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Contents

Intell	lectual Property Rights	2
Legal	l Notice	2
Moda	al verbs terminology	2
Forev	word	5
1	Scope	7
2	References	
3	Definitions of terms, symbols and abbreviations	
3.1	Terms	
3.2	Symbols	
3.3	Abbreviations	8
4	General	
4.1	Relationship between minimum requirements and test requirements	
4.2	Applicability of minimum requirements	
5	Frequency bands	
5.1 5.2	General	
6 6.1	FR1 MIMO OTA requirements General	
6.2	Minimum requirement	
7	FR2 MIMO OTA requirements	11
7.1	General	
7.2	Minimum requirement	11
Anne	ex A (normative): <fr1 methodology="" test=""></fr1>	13
A.1	General	
	Multi-Probe Anechoic Chamber (MPAC)	
A.2 A.2.1		13 13
A.2.2	· · · · · · · · · · · · · · · · · · ·	
A.2.3	1	
A.2.4		
A.2.5	, ,	
A.3	EUT positioning	16
Anne	ex B (normative): <fr2 methodology="" test=""></fr2>	17
B.1	General	17
B.2	FR2 3D Multi-Probe Anechoic Chamber (3D-MPAC)	17
B.2.1	· · · · · · · · · · · · · · · · · · ·	
B.2.2		
	Calibration procedure	19
B.2.3	Calibration procedure	19 19
B.2.3 B.2.4	Calibration procedure Test procedure Minimum Range Length	19 19 21
B.2.3 B.2.4 B.2.5	Calibration procedure Test procedure Minimum Range Length Preliminary MU of FR2 3D-MPAC system	19 19 21
B.2.3 B.2.4 B.2.5 B.2.6	Calibration procedure Test procedure Minimum Range Length Preliminary MU of FR2 3D-MPAC system Sample Device Orientations for Selected Test Points	19212224
B.2.3 B.2.4 B.2.5 B.2.6 B.3	Calibration procedure Test procedure Minimum Range Length Preliminary MU of FR2 3D-MPAC system Sample Device Orientations for Selected Test Points EUT positioning	
B.2.3 B.2.4 B.2.5 B.2.6 B.3	Calibration procedure Test procedure Minimum Range Length Preliminary MU of FR2 3D-MPAC system Sample Device Orientations for Selected Test Points EUT positioning ex C (normative): <fr1 and="" channel="" models="" procedure="" validation=""></fr1>	
B.2.3 B.2.4 B.2.5 B.2.6 B.3	Calibration procedure Test procedure Minimum Range Length Preliminary MU of FR2 3D-MPAC system Sample Device Orientations for Selected Test Points EUT positioning	

C.3	FR1 Channel model validation	30
C.3.1	General	30
C.3.2	Power Delay Profile (PDP)	31
C.3.3	Doppler/Temporal correlation	
C.3.4	Spatial correlation	
C.3.5	Cross-polarization	
C.3.6	Power validation	
C.4	Validation Pass/fail limit	
C.4.1	General	
C.4.2	Pass/Fail Criteria of PDP	
C.4.3	Pass/Fail Criteria of Doppler/Temporal correlation	
C.4.4	Pass/Fail Criteria of Spatial correlation	
C.4.5	Pass/Fail Criteria of Cross-polarization.	
C.4.6	Pass/Fail Criteria of Power validation	53
Anne	ex D (normative): <fr2 and="" channel="" models="" procedure="" validation=""></fr2>	54
	· · · · · · · · · · · · · · · · · · ·	
D.1	FR2 Channel models	54
D.2	FR2 Base Station beam configuration	54
D.3	FR2 Channel model validation	55
D.3.1	General	
D.3.2	FR2 Power Delay Profile (PDP)	
D.3.3	FR2 Doppler/Temporal correlation	
D.3.4	FR2 PAS similarity percentage (PSP)	
D.3.5	FR2 Cross-polarization.	
D.3.6	FR2 Power validation	
D.4	Validation Pass/fail limit	64
D.4.1	General	64
D.4.2	Pass/Fail Criteria of PDP	64
D.4.3	Pass/Fail Criteria of Doppler/Temporal correlation	64
D.4.4	Pass/Fail Criteria of PSP	65
D.4.5	Pass/Fail Criteria of Cross-polarization	66
D.4.6	Pass/Fail Criteria of Power validation	66
Anne	ex E (normative): <gnb configurations=""></gnb>	67
E.1	FR1 gNB configurations	67
	FR2 gNB configurations	
		/ 1
Anne	x F (normative): <environmental requirements=""></environmental>	75
F.1	Scope	75
F.2	Ambient temperature	75
F.3	Operating voltage	75
	ex G (informative): Change history	
Histor	ry	77

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In the present document, modal verbs have the following meanings:

shall indicates a mandatory requirement to do somethingshall not indicates an interdiction (prohibition) to do something

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should not indicates a recommendation not to do something

may indicates permission to do something

need not indicates permission not to do something

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can indicates that something is possiblecannot indicates that something is impossible

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will indicates that something is certain or expected to happen as a result of action taken by an agency

the behaviour of which is outside the scope of the present document

will not indicates that something is certain or expected not to happen as a result of action taken by an

agency the behaviour of which is outside the scope of the present document

might indicates a likelihood that something will happen as a result of action taken by some agency the

behaviour of which is outside the scope of the present document

might not indicates a likelihood that something will not happen as a result of action taken by some agency

the behaviour of which is outside the scope of the present document

In addition:

is (or any other verb in the indicative mood) indicates a statement of fact

is not (or any other negative verb in the indicative mood) indicates a statement of fact

The constructions "is" and "is not" do not indicate requirements.

1 Scope

The present document establishes the Multiple Input Multiple Output (MIMO) Over-the-Air (OTA) performance requirements for NR UEs operating on frequency Range 1 and frequency rang 2, for NR standalone (SA) and NR non-standalone (NSA) operation mode. The corresponding test methodologies are also presented in the Annex of this Technical Specification.

2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

- References are either specific (identified by date of publication, edition number, version number, etc.) or non-specific.
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- For a non-specific reference, the latest version applies. In the case of a reference to a 3GPP document (including a GSM document), a non-specific reference implicitly refers to the latest version of that document *in the same Release as the present document*.
- [1] 3GPP TR 21.905: "Vocabulary for 3GPP Specifications".
 [2] 3GPP TR 38.827: "Study on radiated metrics and test methodology for the verification of multi-antenna reception performance of NR User Equipment (UE)".
- [3] 3GPP TS 38.101-1: "NR; User Equipment (UE) radio transmission and reception; Part 1: Range 1 Standalone"
- [4] 3GPP TS 38.101-2: "NR; User Equipment (UE) radio transmission and reception; Part 2: Range 2 Standalone"
- [5] 3GPP TS 38.101-3: "NR; User Equipment (UE) radio transmission and reception; Part 3: Range 1 and Range 2 Interworking operation with other radios"
- [6] 3GPP TS 36.101: "Evolved Universal Terrestrial Radio Access (E-UTRA); User Equipment (UE) radio transmission and reception"
- [7] 3GPP TS 38.508-1: "5GS; User Equipment (UE) conformance specification; Part 1: Common test environment"
- [8] 3GPP TR 38.901: "Study on channel model for frequencies from 0.5 to 100 GHz"
- [9] F. Zhang, L. Hentilä, P. Kyösti and W. Fan, "Millimeter-wave New Radio Test Zone Validation for MIMO Over-the-air Testing," in IEEE Transactions on Antennas and Propagation, doi: 10.1109/TAP.2021.3111326.
- [10] 3GPP TS 38.101-4: "NR; User Equipment (UE) radio transmission and reception; Part 4: Performance requirements"

3 Definitions of terms, symbols and abbreviations

3.1 Terms

For the purposes of the present document, the terms given in 3GPP TR 21.905 [1] and the following apply. A term defined in the present document takes precedence over the definition of the same term, if any, in 3GPP TR 21.905 [1].

PSP (**PAS Similarity Percentage**): The similarity of the PAS produced by the OTA system and the reference PAS, which is presented by the Total Variation Distance (TVD) of power angular spectrum (PAS). PSP is defined as (1-TVD)*100%. PSP=100% denotes full similarity and PSP=0% denotes full dissimilarity.

3.2 Symbols

For the purposes of the present document, the following symbols apply:

P_{RS-EPRE-MAX} Maximum downlink RS-EPRE

3.3 Abbreviations

For the purposes of the present document, the abbreviations given in 3GPP TR 21.905 [1] and the following apply. An abbreviation defined in the present document takes precedence over the definition of the same abbreviation, if any, in 3GPP TR 21.905 [1].

AOA Azimuth angle Of Arrival AOD Azimuth angle Of Departure

BS Base Station

CDL Clustered Delay Line CW Continuous Wave Data Mode Landscape DML. Data Mode Portrait **DMP DMSU** Data Mode Screen Up Device Under Test DUT **EUT** Equipment Under Test FR1 Frequency Range 1 FR2 Frequency Range 2

FS Free Space

MASC MIMO Average Spherical Coverage MIMO Multiple Input Multiple Output MPAC Multi-Probe Anechoic Chamber

NR New Radio

NSA Non-Standalone, a mode of operation where operation of an other radio is assisted with an other

radio

OTA Over The Air

PAS Power Angular Spectrum
PDP Power Delay Profile
PSP PAS Similarity Percentage

RS-EPRE Reference Signal-Energy Per Resource Element

SS System Simulator

SSS Secondary Synchronization Signal
TRMS Total Radiated Multi-antenna Sensitivity

UE User Equipment
UMa Urban Macro
UMi Urban Micro

XPR Cross-Polarization Ratio
ZOA Zenith angle Of Arrival
ZOD Zenith angle Of Departure
ZSA Zenith angle Spread of Arrival
ZSD Zenith angle Spread of Departure

4 General

4.1 Relationship between minimum requirements and test requirements

The Minimum Requirements given in this specification make no allowance for measurement uncertainty. The test specification in RAN5 will define test tolerances for FR1 and FR2 MIMO OTA. The test tolerances are used to relax the minimum requirements in this specification to create test requirements.

4.2 Applicability of minimum requirements

The MIMO OTA minimum requirements apply only to the primary mechanical mode of UE which is declared by the manufacturer if the UE can support multiple mechanical modes.

The minimum requirements apply only to the UE under normal environmental conditions specified in Annex F.

5 Frequency bands

5.1 General

NR MIMO OTA Requirements are defined separately for different frequency ranges (FR). The frequency ranges in which NR can operate according to this version of the specification are identified as described in Table 5.1-1.

Table 5.1-1: Definition of frequency ranges

Frequency range designation	Corresponding frequency range
FR1	410 MHz – 7125 MHz
FR2	24250 MHz – 52600 MHz

The present specification covers both FR1 and FR2 operating bands. For FR2, only FR2-1 bands are applicable.

5.2 Operating bands

NR is designed to operate in FR1 operating bands defined in TS 38.101-1 [3] and FR2 operating bands defined in TS 38.101-2 [4]. NSA band combinations are defined in TS 38.101-3 [5]. E-UTRA is designed to operate in operating bands defined in TS 36.101 [6].

6 FR1 MIMO OTA requirements

6.1 General

6.1.1 Definition of MIMO throughput

The MIMO throughput is defined here as the time-averaged number of correctly received transport blocks in a communication system running an application, where a Transport Block is defined in the reference measurement

channel. From OTA perspective, this is also called MIMO OTA throughput. It will be used as the baseline figure of merit for FR1 and FR2 MIMO OTA testing.

The MIMO OTA throughput is measured at the top of physical layer of NR system under the use of FRC, the SS transmit fixed-size payload bits to the DUT. The DUT signals back either ACK or NACK to the SS. The SS then records the following:

- Number of ACKs,
- Number of NACKs, and
- Number of DTX slots

Hence the MIMO (OTA) throughput can be calculated as

$$MIMO\ (OTA)\ Throughput = \frac{Transmitte\ d\ TBS \times Num\ of\ ACKs}{Measurement Time}$$

Where Transmitted TBS is the Transport Block Size transmitted by the SS, which is fixed for an FRC during the measurement period. MeasurementTime is the total composed of successful slots (ACK), unsuccessful slots (NACK) and DTX-symbols.

The time-averaging is to be taken over a time period sufficiently long to average out the variations due to the fading channel. Therefore, this is also called the average MIMO OTA throughput. The throughput should be measured at a time when eventual start-up transients in the system have evanesced.

6.1.2 Total Radiated Multi-antenna Sensitivity (TRMS)

The average TRMS of free space data mode portrait (FS DMP), free space data mode landscape (FS DML), and free space data mode screen up (FS DMSU), is defined as the FR1 MIMO OTA requirement. The averaging shall be done in linear scale for the TRMS results at these DUT positions, according to the formula:

$$TRMS_{average,70} = 10\log\left[3/\left(\frac{1}{10^{S_{FS_DMP,70}/10}} + \frac{1}{10^{S_{FS_DML,70}/10}} + \frac{1}{10^{S_{FS_DMSU,70}/10}}\right)\right]$$

where

$$S_{MODE,70} = 10 \log \left[12 / \left(\frac{1}{10^{P_{MODE,70,0}/10}} + \frac{1}{10^{P_{MODE,70,1}/10}} + \dots + \frac{1}{10^{P_{MODE,70,11}/10}} \right) \right]$$

Such that MODE is one of $\{FS_DMP, FS_DML, FS_DMSU\}$, and $\{P_{MODE,70,0}, ..., P_{MODE,70,11}\}$ are the measured sensitivity values at each azimuth position at the 70% throughput outage.

If 1 azimuth position does not result in a defined measured sensitivity at 70% throughput, $S_{MODE,70}$ is calculated using the 11 measured sensitivities and the maximum downlink RS-EPRE $P_{RS-EPRE-MAX}$ (substitution approach) for the one missing result. $P_{RS-EPRE-MAX}$ is the maximum downlink RS-EPRE supported by the test system, and is defined as - 80dBm/15kHz (or equivalent -77dBm/30kHz) for FR1 MIMO OTA.

The TRMS shall be measured at the mid channel as specified in TS 38.508-1 subclause 4.3.1 [7]. The average TRMS shall be lower than the average TRMS requirements specified in Clause 6.2.

The additional criterion in azimuthal orientations shall be met:

- The EUT must meet 70% throughput in 11 of total 12 azimuthal orientations. If the EUT fails to meet this criterion even under maximum downlink power condition (i.e. P_{RS-EPRE-MAX}), the EUT shall fail the FR1 MIMO OTA test.
- The EUT must meet 90% throughput in 10 of total 12 azimuthal orientations. If the EUT fails to meet this criterion even under maximum downlink power condition (i.e. P_{RS-EPRE-MAX}), the EUT shall fail the FR1 MIMO OTA test.

6.2 Minimum requirement

FR1 TRMS minimum performance requirements for NR handheld UEs operating on SA mode in free space and the primary mechanical mode for 70% DL throughput with the corresponding measurement configurations (i.e., channel model and gNB configuration) specified in Annex C.1 and Annex E.1 are defined in Table 6.2-1.

Table 6.2-1: FR1 TRMS minimum performance requirements for NR handheld UEs operating on SA mode in free space and the primary mechanical mode

NR bands	Bandwidth (MHz)	MIMO layer	Channel model	Reference channel	TRMS _{average,70}
n28	10	2x2	FR1 UMi CDL-C	R.PDSCH.1-3.1 FDD	TBD dBm/15kHz
n41	40	4x4	FR1 UMa CDL-C	R.PDSCH.2-2.4 TDD	-93.3 dBm/30kHz
n78	40	4x4	FR1 UMa CDL-C	R.PDSCH.2-2.4 TDD	-94.8 dBm/30kHz
n79	40	4x4	FR1 UMa CDL-C	R.PDSCH.2-2.4 TDD	TBD dBm/30kHz

7 FR2 MIMO OTA requirements

7.1 General

7.1.1 MIMO Average Spherical Coverage (MASC)

The MIMO Average Spherical Coverage (MASC) is the Figure of Merit of FR2 MIMO OTA requirement. FR2 MIMO OTA is measured with 36 constant-density points within the 3D sphere. The MASC is determined by the averaging of the best 18 sensitivity values for power class 3 UE. The averaging shall be done in linear scale for the MASC result according to the formula:

$$MASC_{70} = 10 \log \left[\frac{18}{\left(\frac{1}{10^{\frac{P_{70,1}}{10}}} + \frac{1}{10^{\frac{P_{70,2}}{10}}} + \dots + \frac{1}{10^{\frac{P_{70,18}}{10}}} \right)} \right]$$

Such that $\{P_{70,1}, ..., P_{70,18}\}$ are the best 18 sensitivity values from all the 36 constant density measurement points, as defined in Annex B.2.3.

The MASC shall be measured at the mid channel as specified in TS 38.508-1 subclause 4.3.1 [7]. The MASC shall be lower than the requirements specified in Clause 7.2.

For FR2 MIMO OTA, P_{RS-EPRE-MAX}, i.e., the maximum downlink RS-EPRE supported by the test system, is defined as [-79.1dBm/120kHz].

If the number of test points where the UE can meet 70% maximum throughput outage even under maximum downlink power condition (i.e., [-79.1dBm/120kHz]) is less than [18], then UE fails the test.

Other criteria for FR2 are FFS.

7.2 Minimum requirement

FR2 MASC minimum performance requirements for power class 3 NR handheld UEs in free space and the primary mechanical mode for averaging of the best 18 sensitivity values for 70% DL throughput with the corresponding measurement configurations (i.e., channel model and gNB configuration) specified in Annex D.1 and Annex E.2 are defined in Table 7.2-1.

Table 7.2-1: FR2 MASC minimum performance requirements for NR handheld UEs in free space and the primary mechanical mode

NR bands	Bandwidth (MHz)	MIMO layer	Channel model Reference channel		MASC ₇₀ [dBm/120kHz]
n257	100	2x2	FR2 UMi CDL-C	R.PDSCH.5-2.2 TDD	TBD
n258	100	2x2	FR2 UMi CDL-C	R.PDSCH.5-2.2 TDD	TBD
n260	100	2x2	FR2 UMi CDL-C	R.PDSCH.5-2.2 TDD	TBD
n261	100	2x2	FR2 UMi CDL-C	R.PDSCH.5-2.2 TDD	TBD

Annex A (normative): <FR1 Test methodology>

A.1 General

FR1 MIMO OTA requirement testing is based on UE-noise limited environmental condition, i.e., UE throughput characterized as a function of signal power incident to the DUT antennas.

The minimum test zone size for FR1 MIMO OTA test methods is 20cm. "Black-box" testing approach is adopted for NR MIMO OTA testing, the physical centre of the EUT shall be placed in the centre of the test zone, the EUT shall be completely contained within the minimum test zone size.

FR1 MIMO OTA requirement testing should be performed under primary mechanical mode. The primary mechanical mode for devices having multiple mechanical modes shall be declared by the manufacturers. Single primary mechanical mode for each device should be declared for MIMO OTA conformance testing.

A.2 Multi-Probe Anechoic Chamber (MPAC)

A.2.1 System setup

MPAC test method is the reference methodology for FR NR MIMO OTA testing. By arranging an array of antennas around the Equipment Under Test (EUT), a spatial distribution of angles of arrival in MPAC system may be simulated to expose the EUT to a near field environment that appears to have originated from a complex multipath far field environment.

As illustrated schematically in Figure A.2.1-1, signals propagate from the base station/communication tester to the EUT through a simulated multipath environment known as a spatial channel model, where appropriate channel impairments such as Doppler and fading are applied to each path prior to injecting all of the directional signals into the chamber simultaneously through the antenna array. The resulting field distribution in the test zone is then integrated by the EUT antenna(s) and processed by the receiver(s) just as it would do so in any non-simulated multipath environment. MPAC system with 16 uniformly-spaced dual-polarized probes is permitted for NR FR1 MIMO OTA testing.

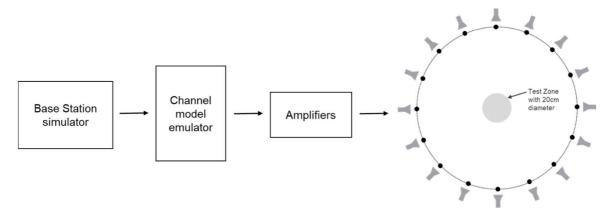


Figure A.2.1-1: MPAC system layout for NR FR1 MIMO OTA testing

A.2.2 Calibration procedure

The system needs to be calibrated by using a reference calibration antenna with known gain values in order to ensure that the downlink signal power is correct. In non-standalone (NSA) mode, the LTE link antenna provides a stable LTE signal without precise path loss or polarization control.

Unlike traditional TRP/TRS testing where the path loss corrections can all be applied as a post processing step to the measured data, the path loss for each probe in the MPAC system must be balanced at test time in order to generate the desired channel model environment within the test zone of the chamber. The imbalance of each path during testing would result in an alteration of the angular dependence of the channel model (i.e. varied characteristics of generated channel model) within the test zone of the chamber.

- 1. Place a vertical reference dipole in the centre of the test zone, connected to a VNA port, with the other VNA port connected to the input of the channel emulator unit.
- 2. Configure the channel emulator for bypass mode.
- 3. Measure the response of each path from each vertical polarization probe to the reference antenna in the centre of test zone.
- 4. Adjust the power on all vertical polarization branches of the channel emulator so that the powers received at the centre are equal.
- 5. Repeat the steps 1 to 4 with the magnetic loop or horizontally polarized reference dipole instead, and adjust the horizontal polarization branches of the channel emulator.
- 6. The worst-case path loss becomes the reference path loss of the entire system, this loss is used to compute the power in the centre of the test zone relative to the output power of the Base Station simulator. Besides, based on the reference path loss, the relative offset of each path loss shall be corrected.

Note: Calibration based on other antennas, e.g., horn antennas is not precluded.

A.2.3 Test procedure

Before throughput testing, the initial conditions shall be confirmed to reach the correct measurement state for each test case.

- 1. Ensure environmental requirements of Annex F are met.
- 2. Configure the test system according to Annex C, D and E for the applicable test case.
- 3. Verify the implementation of the channel model as specified in Annex C.3.
- 4. Position the UE in the chamber according to Annex A.3.
- 5. Power on the UE.
- 6. Set up the connection.

Note: For step 3, the verification of the channel model implementation is usually performed once for each channel model as part of the laboratory accreditation process, and will remain valid as long as the setup and instruments remain unchanged. Otherwise the channel model validation may need to be performed prior to starting each throughput test.

For throughput testing, the following steps shall be followed in order to evaluate NR MIMO OTA performance of the DUT:

- 1. Measure MIMO OTA throughput from one measurement point, the maximum downlink power $P_{\text{RS-EPRE-MAX}}$ is defined in Clause 6.1.2. MIMO OTA throughput is the minimum downlink signal power resulting in a predefined throughput value, i.e., 70% and 90% of the maximum theoretical throughput. The downlink signal power step size shall be no more than 0.5 dB when RF power level is near the NR MIMO sensitivity level.
- 2. Rotate the UE around vertical axis of the test system by 30 degrees and repeat from step 1 until one complete rotation has been measured i.e. 12 different UE azimuth rotations.

- 3. Repeat the test from step 1 for each specified device orientation. A list of orientations is given in Annex A.3.
- 4. The postprocessing method to calculate the average MIMO Throughput is defined in Clause 6.

Note: For step 1 of throughput testing, the measurement is not needed to start from maximum downlink power each time. To save testing time, the starting downlink power can be set as a proper value (lower than maximum downlink power supported by test system) as long as all the throughput curve curves at 12 different UE azimuth rotations can reach at least 90% of the maximum theoretical throughput.

A.2.4 Minimum Range Length

The minimum range length of FR1 MPAC system is defined as the distance from the centre of the test zone to the aperture of the measurement probes/antennas, as illustrated in Figure A.2.4-1.

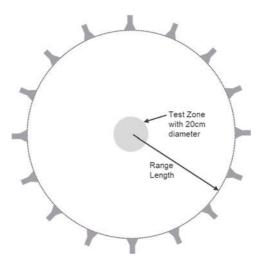


Figure A.2.4-1: Illustration of range length definition of FR1 MPAC

The minimum range length for NR FR1 MPAC OTA systems with 20cm test zone size is 1.2m. While for MPAC systems, the far-field requirements do not have to apply, it was shown that the spatial correlation can be impacted significantly for distances below 1.2m.

A.2.5 Preliminary MU budget of FR1 MPAC system

This clause defines the Preliminary measurement uncertainty (MU) budget for FR1 MPAC system, as shown in Table A.2.5-1.

Table A.2.5-1: Preliminary measurement uncertainty budget for FR1 MPAC system

UID	Description of uncertainty contribution	Example value (410MHz <f ≤3GHz)</f 	Example value (3GHz <f≤7.125ghz)< th=""><th>Distribution of the probability</th><th>Std Uncertainty (410MHz<f≤3 GHz) [dB]</f≤3 </th><th>Std Uncertainty (3GHz <f≤7.125ghz) [dB]</f≤7.125ghz) </th></f≤7.125ghz)<>	Distribution of the probability	Std Uncertainty (410MHz <f≤3 GHz) [dB]</f≤3 	Std Uncertainty (3GHz <f≤7.125ghz) [dB]</f≤7.125ghz) 			
	Stage 2: DUT measurement								
1	Mismatch for measurement process	0	0	U-Shaped	0	0			
2	Measure distance uncertainty	0	0	Normal	0	0			
3	Quality of quiet zone	0.6	0.6	Actual	0.6	0.6			
4	Base Station simulator	1.5dB	2dB	Rectangular	0.87	1.15			
5	Channel Emulator - absolute output power - output signal stability - output stability with temperature	1.5dB 0.5dB 0.4dB	1.5dB 0.5dB 0.4dB	Actual (normal- power; rect-stability)	0.84	0.84			
6	Amplifier uncertainties	0.7dB	0.7dB	Rectangular	0.4	0.4			
7	Random uncertainty	0.2dB	0.2dB	Normal	0.12	0.12			
8	Throughput measurement: output level step resolution	0.25dB	0.25dB	Rectangular	0.14	0.14			
9	DUT sensitivity drift	0.2	0.2	Rectangular	0.12	0.12			
10	Signal flatness	0	0	Normal	0	0			
		1: Calibration	n measurement						
11	Mismatch for calibration process - loopback cable path - system input path - reference antenna	0.2	0.2	U-Shaped	0.14	0.14			
12	Reference antenna positioning misalignment	0	0	Normal	0	0			
13	Quality of quiet zone	0.6	0.6	[Rectangular]	0.35	0.35			
14	Total uncertainty of the Network Analyzer	0.5	0.5	Rectangular	0.29	0.29			
15	Uncertainty of an absolute gain of the calibration antenna	1	1	Normal	0.5	0.5			
16	Offset of the Phase Center of the Reference Antenna	0	0	Normal	0	0			
Total E	Expanded Uncertainty, U, with	95% Confide	nce Interval		3.03	3.38			

The detailed descriptions of each measurement uncertainty contributor are defined in Annex B.1.2 in [2].

A.3 EUT positioning

This Clause defines the measurement coordinate system for the NR MIMO OTA.

For FR1 MIMO OTA, the DUT shall be tested under Free Space Data Mode Portrait (FS DMP), Free Space Data Mode Landscape (FS DML), and Free Space Data Mode Screen Up (FS DMSU), the DUT azimuthal rotation shall be performed over 360 degrees per orientation in 30 degree steps (12 total positions).

Annex B (normative): <FR2 Test methodology>

B.1 General

FR2 MIMO OTA requirement testing is based on UE-noise limited environmental condition, i.e., UE throughput characterized as a function of signal power incident to the DUT antennas.

The minimum test zone size for FR2 MIMO OTA 3D-MPAC system is 20cm. "Black-box" testing approach is adopted for NR MIMO OTA testing, the physical centre of the EUT shall be placed in the centre of the test zone, the EUT shall be completely contained within the minimum test zone size.

FR2 MIMO OTA requirement testing should be performed under primary mechanical mode. The primary mechanical mode for devices having multiple mechanical modes shall be declared by the manufacturers. Single primary mechanical mode for each device should be declared for MIMO OTA conformance testing.

B.2 FR2 3D Multi-Probe Anechoic Chamber (3D-MPAC)

B.2.1 System setup

The 3D MPAC test method is the reference methodology for FR2 NR MIMO OTA testing. By arranging an array of antennas around the Equipment Under Test (EUT), a spatial distribution of angles of arrival in the 3D MPAC system may be simulated to expose the EUT to a near field environment that appears to have originated from a complex multipath far field environment.

As illustrated schematically in Figure B.2.1-1, signals propagate from the base station/communication tester to the EUT through a simulated multipath environment known as a spatial channel model, where appropriate channel impairments such as Doppler and fading are applied to each path prior to injecting all of the directional signals into the chamber simultaneously through the probe array. The resulting field distribution in the test zone is then integrated by the EUT antenna(s) and processed by the receiver(s) just as it would do so in any non-simulated multipath environment. The 3D MPAC system with 6 dual-polarized probes (illustrated with black dots in Figure B.2.1-1) placed on a sector with minimum radius of 0.75m from the centre of the test zone is permitted for NR FR2 MIMO OTA testing.

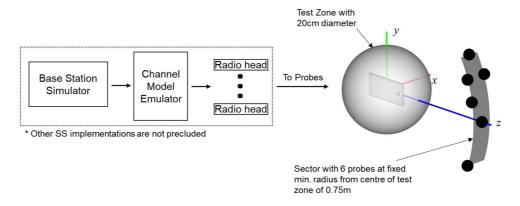


Figure B.2.1-1: 3D MPAC system layout for NR FR2 MIMO OTA testing

The exact probe locations with respect to the OTA test system coordinate system are tabulated in Table B.2.1-1.

Table B.2.1-1. FR2 3D MPAC Probe Locations in OTA test system coordinate system

Probe Number	Theta [deg]	Phi [deg]
1	0.0	0.0
2	11.2	116.7
3	20.6	-104.3
4	20.6	104.3
5	20.6	75.7
6	30.0	90.0

The 3D MPAC probes in Table B.2.1-1 can be implemented using conventional millimetre-wave probes as well as IFF-based probes as long as the same probe configuration and same number of probes is used.

The channel model parameters and probe locations for channel model implementation are defined in a channel model coordinate system, which is illustrated in figure B.2.1-2. The channel model coordinate axes x_{CM} , y_{CM} , and z_{CM} correspond to the OTA test system coordinate axes z, y, and -x, respectively.

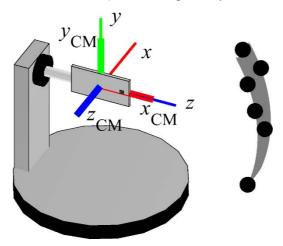


Figure B.2.1-2: Channel Model Coordinate Axes in FR2 3D-MPAC system

The probe locations with respect to channel model coordinate axes are tabulated in table B.2.1-2.

Table B.2.1-2. FR2 3D MPAC Probe Locations in Channel Model Coordinate System

Probe Number	Theta [deg]	Phi [deg]
1	90	0
2	85	10
3	85	-20
4	85	20
5	95	20
6	90	30

The channel model rotations assumed for this probe configuration are tabulated in Table B.2.1-3.

Table B.2.1-3. Channel Model Rotations

UMi CDL-C					
Phi [deg] Theta [deg]					
32	15.0				

This channel model rotation assumes the relative orientations of BS and UE antennas displayed in Figure B.2.1-3, i.e., the DUT antenna is pointed towards the BS in channel model coordinate system.

In order to avoid positioning ambiguities, the turntable implementing the rotation in θ shall match the intended DUT θ for P0 Orientation 1 without the re-positioning approach, as defined in Annex A.3 in [2], applied. With the re-positioning approach applied, the relative orientation between the DUT and the probes for P0 Orientation 2 shall be the same the relative orientation between DUT and probes as for P0 Orientation 1.

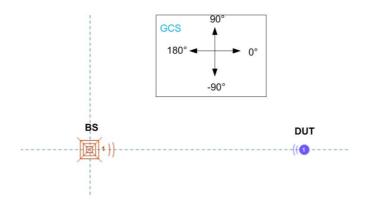


Figure B.2.1-3: Relative orientations of BS and UE antennas.

Since the test points are uniformly spaced in 3D already, Table B.2.3-1, there is no need to adjust/rotate the DUT rotations by the channel model rotations.

B.2.2 Calibration procedure

The system needs to be calibrated by using a reference calibration antenna with known gain values in order to ensure that the downlink signal power is correct. In non-standalone (NSA) mode, the LTE link antenna provides a stable LTE signal without precise path loss or polarization control.

The path loss for each probe in the 3D MPAC system must be calibrated at test time in order to generate the desired channel model environment within the test zone of the chamber. The imbalance of each path during testing would result in an alteration of the angular dependence of the channel model (i.e. varied characteristics of generated channel model) within the test zone of the chamber.

For the calibration measurement, the reference antenna is placed in the centre of the quiet zone, connected to a VNA port, with the other VNA port connected to the input of the channel emulator unit as illustrated schematically in Figure D.3.2-1. For each probe antenna, the reference antenna needs to be aligned in polarization, i.e., θ or ϕ , and direction with the probe antenna that corresponds to the respective path to be calibrated. For each calibration measurement, the channel emulator needs to be configured in bypass mode. The calibration process determines the composite loss, L_{path,pol}, of the entire receiver chain path gains (measurement antenna, amplification) and losses (switches, combiners, cables, path loss, etc.). The calibration measurement is repeated for each measurement path (two orthogonal polarizations and each signal path).

B.2.3 Test procedure

Before throughput testing, the initial conditions shall be confirmed to reach the correct measurement state for each test case.

- 1. Ensure environmental requirements of Annex F are met.
- 2. Configure the test system according to Annex E.2 and Annex D.1 for the applicable test case.
- 3. Verify the implementation of the channel model as specified in Annex D.3.
- 4. Position the UE in the chamber according to Annex B.3.
- 5. Power on the UE.
- 6. Set up the connection.

Note: For step 3, the verification of the channel model implementation is usually performed once for each channel model as part of the laboratory accreditation process, and will remain valid as long as the setup and instruments remain unchanged. Otherwise the channel model validation may need to be performed prior to starting each throughput test.

For throughput testing, the following steps shall be followed in order to evaluate FR2 MIMO OTA performance of the DUT:

- 1. Position the DUT in the default P0 alignment option (Orientation 1), as defined in Annex A.3 in TR38.827 [2].
- 2. Measure MIMO OTA throughput, the maximum downlink power is TBD. MIMO OTA throughput is the minimum downlink signal power resulting in a pre-defined throughput value (70%) of the maximum theoretical throughput. The downlink signal power step size shall be no more than 0.5 dB when RF power level is near the NR MIMO sensitivity level.
- 3. Rotate the UE to the next test point. Table B.2.3-1 lists 36 evenly spaced test points determined using the charged particle approach and with test point #1 centred at (0,0).
- 4. Repeat the test from step 2 for each specified test point. If the re-positioning concept is applied, the device needs to be positioned in P0 Orientation 2 (either option 1 or option 2).
- 5. The postprocessing method and the performance metric are defined in Clause 7.1.

Note: For step 2 of throughput testing, the measurement is not needed to start from maximum downlink power each time. To save testing time, the starting downlink power can be set as a proper value (lower than maximum downlink power supported by test system) as long as the throughput curve can reach at least 70% of the maximum theoretical throughput.

Table B.2.3-1. Evenly spaced FR2 test points with a constant density

Test Point Number	Theta [deg]	Phi [deg]
1	0.0	0.0
2	33.5	139.7
3	33.9	49.7
4	35.5	-142.9
5	35.5	-76.9
6	37.6	-17.2
7	52.3	94.7
8	56.9	175.7
9	62.5	20.4
10	63.7	-99.8
11	67.1	-55.0
12	69.3	-139.5
13	69.5	130.1
14	70.3	60.8
15	72.1	-16.2
16	88.7	-167.5
17	88.7	98.5
18	89.3	157.0
19	93.9	-78.9
20	94.6	31.6
21	95.3	-115.6
22	99.6	-38.3
23	103.8	-1.1
24	104.4	66.3
25	110.1	127.5
26	115.1	-145.6
27	120.8	171.9
28	125.3	-60.7
29	128.2	-104.1
30	128.8	91.3
31	129.9	35.8
32	136.0	-13.4
33	145.8	138.1
34	150.2	-153.3
35	160.6	-67.4
36	161.7	59.1

B.2.4 Minimum Range Length

The minimum range length of FR2 MPAC system is defined as the distance from the centre of the test zone to the aperture of the measurement probes/antennas, as illustrated in Figure B.2.4-1.

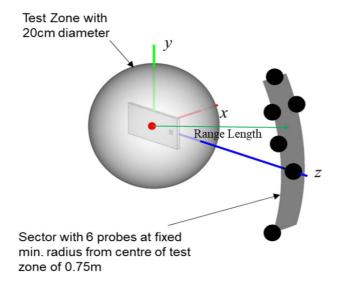


Figure B.2.4-1: Illustration of range length definition of FR2 3D-MPAC

The minimum range length for NR FR2 MPAC OTA systems with 20cm test zone size is 0.75m. It was shown that the PSP can be reduced significantly for distances below 0.75m.

B.2.5 Preliminary MU of FR2 3D-MPAC system

This clause defines the Preliminary measurement uncertainty (MU) budget for FR2 3D-MPAC system, as shown in Table A.2.5-1.

Table B.2.5- 1: Preliminary measuremen t uncertainty budget for FR2 3D- MPAC	Description of uncertainty contribution	Example value (26.5GHz≤f≤29.5GHz)	Example value (37GHz ≤f≤40GHz)	Distribution of the probability	Std Uncertainty (26.5GHz≤f≤29.5GHz) [dB]	Std Uncertaint y (37GHz ≤f≤40GHz) [dB]
systemUID		Stage 2: I	<u>l</u> DUT measur	l ement		
1	Mismatch for measurement	[1.30]	TBD	[Actual]	[1.30]	TBD
	process	F0 (=1	T5 5	10	To 627	
2	Measure distance uncertainty	[0.15]	TBD	[Rectangular	[0.09]	TBD
3	Quality of quiet zone	[1.20]	TBD	[Actual]	[1.20]	TBD
4	Base Station simulator	TBD	TBD	[Normal]	TBD	TBD
5	Channel Emulator -absolute value -stability -linearity	TBD	TBD	Normal	TBD	TBD
6	Amplifier uncertainties	[2.10]	TBD	[Normal]	[1.05]	TBD
7	Random uncertainty	[0.50]	TBD	[Normal]	[0.25]	TBD
8	Throughput measurement : output level step resolution	[0.25]	TBD	Rectangular	[0.14]	TBD
9	DUT sensitivity drift	TBD	TBD	Rectangular	TBD	TBD
10	Signal flatness	TBD	TBD	Normal	TBD	TBD
		Stage 1: Cali				
11	Mismatch for calibration process - loopback cable path - system input path - reference antenna	[0.00]		U-Shaped	[0.00]	TBD
12	Reference antenna positioning misalignment	[0.00]	TBD	[Rectangular	[0.00]	TBD
13	Quality of quiet zone	[0.60]	TBD	[Actual]	[0.60]	TBD
14	Total uncertainty of the Network Analyzer	[0.73]	TBD	[Normal]	[0.37]	TBD
15	Uncertainty of an absolute gain of the calibration antenna	[0.60]	TBD	[Normal]	[0.30]	TBD

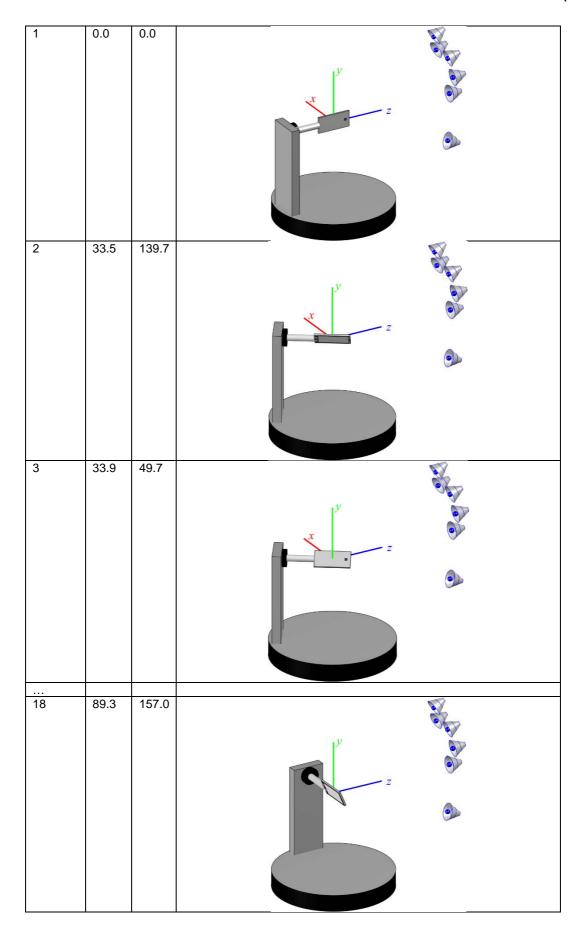
16	Offset of the	[0.47]	TBD	[Rectangular	[0.27]	TBD
	Phase Center			J		
	of the					
	Reference					
	Antenna					
Total Expande	ed Uncertainty,	U, with 95% Confidenc	e Interval		TBD	TBD
_	-					

B.2.6 Sample Device Orientations for Selected Test Points

Tables B.2.6-1 and B.2.6-2 include illustrations of device/positioner/probe configurations & orientations based on a sample MIMO OTA test system for various test points for Theta $< 90^{\circ}$ (Table B.2.6-1) and Theta $> 90^{\circ}$ (Table B.2.6-2), respectively.

Table B.2.6-1. Visualization of DUT Orientation of test points with Theta < 90°.

Point [deg] [deg] with P0 – Orientation 1		Theta [deg]		Sample System/DUT Illustration with P0 – Orientation 1
---	--	----------------	--	---



The illustrations in Table B.2.6-2 with Theta $> 90^{\circ}$ include the device and positioner orientations with the device placed in the P0 alignment option with Orientation 1 as well as Orientation 2 (Option 1 or Option 2) with the re-positioning approach as defined in Annex A.3 in [2].

Table B.2.6-2. Visualization of DUT Orientation of test points with Theta > 90°.

Test Point Number	Theta [deg]	[gca]		Sample System/DUT Illustra – Orientation 2	tion with P0	
19	93.9	-78.9	Z Z		Z Z	
35	160.6	-67.4	z z		Z Z	
36	161.7	59.1			Z Z	

B.3 EUT positioning

This Clause defines the measurement coordinate system for the NR MIMO OTA.

For FR2 MIMO OTA, the DUT shall be tested using a 3D scan. With the DUT positioned in the default P0 alignment option, as defined in Annex A.3 in [2], measurements on 36 evenly spaced test points with a constant density shall be performed.

Annex C (normative): <FR1 Channel models and Validation procedure>

C.1 FR1 Channel models

The following channel models are required for FR1 MIMO OTA measurement.

The generic models are Table C.1-1 FR1 UMi CDL-C and Table C.1-2 FR1 UMa CDL-C, which do not include base station antenna filtering. UMi CDL-C and UMa CDL-C are selected to define 2x2 and 4x4 MIMO OTA requirements, respectively.

Therefore, in addition, the BS beam filtering effect defined in Annex C.2 also apply when emulating the channel models.

Table C.1-1: Channel model parameters for UMi CDL-C at 3.5 GHz

Cluster #	Absolute	Power in	AOD in [°]	AOA in [°]	ZOD in [°]	ZOA in [°]
	Delay [ns]	[dB]				
1	0	-4.4215	-36.1891	-122.2815	98.9242	90
2	20.99	-1.25	-21.5937	125.831	99.1915	90
3	22.19	-3.4684	-21.5937	125.831	99.1915	90
4	23.29	-5.2294	-21.5937	125.831	99.1915	90
5	21.76	-2.5215	-32.5709	-143.6126	99.5732	90
6	63.66	0	-7.4275	166.4003	99.306	90
7	64.48	-2.2185	-7.4275	166.4003	99.306	90
8	65.6	-3.9794	-7.4275	166.4003	99.306	90
9	65.84	-7.4215	37.2175	73.8315	100.4513	90
10	79.35	-7.1215	-47.1664	82.7664	98.5616	90
11	82.13	-10.7215	41.5716	-79.6999	100.6231	90
12	93.36	-11.1215	-67.1585	66.9895	98.218	90
13	122.85	-5.1215	-41.5244	84.0543	100.165	90
14	130.83	-6.8215	-47.0437	-96.2818	100.2604	90
15	217.04	-8.7215	-55.7519	94.8406	98.1225	90
16	271.05	-13.2215	55.3698	53.9494	100.2604	90
17	425.89	-13.9215	53.2234	16.0364	98.4852	90
18	460.03	-13.9215	46.8456	32.2963	98.1416	90
19	549.02	-15.8215	-70.1021	18.2098	97.9698	90
20	560.77	-17.1215	48.9306	37.0455	100.7376	90
21	630.65	-16.0215	49.6052	33.7452	98.1225	90
22	663.74	-15.7215	57.7615	29.801	98.1034	90
23	704.27	-21.6215	65.6725	11.6092	100.4513	90
24	865.23	-22.8215	-83.5324	56.2837	100.9476	90
	<u> </u>	Per-C	Cluster Param	eters		
Parameter	CASD in [°]	CASA in [°]	CZSD in [°]	CZSA in [°]	XPR in [dB]	
Value	1.2265	12.0742	0.5726	0	7	

90

90

90

90

90

90

90

90

90

90

90

14

15

16

17

18

19

20

21

22

23

24

Parameter

Value

477.5295

792.196

989.3325

1554.4985

1679.1095

2003.923

2046.8105

2301.8725

2422.651

2570.5855

3158.0895

CASD in [°]

1.3179

Absolute Power in Cluster # AOD in [°] AOA in [°] ZOD in [°] ZOA in [°] Delay [ns] [dB] -4.4215 -37.4195 -96.4031 96.7645 90 0 -1.25 2 76.6135 -21.7362 118.7405 98.4506 90 3 80.9935 -3.4684 -21.7362 118.7405 98.4506 90 4 -5.2294 -21.7362 118.7405 98.4506 85.0085 90 5 79.424 -2.5215 -33.5316 -124.0196 100.8594 90 6 232.359 0 -6.5142 171.2639 99.1732 90 7 235.352 -2.2185 -6.5142 171.2639 99.1732 90 8 239.44 -3.9794-6.5142 171.2639 99.1732 90 9 240.316 -7.4215 41.4581 51.4188 106.3995 90 -49.2149 10 289.6275 -7.1215 62.9864 94.4761 90 -10.7215 -41.2744 11 299.7745 46.1367 107.4834 90 12 340.764 -11.1215 -70.697 42.5606 92.3083 90 13 448.4025 -5.1215 -43.1524 64.6538 104.5929 90

-49.0831

-58.4403

60.9633

58.6569

51.8037

-73.86

54.0442

54.7691

63.5332

72.0338

-88.2912

CZSD in [°]

3.6131

Per-Cluster Parameters

-62.7423

78.6184

25.6781

-23.4063

-2.3553

-20.5926

3.7933

-0.4794

-5.5859

-29.1381

28.7003

CZSA in [°]

0

105.1951

91.7061

105.1951

93.9944

91.8265

90.7426

108.2061

91.7061

91.5856

106.3995

109.5309

XPR in [dB]

Table C.1-2: Channel model parameters for UMa CDL-C at 3.5 GHz

C.2 FR1 Base Station beam configuration

-6.8215

-8.7215

-13.2215

-13.9215

-13.9215

-15.8215

-17.1215

-16.0215

-15.7215

-21.6215

-22.8215

CASA in [°]

15.632

The emulated BS beam configuration to be used for all emulation of channel models defined in Annex C.1 is specified in this clause.

The Base Station beam configuration includes basic antenna parameters and beamforming characteristic. The basic BS antenna parameters is defined in Table C.2-1.

Parameter value Parameter description **Symbol** FR1 ≤2.5GHz FR1 >2.5GHz Antenna panels in vertical dimension M_q 1 1 Antenna panels in horizontal dimension N_g 1 1 Elements per panel in vertical dimension Me 4 8 Elements per panel in horizontal dimension Ne 8 8 Number of polarizations per panel 2 2 Element spacing in horizontal dimension (λ) d_H 0.5 0.5 Element spacing in vertical dimension (λ) 0.5

Table C.2-1: BS Antenna Parameters

Antenna element radiation patterns, including orientation of the element main polarization components as well as orientation of the antenna array are as in the example pattern in Table 7.3-1 of TR38.901. The antenna element has $\pm 45^{\circ}$ polarization components and the radiation pattern parameters are $\theta_{3dB} = 65^{\circ}$, $\phi_{3dB} = 65^{\circ}$, $\phi_{3dB} = 30^{\circ}$,

The beamforming characteristic of the FR1 BS pattern is defined as follow:

- A code book of 60 fixed beams is constructed to a grid of five elevation angles from -20° to $+20^{\circ}$ with 10° steps and 12 azimuth angles from -80° to $+80^{\circ}$ with $\sim 15^{\circ}$ steps;
- For 4x4 MIMO OTA, two strongest transmitting beams are selected from the pre-defined beam grid based on their proximity to the strong clusters of each FR1 channel model. These beams should have different azimuth directions and can provide the highest receive power for UE.
- For 2x2 MIMO OTA, 1 strongest transmitting beam is selected from the pre-defined beam grid which provides the highest received power for UE based on the FR1 channel model.
- Beam directions for channels model given in Annex C.1 are:
 - For UMa CDL-C, the beam directions are:
 - Strongest beam: AoD: -7.27°, ZoD: 100°
 - 2nd strongest beam: AoD: -21.82°, ZoD: 100°
 - For UMi CDL-C, the strongest beam direction is: AoD: -7.27°, ZoD: 100°.

C.3 FR1 Channel model validation

C.3.1 General

This clause describes the MIMO OTA validation measurements, in order to ensure that the channel models are correctly implemented and hence capable of generating the propagation environment, as described by the model, within the test zone.

The following measurements shall be done for FR1 channel model validation:

Power Delay Profile (PDP)

Doppler/Temporal correlation

Spatial correlation

Cross-polarization

Power validation

Frequencies to be used to test for channel model validation:

Table C.3.1-1: Frequencies for PDP, Doppler, Spatial correlation, and Cross-polarization validation

NR FR1 Bands	Range	Test frequency (MHz)
n71		617MHz
n12, n17, n29, n14, n28	Low	722MHz
n5, n8, n18, n20		836.5MHz
n50, n51, n74		1575.42MHz
n3, n2, n25, n39	NA: al	1880MHz
n1, n34, n65	Mid	2132.5MHz
n7, n30, n41, n40, n38, [n90]		2450MHz
n77,n78	Lliab	3600MHz
n79	High	[4700MHz]

Test frequency NR FR1 Bands Range (centre frequency of each band) n71 n71 n12, n17, n29, n14, n28 n28 Low n5, n8, n18, n20 n8 n50, n51, n74 n51 n3, n2, n25, n39 n3 Mid n1, n34, n65 n1 n7, n30, n41, n40, n38, [n90] n41 n77, n78 n78 High n79 n79

Table C.3.1-2: Frequencies for Power validation

C.3.2 Power Delay Profile (PDP)

This measurement checks that the resulting power delay profile (PDP) is in-line with the PDP defined for the channel model. For PDP validation measurement, only Vertical validation is required.

The PDP measurement is performed with a Vector Network Analyser (VNA). An example setup for PDP measurement is shown in Figure C.3.2-1. VNA transmits frequency sweep signals thorough the NR MIMO OTA test system. A reference antenna (i.e dipole antenna), within the centre of the test zone, receives the signal and VNA analyses the frequency response of the system. A number of traces (frequency responses) are measured and recorded by VNA and analysed by a post processing SW, e.g., Matlab. Special care has to be taken into account to keep the fading conditions unchanged, i.e. frozen, during the short period of time of a single trace measurement. The fading may proceed only in between traces.

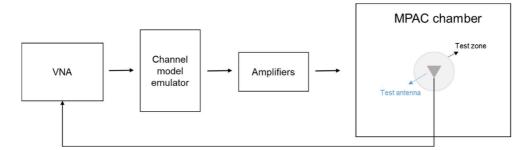


Figure C.3.2-1: Setup for PDP measurements

Step the emulation and store traces from VNA, i.e., run the emulation to CIR number 1, pause, measure VNA trace, run the emulation to CIR number 10, pause, measure VNA trace. Continue until 1000 VNA traces are measured.

VNA settings:

Table C.3.2-1: VNA settings for PDP measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency
Ochire frequency	1711 12	in Table C.3.1-1
Span	MHz	200
Number of traces		1000
Number of points		1101
Averaging		1

Channel model specification:

Table C.3.2-2: Channel model specification for PDP measurements

Item	Unit	Value		
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1		
Distance between traces in channel model	wavelength (Note)	> 2		
Channel model		As specified in Annex C.1		
NOTE: Time [s] = distance $[\lambda]$ / MS speed $[\lambda/s]$ MS speed $[\lambda/s]$ = MS speed $[m/s]$ / Speed of light $[m/s]$ * Centre frequency $[Hz]$				

Method of measurement result analysis:

Measured VNA traces (frequency responses H(t,f)) are saved into a hard drive. The data is read into, e.g., Matlab. The analysis is performed by taking the Fourier transform of each FR. The resulting impulse responses $h(t,\tau)$ are averaged in power over time:

$$P(\tau) = \frac{1}{T} \sum_{t=1}^{T} \left| h(t, \tau) \right|^2$$

Finally the resulting PDP is shifted in delay, such that the first tap is on delay zero.

Beam-Specific Block Diagram

It is assumed that the beams are mapped to the inputs of the channel emulator as follows:

- Beam 1: Input 1 and Input 2
- Beam 2: Input 3 and Input 4 (CDL-C UMa only)

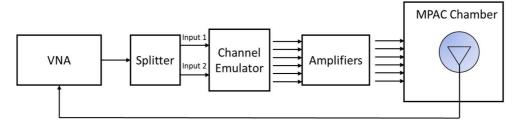


Figure C.3.2-2: Setup for Beam-Specific PDP measurements (Beam 1)

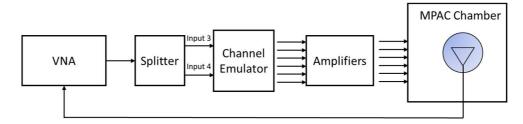


Figure C.3.2-3: Setup for Beam-Specific PDP measurements (Beam 2 CDL-C UMa only)

The detailed PDP reference value for CDL-C UMa and CDL-C UMi validation are defined in the following tables:

Table C.3.2-3: PDP Targets for CDL-C UMa beam 1 at ≤ 2.5 GHz

Combined Clusters index	Delay(ns)	Power(dB)
1	0	-34.3
2-5	80	-19.5
6-8	235	0.0
9-10	290	-33.0
11	450	-35.8
12	480	-34.0

Table C.3.2-4: PDP Targets for CDL-C UMa beam 2 at ≤ 2.5 GHz

Combined Clusters index	Delay(ns)	Power(dB)
1	0	-27.9
2-5	80	0.0
6-8	235	-18.4
9-10	290	-27.8
11	450	-27.9
12	480	-28.0

Table C.3.2-5: PDP Targets for CDL-C UMa beam 1 at > 2.5 GHz

Combined Clusters index	Delay(ns)	Power(dB)
1	0	-34.2
2-5	80	-19.3
6-8	235	0.0
9	290	-34.7
10	450	-35.8
11	480	-34.7

Table C.3.2-6: PDP Targets for CDL-C UMa beam 2 at > 2.5 GHz

Combined Clusters index	delay(ns)	power(dB)
1	0	-27.8
2-5	80	0.0
6-8	235	-18.3
9-10	290	-28.9
11	450	-28.1
12	480	-28.8

Table C.3.2-7: PDP Targets for CDL-C UMi at ≤ 2.5 GHz and > 2.5 GHz

Combined Clusters index	Delay(ns)	Power(dB)
1	0	-30.7
2-5	20	-19.2
6-10	65	0
11-12	130	-31.4

C.3.3 Doppler/Temporal correlation

This measurement checks the Doppler/temporal correlation. For Doppler/Temporal correlation validation measurement, only Vertical validation is required.

The Doppler spectrum is measured with a spectrum analyser as shown in Figure C.3.3-1. In this case a signal generator transmits CW signal through the NR MIMO OTA test system. The signal is received by a test antenna within the test area. Finally, the signal is analysed by a spectrum analyser and the measured spectrum is compared to the target spectrum. This setup can be used to measure Doppler Spectrum of the Channel models defined in Annex C.1.

Method of measurement:

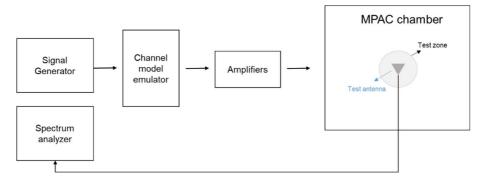


Figure C.3.3-1: Setup for Doppler measurements

Sine wave (CW, carrier wave) signal is transmitted from the signal generator. The signal is connected from the signal generator to fading emulator via cables. The fading emulator output signals are connected to power amplifier boxes via cables. The amplified signals are then transferred via cables to the probe antennas. The probe antennas radiate the signals over the air to the test antenna. The Doppler spectrum is measured by the spectrum analyser and the trace is saved.

Signal generator settings:

Table C.3.3-1: Signal generator settings for Doppler/Temporal correlation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1
Modulation		OFF

Spectrum analyser settings:

Table C.3.3-2: Spectrum analyser settings for Doppler/Temporal correlation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1
Minimum Span	Hz	4 kHz
RBW	Hz	1
VBW	Hz	1
Number of points		16002
Averaging		100

Channel model specification:

Table C.3.3-3: Channel model specification for Doppler/Temporal correlation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1
Channel model		As specified in Annex C.1
Mobile speed	km/h	100

Method of measurement result analysis: Measurement data file (Doppler power spectrum) is saved into hard drive. The data is read into, e.g., Matlab. The analysis is performed by taking the Fourier transformation of the Doppler spectrum.

The resulting temporal correlation function $R_t(\Delta t)$ is normalized such that $\max(abs(R_t(\Delta t)))=1$. Then the function values left from the maximum i.e., the negative lags are cut out. Further on the function values after five periods are cut out.

Time Domain Alternate Method

Time domain techniques can also be used to validate the tempoal correlation. The temporal correlation validation measurement setup is illustrated in Figure C.3.3-2. In this case a Signal generator transmits a CW signal through the MIMO test system. The signal is received by a test antenna within the test area. Finally, the signal is collected by a signal analyser and the measured signal is stored as IQ data format for postprocessing.

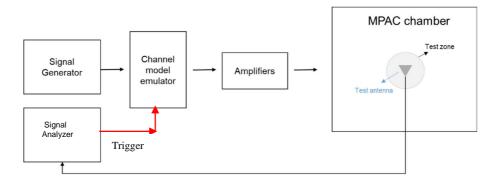


Figure C.3.3-2: Setup for Doppler measurements based on time domain technique

The time domain doppler spectrum is measured by the signal analyzer and the trace in IQ format is saved. Follow the same procedure to post process the data and calculate the temporal correlation curve. Data recording is synchronized with the channel emulator trigger.

The settings for the signal analyzer are in Table C.3.3-4:

Table C.3.3-4: Signal Analyser Settings

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1
Sampling	Hz	At least 15 times bigger than the max Doppler spread $(f_d=v/\lambda)$
Observation time	S	At least 16s. Channel Model length should be the same or greater than the observation time.

Beam-Specific Block Diagram

It is assumed that the beams are mapped to the inputs of the channel emulator as follows:

- Beam 1: Input 1 and Input 2
- Beam 2: Input 3 and Input 4 (CDL-C UMa only)

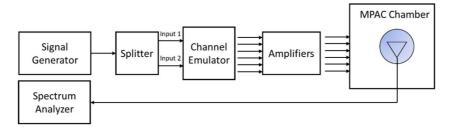


Figure C.3.3-3: Setup for Beam-Specific Doppler measurements (Beam 1)

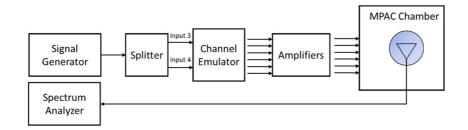


Figure C.3.3-4: Setup for Beam-Specific Doppler measurements (Beam 2 CDL-C UMa only)

The detailed Temporal correlation reference value for CDL-C UMa and CDL-C UMi channel model validation is defined is table C.3.3-5.

Table C.3.3-5: Autocorrelation Targets

Lambda Separation	CDL-C UMa beam 1 at ≤ 2.5 GHz	CDL-C UMa beam 2 at ≤ 2.5 GHz	CDL-C UMa beam 1 at > 2.5 GHz	CDL-C UMa beam 2 at > 2.5 GHz	CDL-C UMi beam 1 at ≤ 2.5 GHz	CDL-C UMi beam 1 at > 2.5 GHz
0.0	1.000	1.000	1.000	1.000	1.000	1.000
0.1	0.986	0.974	0.985	0.973	0.995	0.995
0.2	0.945	0.907	0.942	0.904	0.982	0.982
0.3	0.882	0.832	0.874	0.825	0.962	0.961
0.4	0.801	0.776	0.787	0.765	0.936	0.935
0.5	0.709	0.738	0.689	0.723	0.906	0.905
0.6	0.613	0.695	0.586	0.675	0.872	0.871
0.7	0.518	0.623	0.486	0.599	0.834	0.834
0.8	0.430	0.525	0.394	0.496	0.793	0.793
0.9	0.353	0.426	0.315	0.391	0.750	0.749
1.0	0.289	0.360	0.252	0.319	0.705	0.704
1.1	0.240	0.335	0.206	0.290	0.659	0.658
1.2	0.204	0.320	0.174	0.273	0.614	0.612
1.3	0.181	0.287	0.154	0.239	0.569	0.568
1.4	0.167	0.233	0.143	0.185	0.527	0.525
1.5	0.159	0.176	0.137	0.129	0.487	0.485
1.6	0.155	0.141	0.135	0.096	0.450	0.448
1.7	0.153	0.135	0.134	0.092	0.417	0.415
1.8	0.150	0.137	0.134	0.095	0.387	0.385
1.9	0.144	0.132	0.130	0.093	0.361	0.358
2.0	0.135	0.117	0.122	0.089	0.337	0.335
2.1	0.121	0.097	0.109	0.086	0.316	0.313
2.2	0.105	0.076	0.090	0.076	0.296	0.293
2.3	0.085	0.062	0.069	0.064	0.277	0.274
2.4	0.065	0.071	0.047	0.067	0.258	0.255
2.5	0.048	0.090	0.031	0.088	0.239	0.236
2.6	0.039	0.099	0.033	0.103	0.219	0.216
2.7	0.038	0.088	0.046	0.099	0.198	0.195
2.8	0.042	0.058	0.057	0.073	0.178	0.175
2.9	0.043	0.037	0.062	0.038	0.158	0.154
3.0	0.041	0.067	0.060	0.045	0.138	0.135
3.1	0.037	0.103	0.050	0.080	0.120	0.116
3.2	0.036	0.120	0.036	0.100	0.103	0.100
3.3	0.044	0.115	0.019	0.099	0.089	0.085

3.4	0.056	0.097	0.010	0.081	0.076	0.073
3.5	0.068	0.082	0.019	0.061	0.066	0.063
3.6	0.075	0.083	0.029	0.053	0.057	0.055
3.7	0.076	0.090	0.034	0.060	0.051	0.049
3.8	0.068	0.089	0.036	0.073	0.046	0.044
3.9	0.051	0.079	0.044	0.091	0.042	0.041
4.0	0.027	0.068	0.062	0.111	0.039	0.038
4.1	0.007	0.063	0.090	0.127	0.037	0.035
4.2	0.036	0.062	0.123	0.133	0.036	0.034
4.3	0.067	0.057	0.155	0.129	0.038	0.036
4.4	0.093	0.052	0.182	0.126	0.043	0.040
4.5	0.111	0.055	0.200	0.131	0.051	0.048
4.6	0.119	0.063	0.207	0.139	0.061	0.058
4.7	0.116	0.066	0.200	0.138	0.073	0.070
4.8	0.101	0.058	0.180	0.117	0.085	0.082
4.9	0.078	0.047	0.149	0.079	0.096	0.093
5.0	0.051	0.048	0.110	0.034	0.107	0.104

C.3.4 Spatial correlation

This measurement checks whether the measured correlation curve follows the theoretical curve. For spatial correlation validation measurement, only Vertical validation measurement is required. Spatial correlation validation is only adopted for FR1 MIMO OTA.

The spatial correlation validation measurement setup is illustrated in Figure C.3.4-1. The network analyser transmits signals through the fading emulator and probes. The 16 probes radiate the signals within the anechoic chamber and a receiving test antenna is placed within the test zone. The test antenna is attached to a positioner that can move the antenna to pre-defined spatial locations on a fixed radius from the centre of the quiet zone. The received signal is measured with the network analyser.

The measurement and analysis procedure are as follows:

Set the target channel model to fading emulator.

- 1. For each position of the test antenna in the test zone, step & pause the emulator to different time instances. Measure the frequency responses H(f,t) = H(mΔf, nΔT), m = 0, ..., M 1 for all stepped channel snapshots n = 0, ..., N 1, where the interval between frequency and time samples is Δf and ΔT, respectively. The number of channel snapshots N and frequency samples M should be sufficiently high so that the matrix can be estimated reliably.
- 2. Move the measurement antenna with a positioner to another location k and repeat step 2 to record frequency responses $H_k(m\Delta f, n\Delta T)$ of all stepped channel snapshots.
- 3. Repeat step 3 to record frequency responses at all k = 1, ..., K spatial sample points.
- 4. Stack measured time and frequency samples to a vector and calculate correlation between the first spatial sample point (i.e. k = 1) and other spatial points k = 1, ... K
- 5. $\rho_k = \text{corr} \big[\text{vec} \big(H_1(m \Delta f, n \Delta T) \big), \text{vec} \big(H_k(m \Delta f, n \Delta T) \big) \big]$
- 6. Take the theoretical reference spatial correlation of the corresponding spatial sample points. Plot both the measured and theoretical curves.
- 7. Calculate the weighted RMS correlation error between the measured and the reference.

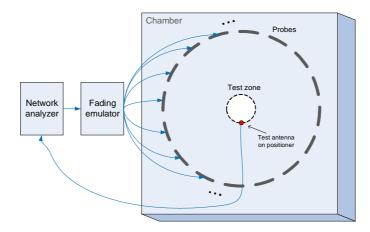


Figure C.3.4-1: Configuration for spatial correlation validation

Beam-Specific Block Diagram

It is assumed that the beams are mapped to the inputs of the channel emulator as follows:

- Beam 1: Input 1 and Input 2
- Beam 2: Input 3 and Input 4 (CDL-C UMa only)

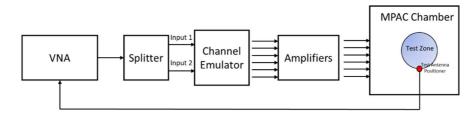


Figure C.3.4-2: Configuration for spatial correlation validation (CDL-C UMi)

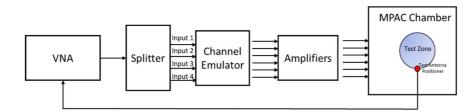


Figure C.3.4-3: Configuration for spatial correlation validation (CDL-C UMa)

Time and frequency samples

The number of temporal snapshots N and frequency samples M is shown in Table C.3.4-1. The channel model specification is presented in Table C.3.4-2.

Table C.3.4-1: VNA settings for spatial correlation

Item	Unit	Value						
Center frequency	MHz	Downlink centre frequency in Table C.3.1-1						
Span	MHz	0 (Note 2)						
RF output level	dBm	-15						
Number of traces		1000						
Distance between traces in channel model	Wavelength (Note 1)	> 2						
Number of points		1 (or the smallest possible) (Note 2)						
Averaging		1						
NOTE1: Time in seconds = distance $[\lambda]$ / MS speed $[\lambda/s]$ MS speed $[\lambda/s]$ = MS speed [m /s] / Speed of light [m/s] * Center frequency [Hz]								

Span and number of points may be increased to estimate reliably

Table C.3.4-2: Channel model specification

Item	Unit	Value
Center frequency	MHz	Downlink centre frequency in Table C.3.1-1
Channel model samples	Wavelength	> 2000
Channel model		As specified in Annex C.1
Mobile speed	km/h	30

Spatial samples

The spatial samples for the correlation validation measurement are on the circumference of the quiet zone, as illustrated in Figure C.3.4-2. The test zone is a circle with 20 cm diameter in the horizontal plane. The reference point (denoted by a red marker) is in AoA 270°. The mean AoAs of the CDL-C UMi and CDL-C UMa models are slightly different, but the underlying geometry for the CDL model indicates that the mean AoA (or assumed LoS direction) of the model is 180°. The reference point orientation of the validation measurement is proposed to be with 90° offset to the channel model reference AoA to enable accurate sampling of the main lobe of the spatial correlation curve. The reference point orientation must be defined in the channel model coordinate system instead of the chamber/probe coordinate system to enable optimization of OTA model implementation to achieve better alignment with the cluster AoAs and probe directions. In order to have spatial samples that yield reasonable measurement times and adequately capture the main lobe of the correlation curve, a non-uniform sampling is used where the first quadrant i.e., 270°-180°, is sampled with dense sampling compared to the rest of the circle. The spacing of the spatial samples is summarized in Table C.3.4-1 for test frequencies less than 1800 MHz and equal to or greater than 1800 MHz.

Table C.3.4-1: Spacing of Spatial Samples

Test Frequencies [MHz]	First quadrant of test zone circumference (270°-180°)	Remaining quadrants
617, 722, 836.5 1575.42	λ/15	λ/4
1800, 2132.50, 2450, 3600, 4700	λ/10	λ/2

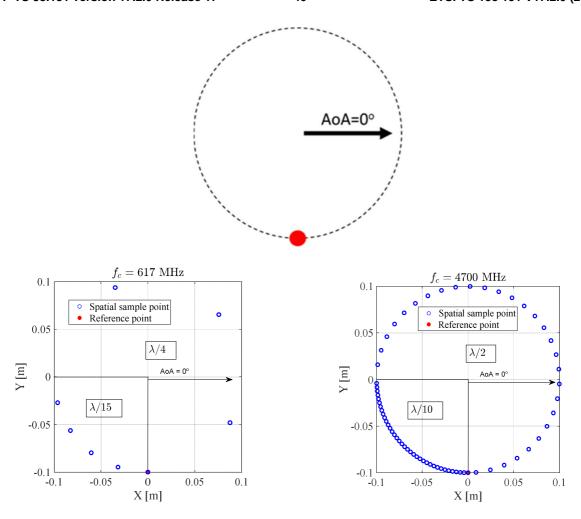


Figure C.3.4-2: Spatial sampling for spatial correlation validation measurement for test frequencies less than and equal to or greater than 1800 MHz: 617 MHz spatial sampling (left) and 4700 MHz spatial sampling (right).

Reference Spatial Correlation Curves

The spatial correlation validation reference curves are tabulated in Tables C.3.4-2 and C.3.4-3 for CDL-C UMi and CDL-C UMa, respectively, for a vertically polarized MPAC OTA setup with 16 uniformly spaced probes.

Table C.3.4-2: Spatial correlation reference curves for CDL-C UMi model for a vertically polarized MPAC OTA setup with 16 uniformly spaced probes at FR1 test frequencies

617 N	1Hz	722 MI	Ηz	836.5	MHz	1575.42	2 MHz	1800 N	ИHz
Azim [°]	 ρ beam 1	Azim [°]	ρ beam 1	Azim [°]	ρ beam 1	Azim [°]	ρ beam 1	Azim [°]	ρ beam 1
270.0	1.00	270.0	1.00	270.0	1.00	270.0	1.00	270.0	1.00
251.4	1.00	254.1	1.00	256.3	1.00	262.7	1.00	260.9	1.00
232.9	1.00	238.3	1.00	242.6	1.00	255.5	1.00	251.7	1.00
214.3	0.99	222.4	1.00	228.9	1.00	248.2	1.00	242.6	0.99
195.8	0.99	206.6	0.99	215.2	0.99	240.9	0.99	233.5	0.99
110.4	0.87	190.7	0.98	201.6	0.98	233.7	0.99	224.3	0.98
40.8	0.87	120.5	0.84	187.9	0.96	226.4	0.99	215.2	0.97
331.2	0.98	61.1	0.80	128.7	0.82	219.1	0.98	206.0	0.95
		1.6	0.91	77.3	0.73	211.9	0.97	196.9	0.92
		302.1	0.99	26.0	0.81	204.6	0.96	187.8	0.87
				334.7	0.95	197.3	0.94	134.3	0.39
				283.3	1.00	190.0	0.91	88.6	0.15
						182.8	0.87	43.0	0.24
						152.7	0.66	357.3	0.62

	l	1		125.5	0.44	311.6	0.94
				98.2	0.30		
				71.0	0.28		
				43.7	0.37		
				16.5	0.54		
				349.2	0.75		
				321.9	0.91		
				294.7	0.99		

2132.5	MHz	2450 M	Hz	3600	MHz	4700 MHz	
Azim [°]	ρ beam 1	Azim [°]	ρ beam 1	Azim [°]	ρ beam 1	Azim [°]	ρ beam 1
270.0	1.00	270.0	1.00	270.0	1.00	270.0	1.00
261.9	1.00	263.0	1.00	265.2	1.00	266.3	1.00
253.9	1.00	256.0	1.00	260.5	1.00	262.7	1.00
245.8	0.99	249.0	0.99	255.7	0.99	259.0	0.99
237.8	0.99	242.0	0.99	250.9	0.99	255.4	0.99
229.7	0.98	234.9	0.99	246.1	0.99	251.7	0.99
221.7	0.97	227.9	0.98	241.4	0.98	248.1	0.98
213.6	0.96	220.9	0.97	236.6	0.98	244.4	0.98
205.6	0.93	213.9	0.95	231.8	0.97	240.8	0.98
197.5	0.89	206.9	0.92	227.1	0.97	237.1	0.97
189.5	0.84	199.9	0.88	222.3	0.95	233.5	0.97
181.4	0.77	192.9	0.83	217.5	0.93	229.8	0.96
139.7	0.27	185.9	0.76	212.7	0.90	226.1	0.95
99.5	0.14	144.9	0.19	208.0	0.86	222.5	0.93
59.2	0.14	109.9	0.26	203.2	0.81	218.8	0.91
18.9	0.26	74.8	0.37	198.4	0.75	215.2	0.87
338.6	0.71	39.8	0.19	193.7	0.68	211.5	0.83
298.4	0.97	4.7	0.29	188.9	0.59	207.9	0.78
		329.7	0.74	184.1	0.49	204.2	0.72
		294.6	0.97	156.1	0.23	200.6	0.64
				132.3	0.62	196.9	0.56
				108.4	0.85	193.3	0.47
				84.6	0.93	189.6	0.37
				60.7	0.92	185.9	0.27
				36.9	0.79	182.3	0.18
				13.0	0.42	161.7	0.51
				349.1	0.15	143.5	0.83
				325.3	0.60	125.2	0.95
				301.4	0.90	106.9	0.89
				277.6	1.00	88.6	0.80
						70.4	0.78
						52.1	0.88
						33.8	0.98
						15.5	0.91
						357.3	0.53
						339.0	0.09
						320.7	0.50
						302.4	0.82
						284.2	0.97

Table C.3.4-3: Spatial correlation reference curves for CDL-C UMa model for a vertically polarized MPAC OTA setup with 16 uniformly spaced probes at FR1 test frequencies

617 MHz		722	722 MHz		836.5 MHz		1575.42 MHz		1800 MHz	
Azim [°]	ρ comb	Azim [°]	ρ comb	Azim [°]	ρ comb	Azim [°]	ρ comb	Azim [°]	ρ comb	
270.0	1.00	270.0	1.00	270.0	1.00	270.0	1.00	270.0	1.00	
251.4	0.99	254.1	0.99	256.3	0.99	262.7	0.99	260.9	0.99	
232.9	0.99	238.3	0.98	242.6	0.98	255.5	0.98	251.7	0.96	

•	1	•		•	1		•	•	•
214.3	0.98	222.4	0.97	228.9	0.97	248.2	0.96	242.6	0.93
195.8	0.96	206.6	0.96	215.2	0.96	240.9	0.94	233.5	0.90
110.4	0.61	190.7	0.94	201.6	0.95	233.7	0.92	224.3	0.89
40.8	0.47	120.5	0.58	187.9	0.92	226.4	0.91	215.2	0.88
331.2	0.85	61.1	0.30	128.7	0.56	219.1	0.90	206.0	0.87
		1.6	0.56	77.3	0.19	211.9	0.89	196.9	0.84
		302.1	0.95	26.0	0.27	204.6	0.88	187.8	0.79
				334.7	0.70	197.3	0.87	134.3	0.16
				283.3	0.99	190.0	0.84	88.6	0.30
						182.8	0.79	43.0	0.22
						152.7	0.42	357.3	0.36
						125.5	0.13	311.6	0.57
						98.2	0.30		
						71.0	0.31		
						43.7	0.29		
						16.5	0.33		
						349.2	0.29		
						321.9	0.48		
						294.7	0.88		

2132	.5 MHz	2450	0 MHz	360	0 MHz	470	4700 MHz		
Azim [°]	ρ comb								
270.0	1.00	270.0	1.00	270.0	1.00	270.0	1.00		
261.9	0.99	263.0	0.99	265.2	0.98	266.3	0.98		
253.9	0.95	256.0	0.95	260.5	0.95	262.7	0.94		
245.8	0.92	249.0	0.91	255.7	0.90	259.0	0.89		
237.8	0.89	242.0	0.87	250.9	0.84	255.4	0.83		
229.7	0.86	234.9	0.85	246.1	0.80	251.7	0.78		
221.7	0.85	227.9	0.83	241.4	0.77	248.1	0.73		
213.6	0.85	220.9	0.82	236.6	0.75	244.4	0.70		
205.6	0.83	213.9	0.82	231.8	0.73	240.8	0.68		
197.5	0.80	206.9	0.80	227.1	0.72	237.1	0.66		
189.5	0.75	199.9	0.77	222.3	0.71	233.5	0.65		
181.4	0.67	192.9	0.73	217.5	0.70	229.8	0.64		
139.7	0.22	185.9	0.66	212.7	0.69	226.1	0.63		
99.5	0.24	144.9	0.26	208.0	0.67	222.5	0.62		
59.2	0.03	109.9	0.23	203.2	0.64	218.8	0.61		
18.9	0.16	74.8	0.19	198.4	0.61	215.2	0.60		
338.6	0.37	39.8	0.13	193.7	0.56	211.5	0.59		
298.4	0.73	4.7	0.15	188.9	0.49	207.9	0.57		
		329.7	0.38	184.1	0.41	204.2	0.55		
		294.6	0.74	156.1	0.42	200.6	0.52		
				132.3	0.19	196.9	0.48		
				108.4	0.64	193.3	0.42		
				84.6	0.47	189.6	0.35		
				60.7	0.44	185.9	0.26		
				36.9	0.28	182.3	0.18		
				13.0	0.16	161.7	0.59		
				349.1	0.16	143.5	0.26		
				325.3	0.41	125.2	0.79		
				301.4	0.40	106.9	0.43		
				277.6	0.95	88.6	0.68		
						70.4	0.63		
						52.1	0.75		
						33.8	0.87		
						15.5	0.67		
						357.3	0.09		
						339.0	0.25		
						320.7	0.32		

1		1		302.4	0.42
				284.2	0.73

Time Domain Alternative Method:

Time domain techniques can also be used to validate the spatial correlation. The spatial correlation validation measurement setup is illustrated in Figure C.3.4-3. In this case a Signal generator transmits a CW signal through the MIMO test system. The signal is received by a test antenna within the test area. Finally, the signal is collected by a signal analyser and the measured signal is stored for postprocessing.

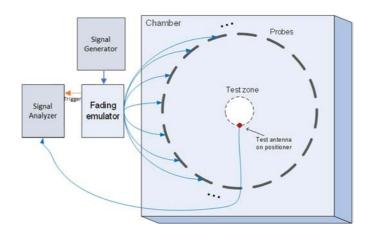


Figure C.3.4-3: Configuration for spatial correlation validation based on time domain techniques

For each spatial point, the channel emulator should issue a trigger signal each time fading is started. For each point collect a time domain trace with the signal analyser, when done, stop fading. Data recording is synchronized with the channel emulator trigger.

Follow the same procedure to postprocess the data and calculate the spatial correlation by setting m to 1. The settings for the Signal Generator and Signal Analyser are in Table C.3.4-6 and C.3.4-7 respectively.

Table C.3.4-6: Signal Generator Settings

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1
Output power	dBm	Function of the CE. Sufficiently above Noise Floor

Table C.3.4-7: Signal Analyser Settings

Item	Value	
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1
Sampling	Hz	At least 15 times bigger than the max Doppler spread $(f_0=v/h)$
Observation time s		At least 16s. Channel Model length should be the same or greater than the observation time.

Beam-Simultaneous Block Diagram

It is assumed that the beams are mapped to the inputs of the channel emulator as follows:

- Beam 1: Input 1 and Input 2
- Beam 2: Input 3 and Input 4 (CDL-C UMa only)

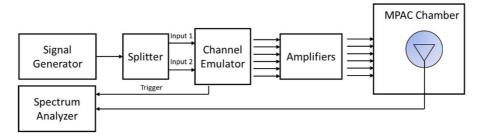


Figure C.3.4-4: Configuration for spatial correlation validation based on time domain techniques (CDL-C UMi)

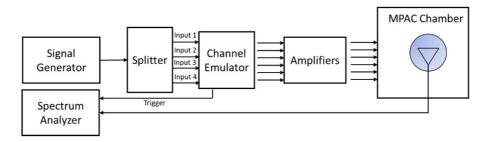


Figure C.3.4-5: Configuration for spatial correlation validation based on time domain techniques (CDL-C UMa)

C.3.5 Cross-polarization

This measurement checks how well the measured vertically or horizontally polarized power levels follow expected values. The test setup for cross-polarization is the same as PDP validation in Figure C.3.2-1.

Method of measurement: Step the emulation and store traces from VNA.

VNA settings:

Table C.3.5-1: VNA settings for cross-polarization

Item	Unit	Value
Centre frequency	MHz	Downlink Centre Frequency in Table C.3.1-1
Span	MHz	40
Number of traces		1000
Number of points		802
Averaging		1

Channel model specification:

Table C.3.5-2: Channel model specification for cross-polarization.

Item	Unit	Value					
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-1					
Distance between traces in channel model	I model wavelength (Note) > 2						
Channel model		As specified in Annex C.1					
Mobile speed (**	km/h	30					
NOTE: Time [s] = distance $[\lambda]$ / MS speed $[\lambda/s]$							
MS speed [\(\alpha\s\)] = MS speed [m/s] / Speed of light [m/s] * Centre frequency [Hz] (** The mobile speed is valid for the Time Domain Alternative method only							

Measurement Procedure:

Step the emulation and store traces from VNA. i.e., run the emulation to CIR number 1, pause, measure VNA trace, run the emulation to CIR number 10, pause, measure VNA trace. Continue until 1000 VNA traces are measured.

- a. Use a vertically polarized sleeve dipole to measure the V component.
- b. Use a horizontally polarized (vertically oriented) magnetic loop dipole, or a horizontally polarized sleeve dipole measured in four orthogonal horizontal positions and summed to measure the H component.

Method of measurement result analysis:

Measured VNA traces (frequency responses $H_V(t, f)$ and $H_H(t, f)$ are saved into a hard drive. The data is read into, e.g., Matlab. The frequency responses are averaged in power over time and frequency and the V/H ratio calculated as follows:

$$\begin{aligned} P_V &= \sum_t \sum_f |H_V(t,f)|^2 \\ P_H &= \sum_t \sum_f |H_H(t,f)|^2 \\ P_{V/H}[dB] &= 10 log_{10} \left(\frac{P_V}{P_H}\right) \end{aligned}$$

Beam-Specific Block Diagram

It is assumed that the beams are mapped to the inputs of the channel emulator as follows:

- Beam 1: Input 1 and Input 2
- Beam 2: Input 3 and Input 4 (CDL-C UMa only)

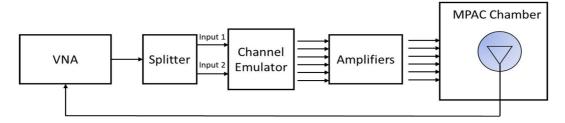


Figure C.3.5-1: Setup for Beam-Specific V/H measurements (Beam 1)

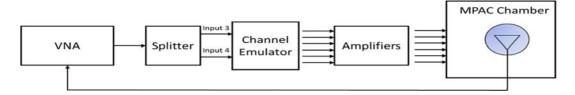


Figure C.3.5-2: Setup for Beam-Specific V/H measurements (Beam 2 CDL-C UMa only)

Time Domain Alternative Method:

The power in the Vertical and Horizontal polarizations can also be measured in time domain. The measurement setup for Beam-Specific are presented in Figures C.3.5-3, and C.3.5-4.

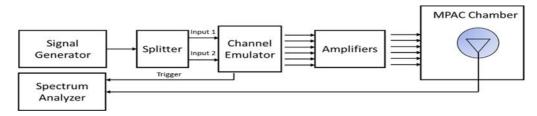


Figure C.3.5-3: Setup for Beam-Specific V/H measurements (Beam 1)

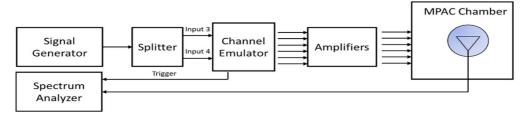


Figure C.3.5-4: Setup for Beam-Specific V/H measurements (Beam 2 CDL-C UMa only)

The instruments settings are the same as those in C.3.4-6 and C.3.4-7. The measurement analysis is the same as that of the frequency domain method setting the summation over f to a single point.

The reference V/H-ratios for CDL-C UMa and CDL-C UMi channel model validation are defined in table C.3.5-3 and C.3.5-4, respectively.

Table C.3.5-3: Reference V/H-ratios for CDL-C UMa

UMa C, fc ≤ 2.5 GHz	Beam 1	Input 1+2: V/H = 0 dB
	Beam 2	Input $3+4$: V/H = 0 dB
UMa C, fc > 2.5 GHz	Beam 1	Input $1+2$: V/H = 0 dB
	Beam 2	Input $3+4$: V/H = 0 dB

Table C.3.5-4: Reference V/H-ratios for CDL-C UMi

ĺ	UMi C, fc ≤ 2.5 GHz	Beam 1	Inputs 1+2: V/H = 0 dB
	UMi C, fc > 2.5 GHz	Beam 1	Inputs 1+2: V/H = 0 dB

C.3.6 Power validation

This measurement checks the total power in the centre of the test zone. The power validation is measured with a spectrum analyser as shown in Figure C.3.6-1.

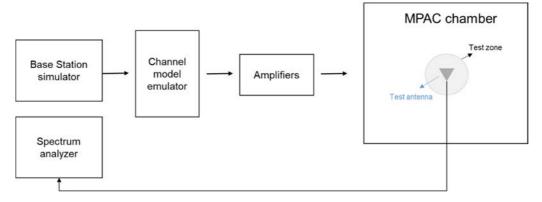


Figure C.3.6-1: Setup for power validation measurements

Spectrum analyser settings:

Table C.3.6-1: Spectrum analyser settings for power validation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table C.3.1-2
Integrated Channel Span	Hz	40MHz
RBW	Hz	30 kHz
VBW	Hz	≥10MHz
Number of points		≥400
Averaging		≥100
Detector		RMS

Measurement Procedure:

- 1. Place a vertical reference dipole in the centre of the test zone connected to a spectrum analyser (or power meter) via a cable.
- 2. Record the cable and reference dipole gains.
- 3. Load the target channel model into the channel emulator and play the model.
- 4. Start the NR FR1 signaling in the base station emulator with the required parameter identical to the measurements conditions.
- 5. Average the power received by the spectrum analyser for a sufficient amount of time to account for the fading channel one full channel simulation might be unnecessary.
- 6. Repeat steps 1 to 4 with a magnetic loop for the horizontal polarization, or a horizontally polarized sleeve dipole measured in at least four orthogonal horizontal positions and average the summed orientations to get the H component.
- 7. Calculate the total power received at the test area as the sum of the power in the two polarizations.

Note: in step 6, if horizontally polarized sleeve dipole is used, the reference gain correction should be the average of the theta gain pattern cut of the dipole. Besides, more horizontal positions for averaging will improve the measurement accuracy but increase the total measurement time.

The power validation result is considered as systematic offset, which needs to be corrected on the UE final sensitivity value to further reduce measurement uncertainty.

The detailed power validation setup for CDL-C UMi and CDL-C UMa channel models are illustrated in Figure C.3.6-2 and Figure C.3.6-3.

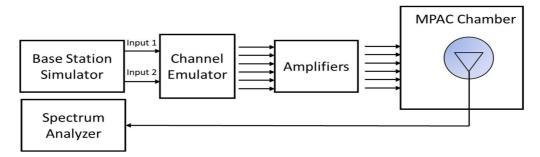


Figure C.3.6-2: Setup for power validation measurements for CDL-C UMi

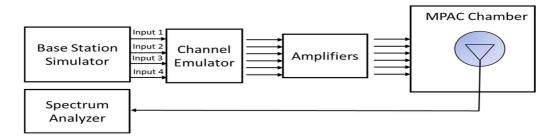


Figure C.3.6-3: Setup for power validation measurements for CDL-C UMa

C.4 Validation Pass/fail limit

C.4.1 General

This clause defines the pass/fail limit of FR1 MPAC system for FR1 channel model validation.

C.4.2 Pass/Fail Criteria of PDP

This clause defines the pass/fail criteria of PDP, this pass/fail limits apply for all FR1 frequency bands, for both combined and individual beams.

The detailed pass/fail limits for each cluster of CDL-C UMa and CDL-C UMi are defined in Table C.4.2-1.

Table C.4.2-1: PDP pass/fail limits for CDL-C UMa and CDL-C UMi channel model validation

	Power Tolerance	Delay Tolerance
Paths from 0dB to 10dB	±1dB	±6ns
Paths from 10dB to 20dB	±2.5dB	±6ns
Paths from 20dB to 30dB	±5dB	±6ns
Paths from 30dB to 40dB	±10dB	±6ns

C.4.3 Pass/Fail Criteria of Doppler/Temporal correlation

This clause defines the pass/fail criteria of doppler/temporal correlation, this pass/fail limits apply for all channel models in all FR1 frequency bands, for both combined and individual beams.

The pass/fail limits for theoretical temporal correlation defined in Clause C.3.3 above 0.3 are formed as bands of ± 0.1 of correlation capped at 1 at the high end. Additionally, when the theoretical temporal correlation drops below 0.3, the limits are formed at bands of ± 0.3 of correlation capped at 0 at the low end.

Table C.4.3-1: pass/fail limits for temporal correlation

CDL-0	C UMa	CDL-	C UMa	CDL-0	C UMa	CDL-	·C UMa	CDL-	C UMi	CDL-	CUMi
	at ≤ 2.5		at ≤ 2.5		at > 2.5		2 at > 2.5		at ≤ 2.5	beam 1	
	Hz		Hz		Hz		Hz		Hz	GI	
Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper
0.9	1	0.9	1	0.9	1	0.9	1	0.9	1	0.9	1
0.886	1	0.874	1	0.885	1	0.873	1	0.895	1	0.895	1
0.845	1	0.807	1	0.842	1	0.804	1	0.882	1	0.882	1
0.782	0.982	0.732	0.932	0.774	0.974	0.725	0.925	0.862	1	0.861	1
0.701	0.901	0.676	0.876	0.687	0.887	0.665	0.865	0.836	1	0.835	1
0.609	0.809	0.638	0.838	0.589	0.789	0.623	0.823	0.806	1	0.805	1
0.513	0.713	0.595	0.795	0.486 0.386	0.686	0.575	0.775	0.772	0.972	0.771	0.971
0.418	0.618 0.53	0.523 0.425	0.723 0.625	0.386	0.586 0.494	0.499 0.396	0.699 0.596	0.734 0.693	0.934	0.734 0.693	0.934
0.33	0.53	0.425	0.625	0.294	0.494	0.396	0.396	0.65	0.85	0.649	0.849
0.253	0.455	0.326	0.326	0.213	0.413	0.291	0.491	0.605	0.805	0.604	0.804
0.169	0.369	0.235	0.435	0.132	0.306	0.219	0.419	0.559	0.759	0.558	0.758
0.104	0.304	0.233	0.433	0.100	0.300	0.173	0.373	0.514	0.739	0.512	0.738
0.104	0.304	0.187	0.387	0	0.3	0.173	0.339	0.469	0.669	0.468	0.668
0	0.3	0.133	0.333	0	0.3	0.139	0.33	0.427	0.627	0.425	0.625
0	0.3	0.133	0.333	0	0.3	0	0.3	0.387	0.587	0.425	0.585
0	0.3	0	0.3	0	0.3	0	0.3	0.35	0.55	0.348	0.548
0	0.3	0	0.3	0	0.3	0	0.3	0.317	0.517	0.315	0.515
0	0.3	0	0.3	0	0.3	0	0.3	0.287	0.487	0.285	0.485
0	0.3	0	0.3	0	0.3	0	0.3	0.261	0.461	0.258	0.458
0	0.3	0	0.3	0	0.3	0	0.3	0.237	0.437	0.235	0.435
0	0.3	0	0.3	0	0.3	0	0.3	0.216	0.416	0.213	0.413
0	0.3	0	0.3	0	0.3	0	0.3	0.196	0.396	0.193	0.393
0	0.3	0	0.3	0	0.3	0	0.3	0.177	0.377	0.174	0.374
0	0.3	0	0.3	0	0.3	0	0.3	0.158	0.358	0.155	0.355
0	0.3	0	0.3	0	0.3	0	0.3	0.139	0.339	0.136	0.336
0	0.3	0	0.3	0	0.3	0	0.3	0.119	0.319	0.116	0.316
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3 0.3	0	0.3	0	0.3
0	0.3	U	0.3	U	0.3	0	0.3	U	0.3	U	0.3
U	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
0	0.3	0	0.3	0	0.3	0	0.3	0	0.3	0	0.3
	0.0		0.0		0.0		0.0		0.0		5.5

Based on the value defined in Table C.4.3-1, Figure C.4.3-1 shows the pass/fail and reference curve of temporal correlation.

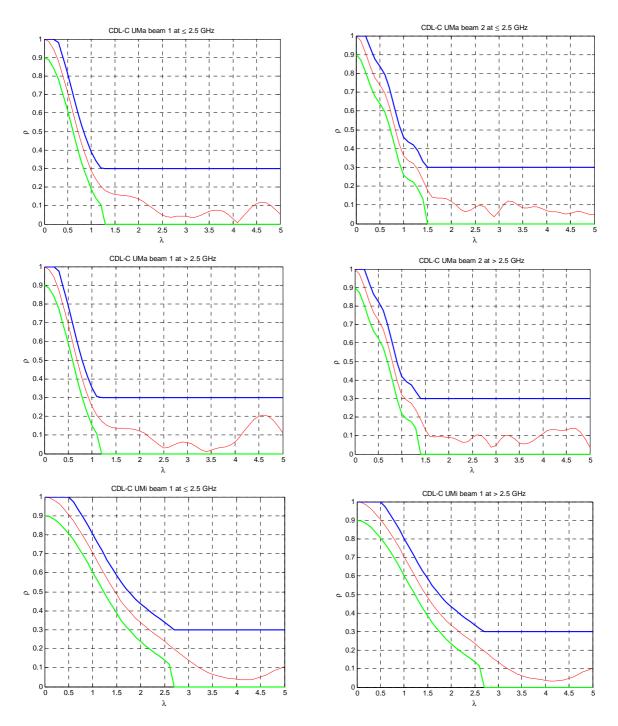


Figure C.4.3-1: Pass/fail limits and targets of Temporal correlation for CDL-C UMa and CDL-C UMi channel model: red curve (reference), blue (upper limit) and green (lower limit)

C.4.4 Pass/Fail Criteria of Spatial correlation

This clause defines the pass/fail criteria of spatial correlation, this general pass/fail limits principle apply for all channel models in all FR1 frequency bands, for both combined and individual beams.

The pass/fail limits for spatial correlation are formed as bands of $\pm 10\%$ of correlation capped at 100% for the upper limit for target correlation defined in clause C.3.4 of 35% (for CDL-C UMa @3600MHz, this value is 65%) and above. For target correlations below 35% (for CDL-C UMa @3600MHz, this value is 65%), the band is widened to $\pm 20\%$ capped at 0%.

For the detailed pass/fail limit, the values are defined in the Table C.4.4-1 and Table C.4.4-2, for CDL-C UMi and CDL-C UMa channel model, respectively.

Table C.4.4-1: Spatial correlation pass/fail limits for CDL-C UMi channel model

617 MHz		722 MHz		836.5	836.5 MHz		2 MHz	1800 MHz		
Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	0.89	1.00	
0.89	1.00	0.89	1.00	0.89	1.00	0.89	1.00	0.89	1.00	
0.88	1.00	0.88	1.00	0.88	1.00	0.89	1.00	0.88	1.00	
0.74	0.94	0.74	0.94	0.86	1.00	0.89	1.00	0.87	1.00	
0.70	0.90	0.70	0.90	0.72	0.92	0.88	1.00	0.85	1.00	
		0.81	1.00	0.63	0.83	0.87	1.00	0.82	1.00	
		0.89	1.00	0.71	0.91	0.86	1.00	0.77	0.97	
				0.85	1.00	0.84	1.00	0.29	0.49	
				0.90	1.00	0.81	1.00	0.00	0.35	
						0.77	0.97	0.04	0.44	
						0.56	0.76	0.52	0.72	
						0.34	0.54	0.84	1.00	
						0.10	0.50			
						0.08	0.48			
						0.27	0.47			
						0.44	0.64			
						0.65	0.85			
						0.81	1.00			
						0.89	1.00			

2132.	2132.5 MHz) MHz	3600	MHz	4700 MHz		
Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	
0.89	1.00	0.89	1.00	0.89	1.00	0.89	1.00	
0.89	1.00	0.89	1.00	0.89	1.00	0.89	1.00	
0.88	1.00	0.89	1.00	0.89	1.00	0.89	1.00	
0.87	1.00	0.88	1.00	0.88	1.00	0.88	1.00	
0.85	1.00	0.87	1.00	0.88	1.00	0.88	1.00	
0.82	1.00	0.85	1.00	0.87	1.00	0.88	1.00	
0.77	0.97	0.82	1.00	0.87	1.00	0.87	1.00	
0.29	0.49	0.78	0.98	0.85	1.00	0.87	1.00	
0.00	0.35	0.73	0.93	0.83	1.00	0.86	1.00	
0.04	0.44	0.66	0.86	0.80	1.00	0.85	1.00	
0.52	0.72	0.00	0.39	0.76	0.96	0.83	1.00	
0.84	1.00	0.06	0.46	0.71	0.91	0.81	1.00	
0.90	1.00	0.27	0.47	0.65	0.85	0.77	0.97	
0.90	1.00	0.00	0.39	0.58	0.78	0.73	0.93	
0.90	1.00	0.09	0.49	0.49	0.69	0.68	0.88	
		0.64	0.84	0.39	0.59	0.62	0.82	
		0.87	1.00	0.03	0.43	0.54	0.74	
				0.52	0.72	0.46	0.66	
				0.75	0.95	0.37	0.57	
				0.83	1.00	0.27	0.47	
				0.82	1.00	0.07	0.47	
				0.69	0.89	0.00	0.38	
				0.32	0.52	0.41	0.61	
				0.00	0.35	0.73	0.93	
				0.50	0.70	0.85	1.00	
				0.80	1.00	0.79	0.99	
				0.90	1.00	0.70	0.90	
						0.68	0.88	
						0.78	0.98	
						0.88	1.00	
						0.81	1.00	
						0.43	0.63	
						0.00	0.29	

			0.40	0.60
			0.72	0.92
			0.87	1.00

Table C.4.4-2: Spatial correlation pass/fail limits for CDL-C UMa channel model

617	MHz	722	MHz	836.5	MHz	1575.4	2 MHz	1800	MHz
Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00
0.89	1.00	0.89	1.00	0.89	1.00	0.89	1.00	0.89	1.00
0.89	1.00	0.88	1.00	0.88	1.00	0.88	1.00	0.86	1.00
0.88	1.00	0.87	1.00	0.87	1.00	0.86	1.00	0.83	1.00
0.86	1.00	0.86	1.00	0.86	1.00	0.84	1.00	0.80	1.00
0.51	0.71	0.84	1.00	0.85	1.00	0.82	1.00	0.79	0.99
0.37	0.57	0.48	0.68	0.82	1.00	0.81	1.00	0.78	0.98
0.75	0.95	0.20	0.40	0.46	0.66	0.80	1.00	0.77	0.97
		0.46	0.66	0.09	0.29	0.79	0.99	0.74	0.94
		0.85	1.00	0.17	0.37	0.78	0.98	0.69	0.89
				0.60	0.80	0.77	0.97	0.00	0.36
				0.89	1.00	0.74	0.94	0.10	0.50
						0.69	0.89	0.02	0.42
						0.32	0.52	0.26	0.46
						0.00	0.33	0.47	0.67
						0.10	0.50		
						0.11	0.51		
						0.09	0.49		
						0.13	0.53		
						0.09	0.49		
						0.38	0.58		
						0.78	0.98		

2132.5 MHz		2450 MHz		3600 MHz		4700 MHz	
Lower	Upper	Lower	Upper	Lower	Upper	Lower	Upper
0.90	1.00	0.90	1.00	0.90	1.00	0.90	1.00
0.89	1.00	0.89	1.00	0.88	1.00	0.88	1.00
0.86	1.00	0.85	1.00	0.85	1.00	0.84	1.00
0.83	1.00	0.81	1.00	0.80	1.00	0.79	0.99
0.80	1.00	0.77	0.97	0.74	0.94	0.73	0.93
0.79	0.99	0.75	0.95	0.70	0.90	0.68	0.88
0.78	0.98	0.73	0.93	0.67	0.87	0.63	0.83
0.77	0.97	0.72	0.92	0.65	0.85	0.60	0.80
0.74	0.94	0.72	0.92	0.63	0.83	0.58	0.78
0.69	0.89	0.70	0.90	0.62	0.82	0.56	0.76
0.00	0.36	0.67	0.87	0.61	0.81	0.55	0.75
0.10	0.50	0.63	0.83	0.60	0.80	0.54	0.74
0.02	0.42	0.56	0.76	0.59	0.79	0.53	0.73
0.26	0.46	0.06	0.46	0.57	0.77	0.52	0.72
0.47	0.67	0.03	0.43	0.44	0.84	0.51	0.71
0.90	1.00	0.00	0.39	0.41	0.81	0.50	0.70
0.89	1.00	0.00	0.33	0.36	0.76	0.49	0.69
0.86	1.00	0.00	0.35	0.29	0.69	0.47	0.67
		0.28	0.48	0.21	0.61	0.45	0.65
		0.64	0.84	0.22	0.62	0.42	0.62
				0.00	0.49	0.38	0.58
				0.44	0.84	0.32	0.52
				0.27	0.67	0.15	0.55
				0.24	0.64	0.06	0.46
				0.08	0.58	0.00	0.38

	0.00	0.46	0.49	0.69
	0.00	0.46	0.06	0.46
	0.21	0.61	0.69	0.89
	0.20	0.60	0.33	0.53
	0.85	1.00	0.58	0.78
			0.53	0.73
			0.65	0.85
			0.77	0.97
			0.57	0.77
			0.00	0.29
			0.05	0.45
			0.12	0.52
			0.32	0.52
			0.63	0.83

C.4.5 Pass/Fail Criteria of Cross-polarization

This clause defines the pass/fail criteria of cross-polarization, this pass/fail limits apply for all channel models in all FR1 frequency bands, for both combined and individual beams.

The cross-polarization ratio pass/fail limit is specified as $\pm 1 dB$.

C.4.6 Pass/Fail Criteria of Power validation

This clause defines the pass/fail criteria of power validation, this pass/fail limits apply for all channel models.

The power validation pass/fail limit is specified as [TBD].

Annex D (normative): <FR2 Channel models and Validation procedure >

D.1 FR2 Channel models

The following channel model is required for FR2 MIMO OTA measurement.

The generic model is Table D.1-1 FR2 UMi CDL-C, which does not include base station antenna filtering. Therefore, in addition, the BS beam filtering effect defined in Annex D.2 also apply when emulating the channel models.

Absolute Power in Cluster # AOD in [°] AOA in [°] ZOD in [°] ZOA in [°] Delay [ns] [dB] -4.4215 -134.4434 98.9242 1 0 -30.4353 83.3318 2 12.594 -1.25 -20.9269 129.1633 99.1915 72.5229 3 13.314 -3.4684 -20.9269 129.1633 99.1915 72.5229 4 13.974 -5.2294-20.9269 129.1633 99.1915 72.5229 5 -2.5215 -28.0782 -152.8206 13.056 99.5732 71.1282 6 38.196 0 -11.6982 164.1145 99.306 74.7544 7 38.688 -2.2185-11.6982 164.1145 99.306 74.7544 8 -3.9794 74.7544 39.36 -11.6982 164.1145 99.306 9 39.504 -7.4215 17.3861 84.3647 100.4513 69.2454 10 47.61 -7.1215 -37.5865 92.0623 98.5616 66.7349 11 49.278 -10.7215 20.2226 -97.7585 100.6231 72.0348 12 56.016 -11.1215 -50.6106 78.4702 98.218 64.4337 13 73.71 -5.1215 -33.911 93.1719 100.165 85.4238 14 78.498 -37.5066 -112.0441 100.2604 -6.8215 64.1548 15 130.224 -8.7215 -43.1797 102.4645 98.1225 64.7824 16 162.63 -13.2215 29.2116 67.2359 100.2604 92.467 17 255.534 -13.921527.8133 34.5731 98.4852 65.6889 18 276.018 -13.9215 23.6584 48.5813 98.1416 68.7572 19 329.412 -15.8215 -52.5282 36.4455 97.9698 59.1339 20 336.462 -17.1215 25.0168 52.6729 100.7376 65.3402 21 378.39 -16.0215 25.4562 49.8296 98.1225 58.4365 22 398.244 -15.7215 30.7697 46.4316 98.1034 65.2705 23 422.562 -21.6215 35.9234 30.759 100.4513 62.6903 -22.8215 24 519.138 -61.2775 69.2469 100.9476 61.993 **Per-Cluster Parameters** Parameter CASD in [°] CASA in [°] CZSD in [°] CZSA in [°] XPR in [dB] Value 0.799 10.4021 0.5726 4.8814 7

Table D.1-1: Channel model parameters for UMi CDL-C at 28 GHz

D.2 FR2 Base Station beam configuration

The emulated BS beam configuration to be used for emulation of channel model defined in Annex D.1 is specified in this clause.

The Base Station beam configuration includes basic antenna parameters and beamforming characteristic. The basic BS antenna parameters is defined in Table D.2-1.

Table D.2-1: FR2 BS Antenna Parameters

Doromotor description	Symbol	Parameter value
Parameter description	Symbol	FR2
Antenna panels in vertical dimension	M_g	1
Antenna panels in horizontal dimension	N_g	1
Elements per panel in vertical dimension	Me	8
Elements per panel in horizontal dimension	Ne	16
Number of polarizations per panel	Р	2
Element spacing in horizontal dimension (λ)	dн	0.5
Element spacing in vertical dimension (λ)	d∨	0.5

Antenna element radiation patterns, including orientation of the element main polarization components as well as orientation of the antenna array are as in the example pattern in Table 7.3-1 of TR 38.901. The antenna element has $\pm 45^{\circ}$ polarization components and the radiation pattern parameters are $\theta_{3dB} = 65^{\circ}$, $\phi_{3dB} = 65^{\circ}$, $A_{max} = 30$ dB, $A_{max} = 30$ dB, $A_{max} = 30$ dB.

The beamforming characteristic of the FR2 BS pattern is defined as follow:

- A code book of 128 fixed beams is constructed to a grid of eight elevation angles from -25° to +25° with ~7.1° step size and 16° azimuth angles from -60° to +60° with 8° step size;
- 1 strongest transmitting beam is generated from BS, the direction of this beam towards the strongest cluster of the FR2 channel model. Specifically, the direction in UMi CDL-C model is: AoD: -12°, ZoD: 100.71°

D.3 FR2 Channel model validation

D.3.1 General

This clause describes the FR2 MIMO OTA validation measurements, in order to ensure that the channel models are correctly implemented and hence capable of generating the propagation environment, as described by the model, within the test zone of the 3D-MPAC system.

The following measurements shall be done for FR2 channel model validation:

Power Delay Profile (PDP)

Doppler/Temporal correlation

PAS similarity percentage (PSP)

Cross-polarization

Power validation

Frequencies to be used to test for FR2 channel model validation:

Table D.3.1-1: FR2 Channel model validation frequencies

NR FR2 Bands	Range	Test Frequency (MHz)
n257	Low	27750
n260	High	38500
n258	Low	25875
n261	Low	27925

D.3.2 FR2 Power Delay Profile (PDP)

This measurement checks that the resulting power delay profile (PDP) is in-line with the PDP defined for the channel model. For PDP validation measurement, only Vertical validation is required.

The PDP measurement is performed with a Vector Network Analyser (VNA). An example setup for PDP measurement is shown in Figure D.3.2-1. VNA transmits frequency sweep signals thorough the NR MIMO OTA test system. A reference antenna, within the centre of the test zone, receives the signal and VNA analyses the frequency response of the system. A number of traces (frequency responses) are measured and recorded by VNA and analysed by a post processing SW, e.g., Matlab. Special care has to be taken into account to keep the fading conditions unchanged, i.e. frozen, during the short period of time of a single trace measurement. The fading may proceed only in between traces.

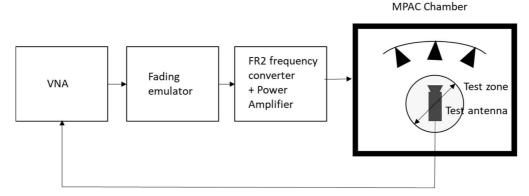


Figure D.3.2-1: Setup for PDP measurements (FR2)

Step the emulation and store traces from VNA. I.e. run the emulation to CIR number 1, pause, measure VNA trace, run the emulation to CIR number 10, pause, measure VNA trace. Continue until 1000 VNA traces are measured.

VNA settings:

Table D.3.2-1: VNA settings for FR2 PDP measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1
Span	MHz	200
Number of traces		1000
Number of points		1101
Averaging		1

Channel model specification:

Table D.3.2-2: Channel model specification for FR2 PDP measurements

Item	Unit	Value			
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1			
Distance between traces in channel model	wavelength (Note)	> 2			
Channel model		As specified in Annex D.1			
NOTE: Time [s] = distance $[\lambda]$ / MS speed $[\lambda/s]$ MS speed $[\lambda/s]$ = MS speed $[m/s]$ / Speed of light $[m/s]$ * Centre frequency $[Hz]$					

Method of measurement result analysis:

Measured VNA traces (frequency responses H(t,f)) are saved into a hard drive. The data is read into, e.g., Matlab. The analysis is performed by taking the Fourier transform of each trace. The resulting impulse responses $h(t,\tau)$ are averaged in power over time:

$$P(\tau) = \frac{1}{T} \sum_{t=1}^{T} \left| h(t, \tau) \right|^2$$

Finally, the resulting PDP is shifted in delay, such that the first tap is on delay zero.

The detailed PDP reference value for FR2 CDL-C UMi validation are defined in the following table:

Table D.3.2-3: PDP Targets for FR2 CDL-C UMi

Combined Clusters index	Delay(ns)	Power(dB)
1-5	15	-17.9
6-11	40	0.0
13-14	75	-31.2

D.3.3 FR2 Doppler/Temporal correlation

This measurement checks the Doppler/temporal correlation. For Doppler/Temporal correlation validation measurement, only Vertical validation is required.

The Doppler spectrum is measured with a spectrum analyser as shown in Figure D.3.3-1. In this case a signal generator transmits CW signal through the NR MIMO OTA test system. The signal is received by a test antenna within the test area. Finally, the signal is analysed by a spectrum analyser and the measured spectrum is compared to the target spectrum. This setup can be used to measure Doppler Spectrum of the Channel models defined in Annex D.2.

Method of measurement:

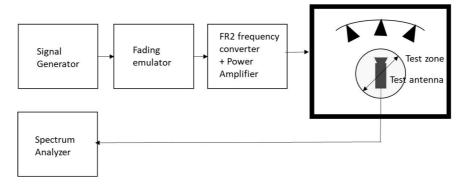


Figure D.3.3-1: Setup for FR2 Doppler measurements

Sine wave (CW, carrier wave) signal is transmitted from the signal generator. The signal is connected from the signal generator to fading emulator via cables. The fading emulator output signals are connected to frequency converter and power amplifier boxes via cables. The amplified signals are then transferred via cables to the probe antennas. The probe antennas radiate the signals over the air to the test antenna The Doppler spectrum is measured by the spectrum analyser and the trace is saved.

Signal generator settings:

Table D.3.3-1: Signal generator settings for FR2 Doppler/Temporal correlation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1
Modulation		OFF

Spectrum analyser settings:

Table D.3.3-2: Spectrum analyser settings for FR2 Doppler/Temporal correlation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1
Minimum Span	Hz	4 kHz
RBW	Hz	1
VBW	Hz	1
Number of points		16002
Averaging		100

Channel model specification:

Table D.3.3-3: Channel model specification for FR2 Doppler/Temporal correlation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1
Channel model		As specified in Annex D.1
Mobile speed	km/h	3

Method of measurement result analysis: Measurement data file (Doppler power spectrum) is saved into hard drive. The data is read into, e.g., Matlab. The analysis is performed by taking the Fourier transformation of the Doppler spectrum.

The resulting temporal correlation function $R_t(\Delta t)$ is normalized such that $\max(abs(R_t(\Delta t)))=1$. Then the function values left from the maximum is cut out. Further on the function values after, e.g. seven periods is cut out.

The detailed Temporal correlation reference value for FR2 CDL-C UMi channel model validation is defined is table D.3.3-4.

Table D.3.3-4: Temporal correlation Targets

Distance [λ]	X2V Corr.	Distance [λ]	X2V Corr.
0	1.0000	2.5	0.1769
0.1	0.9929	2.6	0.1717
0.2	0.9717	2.7	0.1649
0.3	0.9379	2.8	0.1564
0.4	0.8937	2.9	0.1456
0.5	0.8414	3	0.1327
0.6	0.7834	3.1	0.1177
0.7	0.7223	3.2	0.1011
0.8	0.6601	3.3	0.0829
0.9	0.5986	3.4	0.0638
1	0.5387	3.5	0.0449
1.1	0.4817	3.6	0.0272
1.2	0.4284	3.7	0.0121
1.3	0.3796	3.8	0.0023
1.4	0.3362	3.9	0.0079
1.5	0.2984	4	0.0104
1.6	0.2667	4.1	0.0083
1.7	0.2416	4.2	0.0026
1.8	0.2221	4.3	0.0095
1.9	0.2081	4.4	0.0235
2	0.1987	4.5	0.0397
2.1	0.1921	4.6	0.0572
2.2	0.1879	4.7	0.0738
2.3	0.1844	4.8	0.0890
2.4	0.1812	4.9	0.1018
		5	0.1109

D.3.4 FR2 PAS similarity percentage (PSP)

The PSP validation measurements aim at evaluating PAS similarity percentage (PSP), which is one of the validation metrics for characterizing FR2 channel model under test in the quite zone of 3D-MPAC. For PSP validation measurement, only vertical polarization validation is required.

The measurement array is essentially a virtual array configuration realized in 3D-MPAC through a ϕ - θ positioning system. The measurement array is a semi-circle and sectored array configuration illustrated in Figure D.3.4-1 where complex channel frequency response is measured at each antenna location $0.5~\lambda$ apart using a vector network analyser (VNA) setup. The vertical sectors of the measurement array are limited to 60° ($\pm 30^\circ$) and the horizontal sector to 180° ($\pm 90^\circ$) with the broad side direction points towards the probes. Depending of the turntable architecture/implementation, the virtual array configuration for the PSP validation is composed of two alternative semi-circle arrangements (1 x horizontal and either 2 x crossed vertical or 2 x parallel vertical). The radius of the array element locations with respect to the centre of the test zone is 5 cm, which is equivalent to the half of the test zone radius at 28 GHz. For different frequency bands, the radius of the measurement array sectored semi-circles remains fixed at 5 cm while the spatial sampling of the array varies. This measurement validates the proper angular behaviour in the test zone.

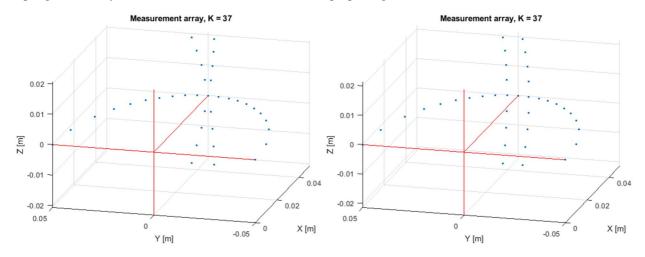


Figure D.3.4-1: Semi-circle measurement array configurations with K = 37 elements (at 28 GHz). On the left with two crossed vertical sectors, on the right with two parallel vertical sectors.

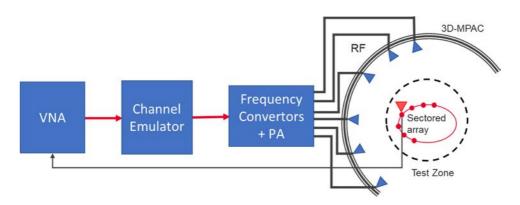


Figure D.3.4-2: Setup for FR2 PSP validation measurements

The PSP validation is measured with a vector network analyser as shown in Figure D.3.4-2 illustrating the PSP measurement setup. Port 1 of the VNA transmits signals through the fading emulator and radiate them through L probes within the anechoic chamber. The radiated signals are then received at the test antenna that is positioned inside the test zone. The test antenna is mounted on a ϕ - θ positioner which is capable of moving the antenna to pre-defined spatial locations on a fixed radius from the centre of the quiet zone according the measurement array configuration. Finally, the signal is received at port 2 of the VNA. The most suitable approach for the PSP validation is based on an

omnidirectional antenna (omnidirectional pattern in AZ and wide BW in EL) as the test can be automated easily. Alternatively, a directional antenna could be used but requires frequent re-positioning.

The measurement and analysis procedure are given as follows:

- 1. Set the target channel model in the Channel Emulator.
- 2. For each position of the test antenna on the measurement array configuration in the test zone, step & pause the emulator to different time instances. Measure the complex frequency responses $H(f,t) = H(m\Delta f, n\Delta T), m = 0, ..., M-1$ for all stepped channel snapshots n = 0, ..., N-1, where the interval between frequency and time samples is Δf and ΔT , respectively. The number of channel snapshots N and frequency samples M.
- 3. Move the measurement antenna with a positioner to another location k and repeat step 2 to record frequency responses $H_k(m\Delta f, n\Delta T)$ of all stepped channel snapshots.
- 4. Repeat step 3 to record frequency responses at all k = 0, ..., K spatial sample points.
- 5. Estimate the measured PAS through the following two- stage processing:
 - a. In the first stage, calculate the discrete azimuth and elevation angles (DoA) for the measurement array configuration by applying the MUSIC algorithm. Estimate the powers from the DoA and auto-covariance matrix of the received signal acquired through VNA complex frequency response data.
 - i) Compose an estimate of the covariance matrix $\mathbf{R}_H \in C^{K \times K}$. The entry on the kth row and k'th column of \mathbf{R}_H is

$$R_H(k,k') = \sum_{n=1}^{N} \sum_{m=1}^{M} H_k(m\Delta f, n\Delta T) \overline{H_{k'}}(m\Delta f, n\Delta T),$$

where () is the complex conjugate operator.

ii) Compose pseudo-PAS of the chamber environment and channel model using the MUSIC algorithm. The intention of this step is to estimate DoAs of signals radiated by probes. Perform first the eigen decomposition of \mathbf{R}_H and pick the noise-subspace matrix \mathbf{V} . The matrix \mathbf{V} is obtained from the eigen decomposition by removing eigenvectors, i.e. columns, that correspond to X strongest eigenvalues, where X is the number of active probes in the MPAC setup. The pseudo-PAS is [9]

$$P_{\text{MUSIC}}(\beta) = \frac{1}{\mathbf{\omega}(\beta) \, \mathbf{V} \mathbf{V}^H \, \mathbf{\omega}^H(\beta)},$$

where $()^H$ is the matrix Hermitean operator and the near-field array factor of the virtual array composed by K spatial measurement antenna locations is

$$\omega(\beta) = \frac{\lambda_0}{4\pi \|\vec{r}_k - R \vec{u}(\beta)\|} \exp\left(\frac{j2\pi \|\vec{r}_k - R \vec{u}(\beta)\|}{\lambda_0}\right),$$

where λ_0 is the wavelength at the carrier centre frequency, $\| \|$ is the norm of a vector, \vec{r}_k is a location vector of the kth virtual array element, $\vec{u}(\beta)$ is the unit vector to direction β , and R is the a priori known approximate range length [9]. Both vectors \vec{r}_k and $\vec{u}(\beta)$ are defined with respect to same origin, which is the centre of the test zone.

- iii) Find local maxima of $P_{\text{MUSIC}}(\beta)$ and pick directions β_x , x = 1, ..., X of the X highest peaks.
- iv) Perform Bartlett beamforming as defined in step 6 with the steering vector $\boldsymbol{\omega}(\beta_x)$ (instead of $a(\beta)$) to the *X* directions identified in iii). The output is *X* power estimates $P_{\text{est}}(\beta_x)$.
- b. In the second stage, use the angle and power estimates, i.e. the discrete PAS of *X* azimuth and elevation directions and power values in conjunction with a 4x4 DUT sampling array for beamforming with the conventional Bartlett beamformer to estimate the "measured PAS seen by DUT" for PSP calculation. This is

$$\hat{P}_o(\beta) = a^H(\beta) \left(\sum_{x=1}^X a(\beta_x) P_{\text{est}}(\beta_x) a^H(\beta_x) \right) a(\beta),$$

where $a(\beta)$ is the array steering vector of the 4x4 DUT array.

6. Evaluate the reference OTA PAS for the 4x4 DUT array by applying the conventional Bartlett beamformer. The theoretical PAS as reference is calculated for the ideal channel model as

$$\hat{P}_r(\beta) = a^H(\beta) \oint a(\beta) P(\beta) a^H(\beta) d\beta a(\beta),$$

where $a(\beta)$ is the array steering vector of the 4x4 DUT array and $P(\beta)$ is the PAS of the reference channel model.

7. Calculate total variation distance (D_p) from the reference and measured PAS. Mathematically,

$$D_{p} = \frac{1}{2} \int \left| \frac{\hat{P}_{r}(\beta)}{\int \hat{P}_{r}(\beta')d\beta'} - \frac{\hat{P}_{o}(\beta)}{\int \hat{P}_{o}(\beta')d\beta'} \right| d\beta$$

8. Calculate PSP values as PSP = $(1-D_p)$ x 100%.

VNA settings:

Table D.3.4-1: VNA settings for FR2 PSP measurements

Item	Unit	Value		
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1		
Span	MHz	0, or the minimum (Note 1)		
Number of traces		1000		
Number of points		1 (Note 1)		
NOTE 1: Span and number of points may be increased to estimate reliably.				

Channel model specification:

Table D.3.4-2: Channel model specification for FR2 PSP measurements

Item	Unit	Value			
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1			
Distance between traces in channel model	wavelength (Note)	> 2			
Channel model		As specified in Annex D.1			
NOTE: Time [s] = distance $[\lambda]$ / MS speed $[\lambda/s]$					
MS speed $[\lambda/s]$ = MS speed $[m/s]$ /	MS speed $[\lambda/s] = MS$ speed $[m/s] / Speed$ of light $[m/s] * Centre$ frequency $[Hz]$				

Time Domain Alternative Method:

PSP validation can also be implemented using time-domain techniques using the testing setup presented in Figure D.3.4-3. The VNA is substituted by a signal generator, and a signal analyser.

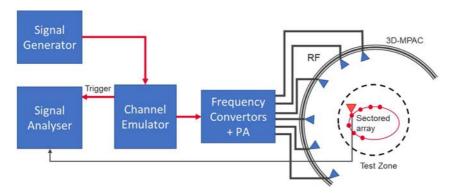


Figure D.3.4-3: Setup for FR2 PSP validation measurements based on time domain

Table D.3.4-3: Signal Generator Settings for FR2 PSP measurements based on time domain

Item	Unit	Value	
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1	
Output power	dBm	Function of the CE. Sufficiently above Noise Floor	

Table D.3.4-4: Signal Analyser Settings for FR2 PSP measurements based on time domain

Item	Unit	Value		
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1		
Sampling	Hz	At least 10 times bigger than the max Doppler spread (f _d =v/		
Observation time	S	At least 32s		

The measurement and analysis procedure are given as follows:

Follow the same procedure as before, but M is set to 1. The Channel Emulator is not stepped, but it is allowed to play in free run mode for each of the K spatial points.

D.3.5 FR2 Cross-polarization

This measurement checks how well the measured vertically or horizontally polarized power levels follow expected values. The test setup for cross-polarization is the same as PDP validation in Figure D.3.2-1.

Method of measurement: Step the emulation and store traces from VNA.

VNA settings:

Table D.3.5-1: VNA settings for FR2 cross-polarization

Item	Unit	Value
Centre frequency	MHz	Downlink Centre Frequency in Table D.3.1-1
Span	MHz	40
Number of traces		1000
Number of points		802
Averaging		1

Channel model specification:

As specified in Annex D.1

30

 Item
 Unit
 Value

 Centre frequency
 MHz
 Downlink centre frequency in Table D.3.1-1

 Distance between traces in channel model
 wavelength (Note)
 > 2

km/h

Table D.3.5-2: Channel model specification for FR2 cross-polarization.

NOTE: Time [s] = distance $[\lambda]$ / MS speed $[\lambda/s]$ MS speed $[\lambda/s]$ = MS speed [m/s] / Speed of light [m/s] * Centre frequency [Hz]

Measurement Procedure:

1. Play or step through the channel model listed in Annex D.1.

Channel model

Mobile speed

- 2. Measure the absolute power received at the centre of the test zone, averaged over a statistically significant number of fades.
 - a. Use a horn antenna with H polarization terminated to measure the V component.
 - b. Use a horn antenna with V polarization terminated for the horizontal polarization, in four orthogonal horizontal positions and summed to measure the H component.
- 3. Calculate the V/H ratio.
- 4. Compare it with the theory value.

Reference target for FR2 CDL-C UMi:

- V/H FR2 CDL-C-UMi, X2+, fc=28 GHz
 - Beam 1, Input 1: V/H = -0.45 dB
 - Beam 1, Input 2: V/H = 0.49 dB
 - Beam 1, Input 1+2: V/H = 0 dB

D.3.6 FR2 Power validation

This measurement checks the total power in the centre of the test zone. The power validation is measured with a spectrum analyser as shown in Figure D.3.6-1.

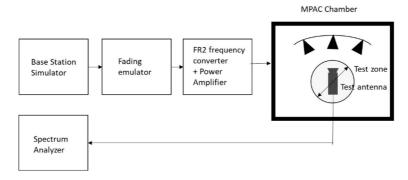


Figure D.3.6-1: Setup for FR2 power validation measurements

Spectrum analyser settings:

Table D.3.6-1: Spectrum analyser settings for FR2 power validation measurements

Item	Unit	Value
Centre frequency	MHz	Downlink centre frequency in Table D.3.1-1
Integrated Channel Span	Hz	20MHz
RBW	Hz	30 kHz
VBW	Hz	≥10MHz
Number of points		≥400
Averaging		≥100
Detector		RMS

Measurement Procedure:

- 1. Place a horn antenna with H polarization terminated in the centre of the test zone connected to a spectrum analyser (or power meter) via a cable.
- 2. Record the cable and horn antenna gains.
- 3. Load the target channel model into the channel emulator.
- 4. Start the NR FR2 signalling in the base station emulator with the required parameter identical to the measurements conditions.
- 5. Average the power received by the spectrum analyser for a sufficient amount of time to account for the fading channel one full channel simulation might be unnecessary.
- 6. Repeat steps 1 to 4 with a horn antenna V polarization terminated for the horizontal polarization, in four orthogonal horizontal positions and summed to measure the H component.
- 7. Calculate the total power received at the test area as the sum of the power in the two polarizations.

D.4 Validation Pass/fail limit

D.4.1 General

This clause defines the pass/fail limit of FR2 3D-MPAC system for FR2 channel model validation.

D.4.2 Pass/Fail Criteria of PDP

This clause defines the pass/fail criteria of PDP, this pass/fail limits apply for all FR2 frequency bands.

The detailed pass/fail limits for each cluster of FR2 CDL-C UMi are defined in Table D.4.2-1.

Table D.4.2-1: PDP pass/fail limits for FR2 CDL-C UMi channel model validation

	Power Tolerance	Delay Tolerance
Paths from 0dB to 10dB	±1dB	±6ns
Paths from 10dB to 30dB	±5dB	±6ns
Paths from 30dB to 40dB	±10dB	±6ns

D.4.3 Pass/Fail Criteria of Doppler/Temporal correlation

This clause defines the pass/fail criteria of doppler/temporal correlation validation, this pass/fail limits apply for all FR2 frequency bands.

The pass/fail limits for theoretical temporal correlation defined in Clause D.3.3 above 0.3 are formed as bands of ± 0.1 of correlation capped at 1 at the high end. Additionally, when the theoretical temporal correlation drops below 0.3, the limits are formed at bands of ± 0.3 of correlation capped at 0 at the low end.

Dietanes ()1	X2V	Corr.	Dictores (1)	X2V	Corr.
Distance [λ]	Lower	Upper	Distance [λ]	Lower	Upper
0	0.9000	1.0000	2.5	0.0000	0.3000
0.1	0.8929	1.0000	2.6	0.0000	0.3000
0.2	0.8717	1.0000	2.7	0.0000	0.3000
0.3	0.8379	1.0000	2.8	0.0000	0.3000
0.4	0.7937	0.9937	2.9	0.0000	0.3000
0.5	0.7414	0.9414	3	0.0000	0.3000
0.6	0.6834	0.8834	3.1	0.0000	0.3000
0.7	0.6223	0.8223	3.2	0.0000	0.3000
0.8	0.5601	0.7601	3.3	0.0000	0.3000
0.9	0.4986	0.6986	3.4	0.0000	0.3000
1	0.4387	0.6387	3.5	0.0000	0.3000
1.1	0.3817	0.5817	3.6	0.0000	0.3000
1.2	0.3284	0.5284	3.7	0.0000	0.3000
1.3	0.2796	0.4796	3.8	0.0000	0.3000
1.4	0.2362	0.4362	3.9	0.0000	0.3000
1.5	0.1984	0.3984	4	0.0000	0.3000
1.6	0.1667	0.3667	4.1	0.0000	0.3000
1.7	0.1416	0.3416	4.2	0.0000	0.3000
1.8	0.1221	0.3221	4.3	0.0000	0.3000
1.9	0.1081	0.3081	4.4	0.0000	0.3000
2	0.0000	0.3000	4.5	0.0000	0.3000
2.1	0.0000	0.3000	4.6	0.0000	0.3000
2.2	0.0000	0.3000	4.7	0.0000	0.3000
2.3	0.0000	0.3000	4.8	0.0000	0.3000
2.4	0.0000	0.3000	4.9	0.0000	0.3000
			5	0.0000	0.3000

Table D.4.3-1: pass/fail limits for temporal correlation

Based on the value defined in Table D.4.3-1, Figure D.4.3-1 shows the pass/fail and reference curve of temporal correlation.

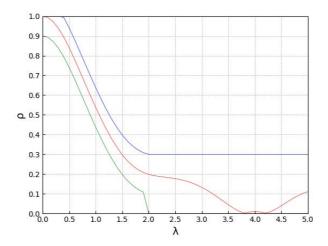


Figure D.4.3-1: Pass/fail limits and targets of Temporal correlation for CDL-C UMi channel model: red curve (reference), blue (upper limit) and green (lower limit)

D.4.4 Pass/Fail Criteria of PSP

This clause defines the pass/fail criteria of PSP, this general pass/fail limits principle apply for all FR2 frequency bands.

The PSP pass/fail limit is specified as [84%].

D.4.5 Pass/Fail Criteria of Cross-polarization

This clause defines the pass/fail criteria of cross-polarization, this pass/fail limits apply for all FR2 frequency bands.

The cross-polarization ratio pass/fail limit is specified as ± 1.5 dB.

D.4.6 Pass/Fail Criteria of Power validation

This clause defines the pass/fail criteria of power validation, this pass/fail limits apply for all FR2 bands.

The power validation pass/fail limit is specified as [TBD].

Annex E (normative): <gNB configurations>

E.1 FR1 gNB configurations

The gNodeB emulator parameters shall be set according to Table E.1-1 for FR1 common parameters, Table E.1-2 for FR1 FDD 2x2 test parameters, Table E.1-3 for FR1 TDD 2x2 test parameters, Table E.1-4 for FR1 FDD 4x4 test parameters, and Table E.1-5 for FR1 TDD 4x4 test parameters.

Table E.1-1: FR1 Common test parameters

	Parameter	Unit	Value
PDSCH transmission	scheme		Transmission scheme 1
Carrier	Offset between Point A and the lowest usable subcarrier on this carrier (Note 2)	RBs	0
configuration	Subcarrier spacing	kHz	15 or 30
	Cyclic prefix		Normal
	RB offset	RBs	0
DL BWP configuration #1	Number of contiguous PRB	PRBs	Maximum transmission bandwidth configuration as specified in clause 5.3.2 of TS 38.101-1 for tested channel bandwidth and subcarrier spacing
	Physical Cell ID		0
Common serving	SSB position in burst		First SSB in Slot #0
cell parameters	SSB periodicity	ms	20
Celi parameters	First DMRS position for Type A PDSCH		2
	mapping		2
	Slots for PDCCH monitoring		Each slot
	Symbols with PDCCH	Symbols	0, 1
PDCCH	Number of PRBs in CORESET		Table 5.2-2 of TS 38.101-4 for tested channel bandwidth and subcarrier spacing
configuration	Number of PDCCH candidates and aggregation levels		1/AL8
	CCE-to-REG mapping type		Non-interleaved
	DCI format		1 1
	TCI state		TCI state #1
Cross carrier schedu			Not configured
	First subcarrier index in the PRB used for CSI-RS		k ₀ =0 for CSI-RS resource 1,2,3,4
	First OFDM symbol in the PRB used for CSI-RS		l_0 = 6 for CSI-RS resource 1 and 3 l_0 = 10 for CSI-RS resource 2 and 4
	Number of CSI-RS ports (X)		1 for CSI-RS resource 1,2,3,4
	CDM Type		'No CDM' for CSI-RS resource 1,2,3,4
	Density (ρ)		3 for CSI-RS resource 1,2,3,4
CSI-RS for tracking	CSI-RS periodicity	Slots	15 kHz SCS: 20 for CSI-RS resource 1,2,3,4 30 kHz SCS: 40 for CSI-RS resource 1,2,3,4
	CSI-RS offset	Slots	15 kHz SCS: 10 for CSI-RS resource 1 and 2 11 for CSI-RS resource 3 and 4 30 kHz SCS: 20 for CSI-RS resource 1 and 2 21 for CSI-RS resource 3 and 4
	Frequency Occupation		Start PRB 0 Number of PRB = BWP size
	QCL info		TCI state #0

	First subcarrier CSI-RS	index in the PRB used for		k ₀ = 0
		mbol in the PRB used for		l ₀ = 12
	CSI-RS			-
	Number of CSI-RS ports (X)			Same as number of transmit antenna
NZP CSI-RS for	CDM Type			'FD-CDM2'
CSI acquisition	Density (ρ)			1
Cor acquiomon	CSI-RS periodi	city	Slots	15 kHz SCS: 20
	·	on,		30 kHz SCS: 40
	CSI-RS offset		Slots	0 Start PRB 0
	Frequency Occ	cupation		Number of PRB = BWP size
	QCL info			TCI state #1
	First subcarrier CSI-RS	index in the PRB used for		k ₀ = 4
	First OFDM syr CSI-RS	mbol in the PRB used for		I ₀ = 12
	Number of CSI	-RS ports (X)		4
ZP CSI-RS for CSI	CDM Type			'FD-CDM2'
acquisition	Density (ρ)			1
	CSI-RS periodi	city	Slots	15 kHz SCS: 20
	Ī	City		30 kHz SCS: 40
	CSI-RS offset		Slots	0
	Frequency Occ	cupation		Start PRB 0
				Number of PRB = BWP size
PDSCH DMRS	Antenna ports i	indexes		{1000, 1001} for Rank 2 tests {1000-1003} for Rank 4 tests
configuration	Number of PDS	Number of PDSCH DMRS CDM group(s)		1 for Rank 2 tests
	without data	3 1 ()		2 for Rank 4 tests
	Type 1 QCL	SSB index		SSB #0
TCI state #0	information	QCL Type		Type C
TOI State #0	Type 2 QCL	SSB index		N/A
	information	QCL Type		N/A
	Type 1 QCL	CSI-RS resource		CSI-RS resource 1 from 'CSI-RS for tracking' configuration
TCI state #1	information	QCL Type		Type A
Torolato #1	Type 2 QCL	CSI-RS resource		N/A
	information	QCL Type		N/A
PT-RS configuration		1		PT-RS is not configured
	code block group	os for ACK/NACK feedback		1
Maximum number of				1
HARQ ACK/NACK b				Multiplexed
Redundancy version coding sequence				N.A
Precoding configuration				SP Type I, Random per slot with PRB bundling granularity
Symbols for all unus	Symbols for all unused REs			OCNG Annex A.5 of TS 38.101-4
				20000 for 15kHz SCS
Minimum Number of Slots per Stream				40000 for 30kHz SCS
				(Note 3)
Transmit Power Con	trol		dBm	13
DL power level			dBm /	Set at gNodeB simulator
(RS EPRE of SSS)			SCS	with correction from calibration
EPRE ratio of PDSCH to SSS			dB	0

Note 1: UE assumes that the TCI state for the PDSCH is identical to the TCI state applied for the PDCCH transmission.

Note 2: Point A coincides with minimum guard band as specified in Table 5.3.3-1 from TS 38.101-1 for tested channel bandwidth and subcarrier spacing.

Note 3: For FR1 MIMO OTA test lab alignments and FR1 MIMO OTA UE performance requirements, the following values can be used:

For FR1 bands >1GHz: 20k for 30kHz SCS, 10k for 15kHz SCS;

For FR1 bands <1GHz: [20k] for 15kHz SCS;

Table E.1-2: Test parameters for FR1 FDD 2x2

Parameter		Unit	Value
Duplex mode			FDD
Reference channel			R.PDSCH.1-3.1 FDD (Note 1)
Bandwidth			10
SCS		kHz	15
Modulation DL			64QAM
Modulation UL			QPSK
Active DL BWP index	(1
	Mapping type		Type A
	k0		0
	Starting symbol (S)		2
	Length (L)		12
	PDSCH aggregation factor		1
PDSCH	PRB bundling type		Static
configuration	PRB bundling size		2
	Resource allocation type		Type 0
	RBG size		Config2
	VRB-to-PRB mapping type		Non-interleaved
	VRB-to-PRB mapping interleaver bundle size		N/A
	DMRS Type		Type 1
PDSCH DMRS	Number of additional DMRS		1
configuration	Maximum number of OFDM symbols for		1
	DL front loaded DMRS		I
CSI-RS for tracking	CSI-RS periodicity	Slots	20
CSI-NS for tracking	CSI-RS offset	Slots	Table 8.2-1.
Number of HARQ Pro	Number of HARQ Processes		4
The number of slots between PDSCH and corresponding HARQ-ACK information			2
	-3.1 FDD" is defined in Table A.3.2.1.1-3 of T	S 38.101-4	

Table E.1-3: Test parameters for FR1 TDD 2x2

Parameter			Value
Duplex mode	uplex mode		TDD
Reference channel			R.PDSCH.2-3.1 TDD (Note 1)
Bandwidth		MHz	40
SCS		kHz	30
Modulation DL			64QAM
Modulation UL			QPSK
Active DL BWP index	(1
	Mapping type		Type A
	k0		0
	Starting symbol (S)		2
	Length (L)		Specific to each Reference channel
	PDSCH aggregation factor		1
PDSCH	PRB bundling type		Static
configuration	PRB bundling size		2
	Resource allocation type		Type 0
	RBG size		Config2
	VRB-to-PRB mapping type		Non-interleaved
	VRB-to-PRB mapping interleaver bundle size		N/A
	DMRS Type		Type 1
PDSCH DMRS	Number of additional DMRS		1
configuration	Maximum number of OFDM symbols for DL front loaded DMRS		1
CCI DC for tracking	First OFDM symbol in the PRB used for CSI-RS		Table 8.2-1.
CSI-RS for tracking	CSI-RS periodicity	Slots	40
CSI-RS offset		Slots	Table 8.2-1.
Number of HARQ Pro	umber of HARQ Processes 8		8

TDD UL-DL pattern		FR1.30-1 (Note 2)
Note 1: "R.PDSCH.2-3.1 TDD" is defined in Table A.3.2.2.2-3 of TS	38.101-4	
Note 2: "FR1.30-1" is defined in Annex A.1.2 of TS 38.101-4		

Table E.1-4: Test parameters for FR1 FDD 4x4

	Parameter	Unit	Value
Duplex mode			FDD
Reference channel			R.PDSCH.1-2.4 FDD (Note 1)
Bandwidth		MHz	10
SCS		kHz	15
Modulation DL			16QAM
Modulation UL			QPSK
Active DL BWP index			1
	Mapping type		Туре А
	k0		0
	Starting symbol (S)		2
	Length (L)		12
	PDSCH aggregation factor		1
PDSCH	PRB bundling type		Static
configuration	PRB bundling size		2
	Resource allocation type		Type 0
	RBG size		Config2
	VRB-to-PRB mapping type		Non-interleaved
	VRB-to-PRB mapping interleaver bundle size		N/A
	DMRS Type		Type 1
PDSCH DMRS	Number of additional DMRS		1
configuration	Maximum number of OFDM symbols for DL front loaded DMRS		1
CCI DC for two obins	CSI-RS periodicity	Slots	20
CSI-RS for tracking	CSI-RS offset	Slots	Table 8.2-1.
Number of HARQ Pro	ocesses		4
The number of slots to ACK information	petween PDSCH and corresponding HARQ-		2
Note 1: "R.PDSCH.1-	-2.4 FDD" is defined in Table A.3.2.1.1-2 of T	S 38.101-4	

Table E.1-5: Test parameters for FR1 TDD 4x4

	Parameter	Unit	Value
Duplex mode			TDD
Reference channel			R.PDSCH.2-2.4 TDD (Note 1)
Bandwidth		MHz	40
SCS		kHz	30
Modulation DL			16QAM
Modulation UL			QPSK
Active DL BWP index	(1
	Mapping type		Type A
	k0		0
	Starting symbol (S)		2
	Length (L)		Specific to each Reference channel
	PDSCH aggregation factor		1
PDSCH	PRB bundling type		Static
configuration	PRB bundling size		2
	Resource allocation type		Type 0
	RBG size		Config2
	VRB-to-PRB mapping type		Non-interleaved
	VRB-to-PRB mapping interleaver bundle		N/A
	size		IN/A
	DMRS Type		Type 1
PDSCH DMRS	Number of additional DMRS		1
configuration	Maximum number of OFDM symbols for DL front loaded DMRS		1

	First OFDM symbol in the PRB used for CSI-RS		Table 8.2-1.			
CSI-RS for tracking	CSI-RS periodicity	Slots	40.			
	CSI-RS offset	Slots	Table 8.2-1.			
Number of HARQ Pro	ocesses		8			
TDD UL-DL pattern			FR1.30-1 (Note 2)			
Note 1: "R.PDSCH.2-2.4 TDD" is defined in Table A.3.2.2.2-2 of TS 38.101-4						
Note 2: "FR1.30-1" is defined in Annex A.1.2 of TS 38.101-4						

E.2 FR2 gNB configurations

The gNodeB emulator parameters for FR2 MIMO OTA testing shall be set according to Table E.2-1 for FR2 common parameters and Table E.2-2 for FR2 TDD 2x2 test parameters.

Table E.2-1: FR2 Common test parameters

	Parameter	Unit	Value
PDSCH transmis			Transmission scheme 1
PTRS epre-Ration			0
Actual carrier configuration	Offset between Point A and the lowest usable subcarrier on this carrier (Note 2)	RBs	0
	Subcarrier spacing	kHz	120
	Cyclic prefix		Normal
	RB offset	RBs	0
DL BWP configuration #1	Number of contiguous PRB	PRBs	Maximum transmission bandwidth configuration as specified in clause 5.3.2 of TS 38.101-2 for tested channel bandwidth and subcarrier spacing
	Physical Cell ID		0
Common	SSB position in burst		1
serving cell	SSB periodicity	ms	20
parameters	First DMRS position for Type A PDSCH mapping		2
	Slots for PDCCH monitoring		Each slot
	Symbols with PDCCH		0
PDCCH	Number of PRBs in CORESET		Table 7.2-2 of TS 38.101-4 for tested channel bandwidth and subcarrier spacing
configuration	Number of PDCCH candidates and aggregation levels		1/AL8
	CCE-to-REG mapping type		Non-interleaved
	DCI format		1_1
	TCI state		TCI state #1
Cross carrier sch			Not configured
	First subcarrier index in the PRB used for CSI-RS (<i>k</i> ₀)		0 for CSI-RS resource 1,2,3,4
	First OFDM symbol in the PRB used for CSI-RS (<i>lo</i>)		6 for CSI-RS resource 1 and 3 10 for CSI-RS resource 2 and 4
	Number of CSI-RS ports (X)		1 for CSI-RS resource 1,2,3,4
	CDM Type		'No CDM' for CSI-RS resource 1,2,3,4
CSI-RS for tracking	Density (ρ)		3 for CSI-RS resource 1,2,3,4
	CSI-RS periodicity	Slots	120 kHz SCS: 160 for CSI- RS resource 1,2,3,4
	CSI-RS offset	Slots	120 kHz SCS: 80 for CSI-RS resource 1 and 2 81 for CSI-RS resource 3 and 4
	Frequency Occupation		Start PRB 0 Number of PRB = BWP size
	QCL info		TCI state #0
	First subcarrier index in the PRB used for CSI-RS (<i>k</i> ₀)		0
	First OFDM symbol in the PRB used for CSI-RS (<i>I</i> ₀)		12
	Number of CSI-RS ports (X)		2
NZP CSI-RS	CDM Type		FD-CDM2
for CSI	Density (ρ)		1
acquisition	CSI-RS periodicity	Slots	120 kHz SCS: 160
	CSI-RS offset	SIULS	0
	Frequency Occupation		Start PRB 0 Number of PRB = BWP size
	QCL info		TCI state #1
ZP CSI-RS for CSI acquisition	First subcarrier index in the PRB used for CSI-RS (k ₀)		4

		symbol in the PRB		12
	used for CS			12
	Number of C	CSI-RS ports (X)		4
	CDM Type			FD-CDM2
	Density (ρ)			1
	CSI-RS peri	odicity	Slots	120 kHz SCS: 160
	CSI-RS offse		0.010	0
	Frequency C			Start PRB 0 Number of PRB = BWP size
	First subser	rier index in the PRB		Number of PRB = BVVP Size
	used for CS	I-RS		k ₀ =0 for CSI-RS resource 1,2
		symbol in the PRB		$l_0 = 8$ for CSI-RS resource 1
	used for CS			$I_0 = 9$ for CSI-RS resource 2
	Number of C	CSI-RS ports (X)		1 for CSI-RS resource 1,2
CSI-RS for	CDM Type			'No CDM' for CSI-RS
beam				resource 1,2
refinement	Density (ρ)			3 for CSI-RS resource 1,2
				60 kHz SCS: 80 for CSI-RS
	CSI-RS peri	odicity	Slots	resource 1,2
	our no pon	outony	0.010	120 kHz SCS: 160 for CSI-
				RS resource 1,2
	CSI-RS offse	et	Slots	0 for CSI-RS resource 1,2
	QCL info			TCI state #1
				(4000) for Donley 4 to the
PDSCH DMRS configuration	Antenna por	ts indexes		{1000} for Rank 1 tests {1000, 1001} for Rank 2 tests
Comigaration	Number of F	PDSCH DMRS CDM		_
	group(s) with	nout data		1
	Type 1	SSB index		SSB #0
	QCL			
	information	QCL Type		Type C
TCI state #0	Type 2	SSB index		SSB #0
	QCL	COB III dox		0020
	information	QCL Type		Type D
	Type 1			CSI-RS resource 1 from
	QCL	CSI-RS resource		'CSI-RS for tracking'
	information	00111010000100		configuration
	IIIIOIIIIatioii	QCL Type		Type A
TCI state #1	Tuno 2	QOL TYPE		CSI-RS resource 1 from
	Type 2	CCL DC resource		
	QCL	CSI-RS resource		'CSI-RS for tracking'
	information	OCL Turns		configuration
	 	QCL Type		Type D
PTRS		lensity (KPT-RS)		2
configuration	Time density			1
Maximum numb		ck groups for		1
ACK/NACK feed				'
Maximum numb		ansmission		1
HARQ ACK/NAC				Multiplexed
Redundancy ver	sion coding se	equence		{0,2,3,1}
				SP Type I, Random per slot
Precoding config	guration			with PRB bundling
	-			granularity
Symbols for all u	ınused Res			OCNG in Annex A.5 of TS 38.101-4
Minimum Numbe	er of Slots per	Stream		20000 for FR2 UMi CDL-C
Transmit Power			dBm	13 dBm

Note 1: UE assumes that the TCI state for the PDSCH is identical to the TCI state applied for the PDCCH transmission.

Note 2: Point A coincides with minimum guard band as specified in Table 5.3.3-1 from TS 38.101-2 for tested channel bandwidth and subcarrier spacing.

Table E.2-2: Test parameters for FR2 TDD 2x2

	Parameter	Unit	Value			
Duplex mode			TDD			
Reference channel			R.PDSCH.5-2.2 TDD			
Reference channel			(Note 1)			
Bandwidth		MHz	100			
SCS		kHz	120			
Modulation DL			16QAM			
Modulation UL			QPSK			
Active DL BWP index			1			
CSI-RS for tracking	First OFDM symbol in the PRB used for CSI-RS (<i>lo</i>)		Table E.2-1			
_	CSI-RS offset	Slots	Table E.2-1			
PDCCH configuration	Number of PDCCH candidates and aggregation levels		1/AL8			
	Mapping type		Type A			
	kO		0			
	Starting symbol (S)		1			
	Length (L)		Specific to each Reference channel as defined in A.3.2.2 of TS 38.101-4			
DDCCH configuration	PDSCH aggregation factor		1			
PDSCH configuration	PRB bundling type		Static			
	PRB bundling size		WB for Test 1-1, 2 for other tests			
	Resource allocation type		Type 0			
	RBG size		config2			
	VRB-to-PRB mapping type		Non-interleaved			
	VRB-to-PRB mapping interleaver bundle size		N/A			
	DMRS Type		Type 1			
PDSCH DMRS	Number of additional DMRS		1			
configuration	Maximum number of OFDM symbols for DL front loaded DMRS		1			
Number of HARQ Proce			8			
TDD UL-DL pattern		FR2.120-1 (Note2)				
Note 1: "R.PDSCH.5-2.2 TDD" is defined in Table A.3.2.2.5-2 of TS 38.101-4						

Note 1: "R.PDSCH.5-2.2 TDD" is defined in Table A.3.2.2.5-2 of TS 38.101-4 Note 2: "FR2.120-1" is defined in Annex A.1.3 of TS 38.101-4

Annex F (normative): <Environmental requirements>

F.1 Scope

The requirements in this clause apply to all types of UE(s) in FR1 and FR2.

F.2 Ambient temperature

All the MIMO OTA requirements are applicable in room temperature e.g. 25°C.

F.3 Operating voltage

For FR1 MIMO OTA, all nominal voltage test cases shall be performed with the DUT operated in stand-alone battery powered mode.

For FR2 MIMO OTA, all nominal voltage test cases shall be performed with the DUT operated in stand-alone battery powered mode or external power source. It shall be demonstrated that the impact of external power source to device performance is negligible comparing to stand-alone battery powered mode.

Annex G (informative): Change history

Change history							
Date	Meeting	TDoc	CR	Rev	Cat	Subject/Comment	New
							version
2020-08	RAN4#96-e	R4-2012709				Initial Skeleton	0.0.1
2020-11	RAN4#97-e	R4-2016216				R4-2016218, TP to TS 38.151 v0.0.1 on general part	0.1.0
						R4-2016222, TP to TS 38.151 v0.0.1 on FR1 test system for	
						requirements	
						R4-2017584, TP to TS 38.151 v0.0.1 on FR1 Channel model and	
						RMC	
2021-02	RAN4#98-e	R4-2101822				R4-2103969 TP to TS38.151 v0.1.0 on FR2 Channel model and	0.2.0
						RMC	
						R4-2103970 TP to TS38.151 v0.1.0 on FR2 test system for	
						requirements	
						R4-2103971 TP to TS38.151 v0.1.0 on Performance metrics for NR	
	54514#66	5 / 6 / 6 / 5 / 5				MIMO OTA requirements	
2021-04	RAN4#98-	R4-2104512				R4-2106094 TP to TS38.151 v0.2.0 on FR1 Channel model	0.3.0
	bis-e					R4-2104511 TP to TS38.151 v0.2.0 on FR1 Calibration and Test	
						procedure R4-2106093 TP to TS38.151: revision on MIMO Average Spherical	
						Coverage	
2021-05	RAN4#99-e	R4-2108094				R4-2108614 TP to TS38.151 v0.3.0 on FR1 TRMS	0.4.0
2021-03	KAN4#99-E	K4-2100094				R4-2109660 TP to TS38.151 v0.3.0 on CDL-C UMi channel model	0.4.0
						R4-2108615 TP to TS38.151 v0.3.0 on Power validation	
2021-08	RAN4#100-	R4-2112976				R4-2112977 Rapporteur input to TS38.151	0.5.0
2021 00	е	114 2112370				R4-2112979 TP to TS38.151 on Minimum Number of Slots and	0.5.0
						Power Control	
						R4-2115757 TP on Channel Model and DUT Positioning	
						Clarifications	
						R4-2115811 TP to TS38.151 on FR2 PAS similarity percentage	
2021-11	RAN4#101-	R4-2118299				R4-2118302 TP to TS 38.151 on updated structure	0.6.0
	е					R4-2119377 Clarification of NF Compensation for FR2 PSP	
2022-01	RAN4#101-	R4-2200966				R4-2201920 Illustration of Device Orientations for Select Test	0.7.0
	bis-e					Points	
						R4-2200780 TP on TS 38.151 for test parameters of FR2	
						performance	
						R4-2200967 TP to TS38.151 on FR2 maximum downlink power	
						and test procedure	
						R4-2203064 TP to TS38.151 on FR1 Spatial Channel Model	
2000 65	DANI4#466	D 4 000 46 17		<u> </u>	<u> </u>	Validation EDIAMMO OTA :	0.0.6
2022-03	RAN4#102-	R4-2204945				R4-2204572 TP to TS 38.151 on FR1 MIMO OTA test parameter	0.8.0
	е					R4-2207306 TP to TS38.151 on FR1 MPAC MU budget	
		1				R4-2207307 TP to TS38.151 on channel model validation limits	
						R4-2207308 TP to TS38.151 on FR1 Temporal Correlation Validation – Time domain technique	
2022.02	RAN#95-e	RP-220793		<u> </u>	-		1.0.0
2022-03	9-ce#rian	KP-220/93			1	For one-step approval in RAN Plenary	1.0.0

	Change history								
Date	Meeting	TDoc	CR	Rev	Cat	Subject/Comment	New .		
							version		
2022-03	RAN#95					Approved by plenary – Rel-17 spec under change control	17.0.0		
2022-06	RAN#96	RP-221662	0001		F	BIG CR to 38.151	17.1.0		
2022-09	RAN#97	RP-222039	0003		В	Big CR to 38.151: Introduction MIMO OTA performance	17.2.0		
					Р	requirements (Rel-17, CAT B)			

History

	Document history							
V17.0.0	April 2022	Publication						
V17.1.0	August 2022	Publication						
V17.2.0	October 2022	Publication						