explanation
<i>fta</i>	The field is mandatory present if the target device supports fine time assistance in <i>GNSSReferenceTime</i> IE; otherwise it is not present.

#### GNSS-ReferenceTimeSupport field descriptions

##### **gnss-SystemTime**

This field specifies the GNSS system time(s) supported by the target device. This is represented by a bit string in *GNSS-ID-Bitmap*, with a one-value at the bit position means the particular GNSS system time is supported; a zero-value means not supported.

##### **fta-Support**

This field specifies that the target device supports fine time assistance (i.e., GNSS-cellular time association) in *GNSS-ReferenceTime* IE. This is represented by a bit string in *AccessTypes*, with a one-value at the bit position means FTA for the specific cellular network time is supported; a zero-value means not supported.

### – GNSS-ReferenceLocationSupport

```

-- ASN1START
GNSS-ReferenceLocationSupport ::= SEQUENCE {
    ...
}
-- ASN1STOP

```

### – GNSS-IonosphericModelSupport

```

-- ASN1START
GNSS-IonosphericModelSupport ::= SEQUENCE {
    ionoModel      BIT STRING {
        klobuchar   (0),
        neQuick     (1) } (SIZE (1..8)),
    ...
}
-- ASN1STOP

```

#### GNSS-IonosphericModelSupport field descriptions

##### **ionoModel**

This field specifies the ionospheric model(s) supported by the target device. This is represented by a bit string, with a one-value at the bit position means the particular ionospheric model is supported; a zero-value means not supported.

### – GNSS-EarthOrientationParametersSupport

```

-- ASN1START
GNSS-EarthOrientationParametersSupport ::= SEQUENCE {
    ...
}
-- ASN1STOP

```

### – GNSS-GenericAssistanceDataSupport

The IE *GNSS-GenericAssistanceDataSupport* is used by the target device to provide information on supported GNSS generic assistance data types to the location server for each supported GNSS.

```

-- ASN1START
GNSS-GenericAssistanceDataSupport ::=
    SEQUENCE (SIZE (1..16)) OF GNSS-GenericAssistDataSupportElement
GNSS-GenericAssistDataSupportElement ::= SEQUENCE {
    gnss-ID                GNSS-ID,
    sbas-ID                SBAS-ID                OPTIONAL, -- Cond GNSS-ID-SBAS
    gnss-TimeModelsSupport GNSS-TimeModelListSupport
                                OPTIONAL, -- Cond TimeModSup
    gnss-DifferentialCorrectionsSupport GNSS-DifferentialCorrectionsSupport
                                OPTIONAL, -- Cond DGNSS-Sup
    gnss-NavigationModelSupport GNSS-NavigationModelSupport
                                OPTIONAL, -- Cond NavModSup
    gnss-RealTimeIntegritySupport GNSS-RealTimeIntegritySupport
                                OPTIONAL, -- Cond RTISup
    gnss-DataBitAssistanceSupport GNSS-DataBitAssistanceSupport
                                OPTIONAL, -- Cond DataBitsSup
    gnss-AcquisitionAssistanceSupport GNSS-AcquisitionAssistanceSupport
                                OPTIONAL, -- Cond AcquAssistSup
    gnss-AlmanacSupport      GNSS-AlmanacSupport
                                OPTIONAL, -- Cond AlmanacSup
    gnss-UTC-ModelSupport    GNSS-UTC-ModelSupport
                                OPTIONAL, -- Cond UTCModSup
    gnss-AuxiliaryInformationSupport GNSS-AuxiliaryInformationSupport
                                OPTIONAL, -- Cond AuxInfoSup
    ...
}
-- ASN1STOP

```

Conditional presence	Explanation
<i>GNSS-ID-SBAS</i>	The field is mandatory present if the <i>GNSS-ID = sbas</i> ; otherwise it is not present.
<i>TimeModSup</i>	The field is mandatory present if the target device supports <i>GNSS-TimeModelList</i> ; otherwise it is not present.
<i>DGNSS-Sup</i>	The field is mandatory present if the target device supports <i>GNSS-DifferentialCorrections</i> ; otherwise it is not present.
<i>NavModSup</i>	The field is mandatory present if the target device supports <i>GNSS-NavigationModel</i> ; otherwise it is not present.
<i>RTISup</i>	The field is mandatory present if the target device supports <i>GNSS-RealTimeIntegrity</i> ; otherwise it is not present.
<i>DataBitsSup</i>	The field is mandatory present if the target device supports <i>GNSS-DataBitAssistance</i> ; otherwise it is not present.
<i>AcquAssistSup</i>	The field is mandatory present if the target device supports <i>GNSS-AcquisitionAssistance</i> ; otherwise it is not present.
<i>AlmanacSup</i>	The field is mandatory present if the target device supports <i>GNSS-Almanac</i> ; otherwise it is not present.
<i>UTCModSup</i>	The field is mandatory present if the target device supports <i>GNSS-UTC-Model</i> ; otherwise it is not present.
<i>AuxInfoSup</i>	The field is mandatory present if the target device supports <i>GNSS-AuxiliaryInformation</i> ; otherwise it is not present.

### – *GNSS-TimeModelListSupport*

```

-- ASN1START
GNSS-TimeModelListSupport ::= SEQUENCE {
    ...
}
-- ASN1STOP

```

### – *GNSS-DifferentialCorrectionSupport*

```

-- ASN1START
GNSS-DifferentialCorrectionsSupport ::= SEQUENCE {
    gnssSignalIDs    GNSS-SignalIDs,
    dgnss-ValidityTimeSup    BOOLEAN,

```

```

    ...
}
-- ASN1STOP

```

#### GNSS-DifferentialCorrectionsSupport field descriptions

##### **gnss-SignalIDs**

This field specifies the GNSS signal types for which differential corrections are supported by the target device. This is represented by a bit string in *GNSS-SignalIDs*, with a one-value at the bit position means differential corrections for the particular GNSS signal type is supported; a zero-value means not supported.

##### **dgnss-ValidityTimeSup**

This field specifies if the target device supports estimation of UDRE based on growth rate and validity time for differential corrections. TRUE means supported.

#### – GNSS-NavigationModelSupport

```

-- ASN1START
GNSS-NavigationModelSupport ::= SEQUENCE {
    clockModel      BIT STRING {
        model-1      (0),
        model-2      (1),
        model-3      (2),
        model-4      (3),
        model-5      (4) } (SIZE (1..8))      OPTIONAL,
    orbitModel      BIT STRING {
        model-1      (0),
        model-2      (1),
        model-3      (2),
        model-4      (3),
        model-5      (4) } (SIZE (1..8))      OPTIONAL,
    ...
}
-- ASN1STOP

```

#### GNSS-NavigationModelSupport field descriptions

##### **clockModel**

This field specifies the *gnss-ClockModel* choice(s) in *GNSS-NavigationModel* IE supported by the target device for the GNSS indicated by *GNSS-ID*. This is represented by a bit string, with a one-value at the bit position means the particular clock model is supported; a zero-value means not supported.

If the target device supports GPS and *GNSS-NavigationModel* assistance, it shall support *clockModel* Model-2.

If the target device supports SBAS and *GNSS-NavigationModel* assistance, it shall support *clockModel* Model-5.

If the target device supports QZSS and *GNSS-NavigationModel* assistance, it shall support *clockModel* Model-2.

If the target device supports Galileo and *GNSS-NavigationModel* assistance, it shall support *clockModel* Model-1.

If the target device supports GLONASS and *GNSS-NavigationModel* assistance, it shall support *clockModel* Model-4.

If this field is absent, the target device supports the mandatory (native) *clockModel* choice only as listed above for the GNSS indicated by *GNSS-ID*.

##### **orbitModel**

This field specifies the *gnss-OrbitModel* choice(s) in *GNSS-NavigationModel* IE supported by the target device for the GNSS indicated by *GNSS-ID*. This is represented by a bit string, with a one-value at the bit position means the particular orbit model is supported; a zero-value means not supported.

If the target device supports GPS and *GNSS-NavigationModel* assistance, it shall support *orbitModel* Model-2.

If the target device supports SBAS and *GNSS-NavigationModel* assistance, it shall support *orbitModel* Model-5.

If the target device supports QZSS and *GNSS-NavigationModel* assistance, it shall support *orbitModel* Model-2.

If the target device supports Galileo and *GNSS-NavigationModel* assistance, it shall support *orbitModel* Model-1.

If the target device supports GLONASS and *GNSS-NavigationModel* assistance, it shall support *orbitModel* Model-4.

If this field is absent, the target device supports the mandatory (native) *orbitModel* choice only as listed above for the GNSS indicated by *GNSS-ID*.

#### – GNSS-RealTimeIntegritySupport

```

-- ASN1START
GNSS-RealTimeIntegritySupport ::= SEQUENCE {
    ...
}

```

```
-- ASN1STOP
```

### – GNSS-DataBitAssistanceSupport

```
-- ASN1START
```

```
GNSS-DataBitAssistanceSupport ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### – GNSS-AcquisitionAssistanceSupport

```
-- ASN1START
```

```
GNSS-AcquisitionAssistanceSupport ::= SEQUENCE {
    ...
}
-- ASN1STOP
```

### – GNSS-AlmanacSupport

```
-- ASN1START
```

```
GNSS-AlmanacSupport ::= SEQUENCE {
    almanacModel BIT STRING {
        model-1 (0),
        model-2 (1),
        model-3 (2),
        model-4 (3),
        model-5 (4),
        model-6 (5) } (SIZE (1..8)) OPTIONAL,
    ...
}
-- ASN1STOP
```

#### GNSS-AlmanacSupport field descriptions

##### **almanacModel**

This field specifies the *almanacModel* choice(s) in *GNSS-Almanac* IE supported by the target device for the GNSS indicated by *GNSS-ID*. This is represented by a bit string, with a one-value at the bit position means the particular almanac model is supported; a zero-value means not supported.

If the target device supports GPS and *GNSS-Almanac* assistance, it shall support Model-2.

If the target device supports SBAS and *GNSS-Almanac* assistance, it shall support Model-6.

If the target device supports QZSS and *GNSS-Almanac* assistance, it shall support Model-2.

If the target device supports Galileo and *GNSS-Almanac* assistance, it shall support Model-1.

If the target device supports GLONASS and *GNSS-Almanac* assistance, it shall support Model-5.

If this field is absent, the target device supports the mandatory (native) *almanacModel* choice only as listed above for the GNSS indicated by *GNSS-ID*.

### – GNSS-UTC-ModelSupport

```
-- ASN1START
```

```
GNSS-UTC-ModelSupport ::= SEQUENCE {
    utc-Model BIT STRING {
        model-1 (0),
        model-2 (1),
        model-3 (2),
        model-4 (3) } (SIZE (1..8)) OPTIONAL,
    ...
}
-- ASN1STOP
```

**GNSS-UTC-ModelSupport field descriptions*****utc-Model***

This field specifies the *GNSS-UTC-Model* choice(s) in *GNSS-UTC-Model* IE supported by the target device for the GNSS indicated by *GNSS-ID*. This is represented by a bit string, with a one-value at the bit position means the particular UTC model is supported; a zero-value means not supported.

If the target device supports GPS and *GNSS-UTC-Model* assistance, it shall support Model-1.

If the target device supports SBAS and *GNSS-UTC-Model* assistance, it shall support Model-4.

If the target device supports QZSS and *GNSS-UTC-Model* assistance, it shall support Model-1.

If the target device supports Galileo and *GNSS-UTC-Model* assistance, it shall support Model-1.

If the target device supports GLONASS and *GNSS-UTC-Model* assistance, it shall support Model-3.

If this field is absent, the target device supports the mandatory (native) *utc-Model* choice only as listed above for the GNSS indicated by *GNSS-ID*.

***GNSS-AuxiliaryInformationSupport***

```
-- ASN1START
```

```
GNSS-AuxiliaryInformationSupport ::= SEQUENCE {
    ...
}
```

```
-- ASN1STOP
```

**6.5.2.11 GNSS Capability Information Request*****A-GNSS-RequestCapabilities***

The IE *A-GNSS-Request-Capabilities* is used by the location server to request A-GNSS location capabilities (e.g., GNSSs and assistance data supported) from the target device.

```
-- ASN1START
```

```
A-GNSS-RequestCapabilities ::= SEQUENCE {
    gnss-SupportListReq          BOOLEAN,
    assistanceDataSupportListReq  BOOLEAN,
    locationVelocityTypesReq     BOOLEAN,
    ...
}
```

```
-- ASN1STOP
```

***A-GNSS-RequestCapabilities* field descriptions*****gnss-SupportListReq***

This field specifies whether the target device is requested to include the *gnss-SupportList* field in the *A-GNSS-ProvideCapabilities* IE or not. TRUE means requested.

***assistanceDataSupportListReq***

This field specifies whether the target device is requested to include the *assistanceDataSupportList* field in the *A-GNSS-ProvideCapabilities* IE or not. TRUE means requested.

***locationVelocityTypesReq***

This field specifies whether the target device is requested to include the *locationCoordinateTypes* field and *velocityTypes* field in the *A-GNSS-ProvideCapabilities* IE or not. TRUE means requested.

**6.5.2.12 GNSS Error Elements*****A-GNSS-Error***

The IE *A-GNSS-Error* is used by the location server or target device to provide GNSS error reasons.

```
-- ASN1START
```

```
A-GNSS-Error ::= CHOICE {
    locationServerErrorCauses    GNSS-LocationServerErrorCauses,
    targetDeviceErrorCauses     GNSS-TargetDeviceErrorCauses,
```



```

    ...
}
-- ASN1STOP

```

### – GNSS-LocationServerErrorCauses

The IE *GNSS-LocationServerErrorCauses* is used by the location server to provide GNSS error reasons to the target device.

```

-- ASN1START
GNSS-LocationServerErrorCauses ::= SEQUENCE {
    cause      ENUMERATED {
        undefined,
        undeliveredAssistanceDataIsNotSupportedByServer,
        undeliveredAssistanceDataIsSupportedButCurrentlyNotAvailableByServer,
        undeliveredAssistanceDataIsPartlyNotSupportedAndPartlyNotAvailableByServer,
        ...
    },
    ...
}
-- ASN1STOP

```

### – GNSS-TargetDeviceErrorCauses

The IE *GNSS-TargetDeviceErrorCauses* is used by the target device to provide GNSS error reasons to the location server.

```

-- ASN1START
GNSS-TargetDeviceErrorCauses ::= SEQUENCE {
    cause      ENUMERATED {
        undefined,
        thereWereNotEnoughSatellitesReceived,
        assistanceDataMissing,
        notAllRequestedMeasurementsPossible,
        ...
    },
    fineTimeAssistanceMeasurementsNotPossible    NULL        OPTIONAL,
    adrMeasurementsNotPossible                   NULL        OPTIONAL,
    multiFrequencyMeasurementsNotPossible        NULL        OPTIONAL,
    ...
}
-- ASN1STOP

```

#### GNSS-TargetDeviceErrorCauses field descriptions

##### **cause**

This field provides a GNSS specific error cause. If the cause value is '*notAllRequestedMeasurementsPossible*', the target device was not able to provide all requested GNSS measurements (but may be able to report a location estimate or location measurements). In this case, the target device should include any of the '*fineTimeAssistanceMeasurementsNotPossible*', '*adrMeasurementsNotPossible*', or '*multiFrequencyMeasurementsNotPossible*' fields, as applicable.

## 6.5.2.13 Common GNSS Information Elements

### – AccessTypes

The IE *AccessTypes* is used to indicate several cellular access types using a bit map.

```

-- ASN1START
AccessTypes ::= SEQUENCE {
    accessTypes  BIT STRING {
        eutra    (0),
        ultra    (1),

```

```

        gsm          (2) } (SIZE (1..8)),
    ...
}
-- ASN1STOP

```

#### **AccessTypes field descriptions**

##### **accessTypes**

This field specifies the cellular access type(s). This is represented by a bit string, with a one-value at the bit position means the particular access type is addressed; a zero-value means not addressed.

#### – **GNSS-ID**

The IE *GNSS-ID* is used to indicate a specific GNSS.

```

-- ASN1START
GNSS-ID ::= SEQUENCE {
    gnss-id      ENUMERATED{ gps, sbas, qzss, galileo, glonass, ...},
    ...
}
-- ASN1STOP

```

#### – **GNSS-ID-Bitmap**

The IE *GNSS-ID-Bitmap* is used to indicate several GNSSs using a bit map.

```

-- ASN1START
GNSS-ID-Bitmap ::= SEQUENCE {
    gnss-ids      BIT STRING {
        gps          (0),
        sbas         (1),
        qzss         (2),
        galileo      (3),
        glonass      (4) } (SIZE (1..16)),
    ...
}
-- ASN1STOP

```

#### **GNSS-ID-Bitmap field descriptions**

##### **gnss-ids**

This field specifies the GNSS(s). This is represented by a bit string, with a one-value at the bit position means the particular GNSS is addressed; a zero-value means not addressed.

#### – **GNSS-SignalID**

The IE *GNSS-SignalID* is used to indicate a specific GNSS signal type. The interpretation of *GNSS-SignalID* depends on the *GNSS-ID*.

```

-- ASN1START
GNSS-SignalID ::= SEQUENCE {
    gnss-SignalID INTEGER (0 .. 7),
    ...
}
-- ASN1STOP

```

<b>GNSS-SignalID field descriptions</b>
<p><b>gnss-SignalID</b>                      This field specifies a particular GNSS signal. The interpretation of <i>gnss-SignalID</i> depends on the <i>GNSS-ID</i> and is as shown in the table System to Value &amp; Explanation relation below.</p>

**System to Value & Explanation relation**

System	Value	Explanation
GPS	0	GPS L1 C/A
	1	GPS L1C
	2	GPS L2C
	3	GPS L5
	4-7	Reserved
SBAS	0	L1
	1-7	Reserved
QZSS	0	QZS-L1
	1	QZS-L1C
	2	QZS-L2C
	3	QZS-L5
	4-7	Reserved
GLONASS	0	GLONASS G1
	1	GLONASS G2
	2	GLONASS G3
	3-7	Reserved
Galileo	0	Galileo E1
	1	Galileo E5A
	2	Galileo E5B
	3	Galileo E6
	4	Galileo E5A + E5B
	5-7	Reserved

– **GNSS-SignalIDs**

The IE *GNSSSignal-IDs* is used to indicate several GNSS signals using a bit map. The interpretation of *GNSSSignal-IDs* depends on the *GNSS-ID*.

```

-- ASN1START
GNSS-SignalIDs ::= SEQUENCE {
    gnss-SignalIDs    BIT STRING (SIZE(8)),
    ...
}
-- ASN1STOP
    
```

<b>GNSS-SignalIDs field descriptions</b>
<p><b>gnss-SignalIDs</b>                      This field specifies one or several GNSS signals using a bit map. A one-value at the bit position means the particular signal is addressed; a zero-value at the particular bit position means the signal is not addressed. The interpretation of the bit map in <i>gnssSignalIDs</i> depends on the <i>GNSS-ID</i> and is shown in the table below.                      Unfilled table entries indicate no assignment and shall be set to zero.</p>

interpretation of the bit map in *gnssSignalIDs*

GNSS	Bit 1 (MSB)	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8 (LSB)
GPS	L1 C/A	L1C	L2C	L5				
SBAS	L1							
QZSS	QZS-L1	QZS-L1C	QZS-L2C	QZS-L5				
GLONASS	G1	G2	G3					
Galileo	E1	E5a	E5b	E6	E5a+E5b			

– **SBAS-ID**

The IE *SBAS-ID* is used to indicate a specific SBAS.

```
-- ASN1START
SBAS-ID ::= SEQUENCE {
    sbas-id          ENUMERATED { waas, egnos, msas, gagan, ... },
    ...
}
-- ASN1STOP
```

– **SBAS-IDs**

The IE *SBAS-IDs* is used to indicate several SBASs using a bit map.

```
-- ASN1START
SBAS-IDs ::= SEQUENCE {
    sbas-IDs        BIT STRING {
        waas          (0),
        egnos         (1),
        msas          (2),
        gagan         (3) } (SIZE (1..8)),
    ...
}
-- ASN1STOP
```

**SBAS-IDs field descriptions**

***sbasIDs***

This field specifies one or several SBAS(s) using a bit map. A one-value at the bit position means the particular SBAS is addressed; a zero-value at the particular bit position means the SBAS is not addressed.

– **SV-ID**

The IE *SV-ID* is used to indicate a specific GNSS satellite. The interpretation of *SV-ID* depends on the *GNSS-ID*.

```
-- ASN1START
SV-ID ::= SEQUENCE {
    satellite-id    INTEGER(0..63),
    ...
}
-- ASN1STOP
```

**SV-ID field descriptions****satellite-id**

This field specifies a particular satellite within a specific GNSS. The interpretation of *satellite-id* depends on the *GNSS-ID* see the table below.

**interpretation of satellite-id**

System	Value of <i>satellite-id</i>	Interpretation of <i>satellite-id</i>
GPS	'0' – '62' '63'	Satellite PRN Signal No. 1 to 63 Reserved
SBAS	'0' – '38' '39' – '63'	Satellite PRN Signal No. 120 to 158 Reserved
QZSS	'0' – '4' '5' – '63'	Satellite PRN Signal No. 193 to 197 Reserved
GLONASS	'0' – '23' '24' – '63'	Slot Number 1 to 24 Reserved
Galileo	TBD	TBD

## 6.5.3 Enhanced Cell ID Positioning

### 6.5.3.1 E-CID Location Information

#### – *ECID-ProvideLocationInformation*

The IE *ECID-ProvideLocationInformation* is used by the target device to provide E-CID location measurements to the location server. It may also be used to provide ECID positioning specific error reason.

```
-- ASN1START
ECID-ProvideLocationInformation ::= SEQUENCE {
    ecid-SignalMeasurementInformation    ECID-SignalMeasurementInformation    OPTIONAL,
    ecid-Error                           ECID-Error                           OPTIONAL,
    ...
}
-- ASN1STOP
```

### 6.5.3.2 E-CID Location Information Elements

#### – *ECID-SignalMeasurementInformation*

The IE *ECID-SignalMeasurementInformation* is used by the target device to provide various UE-measurements to the location server.

```
-- ASN1START
ECID-SignalMeasurementInformation ::= SEQUENCE {
    servingCellMeasuredResults    MeasuredResultsElement    OPTIONAL,
    measuredResultsList           MeasuredResultsList,
    ...
}
MeasuredResultsList ::= SEQUENCE (SIZE(1..32)) OF MeasuredResultsElement
MeasuredResultsElement ::= SEQUENCE {
    physCellId        INTEGER (0..503),
    cellGlobalId      CellGlobalIdEUTRA-AndUTRA                OPTIONAL,
    arfcnEUTRA        ARFCN-ValueEUTRA,
    systemFrameNumber
                        BIT STRING (SIZE (10))                OPTIONAL,
    rsrp-Result       INTEGER (0..97)                          OPTIONAL,
    rsrq-Result       INTEGER (0..34)                          OPTIONAL,
}
```

```

    ue-RxTxTimeDiff INTEGER (0..4095) OPTIONAL,
    ...
}
-- ASN1STOP

```

#### ***ECID-SignalMeasurementInformation* field descriptions**

<b><i>measuredResultsList</i></b>
This list contains the E-CID measurements for up to 32 cells.
<b><i>physCellId</i></b>
This field specifies the physical cell identity of the measured cell.
<b><i>cellGlobalId</i></b>
This field specifies cell global ID of the measured cell. The target device shall provide this field if it was able to determine the ECGI of the measured cell at the time of measurement.
<b><i>arfcnEUTRA</i></b>
This field specifies the ARFCN of the measured E-UTRA carrier frequency, as defined in [12].
<b><i>sfn</i></b>
This field specifies the system frame number of the measured neighbour cell. The target device shall include this field if it was able to determine the SFN of the neighbour cell at the time of measurement.
<b><i>rsrp-Result</i></b>
This field specifies the reference signal received power (RSRP) measurement, as defined in [12],[17].
<b><i>rsrq-Result</i></b>
This field specifies the reference signal received quality (RSRQ) measurement, as defined in [12],[17].
<b><i>ue-RxTxTimeDiff</i></b>
This field specifies the UE Rx-Tx time difference measurement, as defined in [17]. It is provided only for measurements on the UE's serving cell. Measurement report mapping is according to 3GPP TS 36.133 [18].

### 6.5.3.3 E-CID Location Information Request

#### – ***ECID-RequestLocationInformation***

The IE *ECID-RequestLocationInformation* is used by the location server to request E-CID location measurements from a target device.

```

-- ASN1START
ECID-RequestLocationInformation ::= SEQUENCE {
    requestedMeasurements BIT STRING {
        rsrpReq      (0),
        rsrqReq      (1),
        ueRxTxReq    (2) } (SIZE(1..8)),
    ...
}
-- ASN1STOP

```

#### ***ECID-RequestLocationInformation* field descriptions**

<b><i>requestedMeasurements</i></b>
This field specifies the E-CID measurements requested. This is represented by a bit string, with a one-value at the bit position means the particular measurement is requested; a zero-value means not requested.

### 6.5.3.4 E-CID Capability Information

#### – ***ECID-ProvideCapabilities***

The IE *ECID-ProvideCapabilities* is used by the target device to indicate its capability to support E-CID and to provide its E-CID location capabilities to the location server.

```

-- ASN1START
ECID-ProvideCapabilities ::= SEQUENCE {
    ecid-MeasSupported BIT STRING {
        rsrpSup      (0),

```

```

        rsrqSup      (1),
        ueRxTxSup    (2) } (SIZE(1..8)),
    ...
}
-- ASN1STOP

```

#### ***ECID-Provide-Capabilities* field descriptions**

##### ***ecid-MeasSupported***

This field specifies the E-CID measurements supported by the target device. This is represented by a bit string, with a one-value at the bit position means the particular measurement is supported; a zero-value means not supported. A zero-value in all bit positions in the bit string means only the basic Cell ID positioning method is supported by the target device. The *ueRxTxSup* field specifies that reporting UE Rx-Tx time difference measurement results via RRC signalling is supported by the target device, as well as reporting UE Rx-Tx time difference measurement results via LPP signalling for downlink E-CID positioning is supported. If a target device doesn't support LPP, E-SMLC may consider the target device can not report the UE Rx-Tx time difference measurement results via RRC signalling.

### 6.5.3.5 E-CID Capability Information Request

#### – *ECID-RequestCapabilities*

The IE *ECID-Request-Capabilities* is used by the location server to request E-CID positioning capabilities from a target device.

```

-- ASN1START
ECID-RequestCapabilities ::= SEQUENCE {
    ...
}
-- ASN1STOP

```

### 6.5.3.6 E-CID Error Elements

#### – *ECID-Error*

The IE *ECID-Error* is used by the location server or target device to provide E-CID error reasons to the target device or location server, respectively.

```

-- ASN1START
ECID-Error ::= CHOICE {
    locationServerErrorCauses      ECID-LocationServerErrorCauses,
    targetDeviceErrorCauses        ECID-TargetDeviceErrorCauses,
    ...
}
-- ASN1STOP

```

#### – *ECID-LocationServerErrorCauses*

The IE *ECID-LocationServerErrorCauses* is used by the location server to provide E-CID error reasons to the target device.

```

-- ASN1START
ECID-LocationServerErrorCauses ::= SEQUENCE {
    cause      ENUMERATED { undefined,
    ...
    },
    ...
}
-- ASN1STOP

```

– *ECID-TargetDeviceErrorCauses*

The IE *ECID-TargetDeviceErrorCauses* is used by the target device to provide E-CID error reasons to the location server.

```
-- ASN1START
ECID-TargetDeviceErrorCauses ::= SEQUENCE {
  cause          ENUMERATED {   undefined,
                                requestedMeasurementNotAvailable,
                                notAllrequestedMeasurementsPossible,
                                ...
                                },
  rsrpMeasurementNotPossible    NULL          OPTIONAL,
  rsrqMeasurementNotPossible    NULL          OPTIONAL,
  ueRxTxMeasurementNotPossible  NULL          OPTIONAL,
  ...
}
-- ASN1STOP
```

<i>ECID-TargetDeviceErrorCauses</i> field descriptions
--

<p><b>cause</b></p>
---------------------

<p>This field provides a ECID specific error cause. If the cause value is '<i>notAllRequestedMeasurementsPossible</i>', the target device was not able to provide all requested ECID measurements (but may be able to provide some measurements). In this case, the target device should include any of the '<i>rsrpMeasurementNotPossible</i>', '<i>rsrqMeasurementNotPossible</i>', or '<i>ueRxTxMeasurementNotPossible</i>' fields, as applicable.</p>
---

– *End of LPP-PDU-Definitions*

```
-- ASN1START
END
-- ASN1STOP
```



## Annex A (informative): Change History

Change history							
Date	TSG #	TSG Doc.	CR	Rev	Subject/Comment	Old	New
2009-10	RAN2 #67bis	R2-096252			RAN2 agreed TS 36.355 v0.1.0	-	0.1.0
2009-11	RAN2 #68	R2-097492			RAN2 agreed TS 36.355 v2.0.0	0.1.0	2.0.0
2009-12	RP-46	RP-091208			RAN #46 approval of TS 36.355	2.0.0	9.0.0
2010-03	RP-47	RP-100304	0001	-	Clarification on Position location	9.0.0	9.1.0
	RP-47	RP-100304	0002	-	Clarification on UE Rx-Tx time difference supporting capability	9.0.0	9.1.0
	RP-47	RP-100304	0003	2	Completion of LPP common material	9.0.0	9.1.0
	RP-47	RP-100304	0004	5	Completion of OTDOA in LPP	9.0.0	9.1.0
	RP-47	RP-100304	0006	-	Provision of Frame Drift Information in Network Time	9.0.0	9.1.0
	RP-47	RP-100304	0007	-	Clarification of measurement reference point	9.0.0	9.1.0
	RP-47	RP-100304	0010	-	GNSS-DifferentialCorrectionsSupport	9.0.0	9.1.0
	RP-47	RP-100304	0011	-	BSAlign Indication in GNSS Reference Time	9.0.0	9.1.0
	RP-47	RP-100304	0012	1	Changes to reflect LPP ASN.1 review	9.0.0	9.1.0
	RP-47	RP-100304	0013	1	Introduction of LPP reliability sublayer	9.0.0	9.1.0
	RP-47	RP-100304	0015	-	LPP error procedures and conditions	9.0.0	9.1.0
	RP-47	RP-100304	0016	-	Triggered Location Information Transfer due to Cell Change	9.0.0	9.1.0
2010-06	RP-48	RP-100558	0018	2	Addition of need codes to optional LPP information elements	9.1.0	9.2.0
	RP-48	RP-100558	0019	1	Miscellaneous corrections to LPP stage 3	9.1.0	9.2.0
	RP-48	RP-100558	0020	1	Small corrections to LPP specification	9.1.0	9.2.0
	RP-48	RP-100558	0021	-	Clarifications of OTDOA parameters	9.1.0	9.2.0
	RP-48	RP-100558	0022	1	Signalling support for PRS muting in OTDOA	9.1.0	9.2.0
	-	-	-	-	Two times capital R replaced by lower case r in "MeasuredResultsElement" (undoing not intended change)	9.2.0	9.2.1

---

## History

<b>Document history</b>		
V9.0.0	February 2010	Publication
V9.1.0	May 2010	Publication
V9.2.1	July 2010	Publication