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Digital cellular telecommunications system (Phase 2+) (GSM);
Full rate speech;
Substitution and muting of lost frames
for full rate speech channels
(3GPP TS 46.011 version 14.0.0 Release 14)



# Reference RTS/TSGS-0446011ve00 Keywords GSM

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#### **Foreword**

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#### where:

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  - 1 presented to TSG for information;
  - 2 presented to TSG for approval;
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- y the second digit is incremented for all changes of substance, i.e. technical enhancements, corrections, updates, etc.
- z the third digit is incremented when editorial only changes have been incorporated in the document.

#### 1 Scope

The present document defines a frame substitution and muting procedure which shall be used by the RX DTX handler when one or more lost speech or SID frames are received from the radio subsystem.

The requirements of the present document are mandatory for implementation in all GSM Base Station Systems (BSS) and Mobile Stations (MS).

#### 2 References

The following documents contain provisions which, through reference in this text, constitute provisions of the present document.

- References are either specific (identified by date of publication, edition number, version number, etc.) or non-specific.
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  - [1] GSM 01.04: "Digital cellular telecommunications system (Phase 2+); Abbreviations and acronyms".
  - [2] GSM 06.10: "Digital cellular telecommunications system (Phase 2+); Full rate speech; Transcoding".
  - [3] GSM 06.31: "Digital cellular telecommunications system (Phase 2+); Full rate speech; Discontinuous Transmission (DTX) for full rate speech traffic channel".

#### 3 Definitions and abbreviations

Abbreviations used in the present document are listed in GSM 01.04 [1].

The definitions of terms used in the present document can be found in GSM 06.31 [3].

#### 4 General

The purpose of the frame substitution is to conceal the effect of lost frames.

The purpose of muting the output in the case of several lost frames is to indicate the breakdown of the channel to the user.

#### 5 Requirements

#### 5.1 First lost speech frame

Normal decoding of lost speech frames would result in very unpleasant noise effects. In order to improve the subjective quality, the first lost speech frame shall be substituted with either a repetition or an extrapolation of the previous good speech frame(s). Lost speech frames shall not be delivered to the speech decoder, nor shall the output be muted directly.

#### 5.2 Subsequent lost speech frames

For subsequent lost speech frames, a muting technique shall be used that will gradually decrease the output level, resulting in silencing of the output after a maximum of 320 ms. Clause 6 gives an example solution.

#### 5.3 First lost SID frame

A single lost SID frame shall be substituted by the last valid SID frame and the procedure for valid SID frames be applied as described in GSM 06.31 [3].

#### 5.4 Subsequent lost SID frame

For the second lost SID frame, a muting technique shall be used on the comfort noise that will gradually decrease the output level, resulting in silencing of the output after a maximum of 320 ms. Clause 6 gives an example solution.

For subsequent lost SID frames, the muting of the output shall be maintained.

### 6 Example solution

For guidance, an example solution is given.

The first lost speech frame is replaced at the speech decoder input by the previous good speech frame. Normal decoding is then performed.

The muting procedure to be used in the case of subsequent lost speech frames or for comfort noise frames following the second lost SID frame is as follows:

The pseudo-logarithmic encoded block amplitude Xmaxcr (GSM 06.10 [2]), coded on the interval from 0 to 63, is decreased with a constant value d=4 in each frame, down to the lowest possible value. Consequently, Xmaxcr will be reduced gradually, and the output muted after a maximum of 320 ms. The grid position parameters are chosen randomly between 0 and 3 during this time.

For subsequent unusable frames, after the frame where Xmaxcr reached the lowest possible value, "silence frames" are passed from the RX DTX handler to the speech decoder to guarantee a low output level under all conditions. The silence frame is defined in table 1.

Table 1: Encoded parameters (GSM 06.10) of the silence frame

Log area ratio 1 = 42 Log area ratio 2 = 39 Log area ratio 3 = 21 Log area ratio 4 = 10 Log area ratio 5 = 9 Log area ratio 6 = 4 Log area ratio 7 = 3Log area ratio 8 = 2LTP gain = 0LTP lag = 40 Grid position = 1 Block amplitude = 0RPE pulse no. 1 = 3RPE pulse no. 2 = 4RPE pulse no. 3 = 3RPE pulse no. 4 = 4RPE pulse no. 5 = 4- repeated for each subsegment RPE pulse no. 6 = 3RPE pulse no. 7 = 3RPE pulse no. 8 = 3RPE pulse no. 9 = 3RPE pulse no. 10 = 4RPE pulse no. 11 = 4RPE pulse no. 12 = 3RPE pulse no. 13 = 3

# Annex A (informative): Change history

Change history						
SMG No.	TDoc. No.	CR. No.	Section affected	New version	Subject/Comments	
SMG#07				4.0.4	ETSI Publication	
SMG#20				5.0.1	Release 1996 version	
SMG#27				6.0.0	Release 1997 version	
SMG#28				6.0.1	ETSI Publication	
SMG#29				7.0.0	Specification version 6.0.0 upgrade to Release 1998 version 7.0.0	
				7.0.1	Version update for Publication	
SMG#31				8.0.0	Release 1999 version	

	Change history						
Date	TSG #	TSG Doc.	CR	Rev	Subject/Comment	Old	New
03-2001	11				Version for Release 4		4.0.0
06-2002	16				Version for Release 5	4.0.0	5.0.0
12-2004	26				Version for Release 6	5.0.0	6.0.0
06-2007	36				Version for Release 7	6.0.0	7.0.0
12-2008	42				Version for Release 8	7.0.0	8.0.0
12-2009	46				Version for Release 9	8.0.0	9.0.0
03-2011	51				Version for Release 10	9.0.0	10.0.0
09-2012	57				Version for Release 11	10.0.0	11.0.0
09-2014	65				Version for Release 12	11.0.0	12.0.0
12-2015	70				Version for Release 13	12.0.0	13.0.0

Change history							
Date	Meeting	TDoc	CR	Rev	Cat	st Subject/Comment	
03-2017	SA#75					Version for Release 14	14.0.0

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